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A LARGE-SCALE SOLAR INDUSTRIAL PROCESS HEAT SYSTEM FOR CATERPILLAR TRACTOR CO.



CONSTRUCTION REPORT

PREPARED FOR:
DEPARTMENT OF ENERGY

SEPTEMBER 30, 1982



SOUTHWEST RESEARCH INSTITUTE
SAN ANTONIO

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**A LARGE-SCALE SOLAR INDUSTRIAL
PROCESS HEAT SYSTEM
FOR CATERPILLAR TRACTOR CO.:
CONSTRUCTION REPORT**

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Project No. 02-5821

Prepared for:
DEPARTMENT OF ENERGY

September 30, 1982

Approved:



Robert L. Bass, Director
Department of Mechanical Sciences

EXECUTIVE SUMMARY

The objective of this phase of the project was to construct the solar process heating system previously designed for the Caterpillar Tractor Company's San Leandro plant. This phase of the project was completed on time and within 1% of the construction budget.

The San Leandro plant's predominate energy load is its parts washing activity. This activity requires 836 gpm of 235°F pressurized hot water, and is ideally suited to integrate with a simple solar hot water system. The climate at San Leandro is, also, ideally suited for a solar thermal system. Located on the east shore of the San Francisco Bay, San Leandro enjoys a relatively mild climate with an average solar radiation of 1536 Btu/ft²/day. The collector performance, therefore, is estimated to provide 12 billion Btu/yr with a peak output of 9 million Btu/hr and a best day output of 83 million Btu/day.

The solar thermal system consists of 50,400 ft² of parabolic trough collectors. These collectors are assembled in a simple open loop hot water heating system that provides 450 gpm of heated hot water at 235°F. The overall quality of construction is excellent and is illustrated by the photographs documenting construction.

The thermal performance of this system will be determined during the operational phase and recorded by the computer based automatic data acquisition system provided.

As with any construction project, especially an experimental system such as this, a number of construction problems were encountered. Since the majority of these problems were resolved during construction only a few recommended modifications are presented, and most of these have to do with the collector hardware itself. In summary, this phase of the project was highly successful and a relatively trouble-free operating phase is anticipated.

TABLE OF CONTENTS

	<u>Page</u>
EXECUTIVE SUMMARY	ii
LIST OF FIGURES	vi
LIST OF TABLES	vii
I. INTRODUCTION	1
II. INDUSTRIAL PLANT	3
A. PLANT SITE	3
B. CLIMATOLOGICAL SUMMARY	6
III. THERMAL SYSTEM	10
A. SYSTEM DESCRIPTION	10
B. INITIAL SYSTEM START-UP	13
C. SYSTEM FLOW BALANCING	14
D. SYSTEM OPERATION SEQUENCE	15
E. SYSTEM PHOTOGRAPHS	16
IV. AUTOMATIC DATA ACQUISITION SYSTEM	30
A. INTRODUCTION	30
B. DATA ACQUISITION SYSTEM (DAS) OBJECTIVES	30
1. SOLAR RADIATION	34
2. THERMAL ENERGY	35
3. PARASITIC LOSSES	37
4. ENVIRONMENTAL CONDITIONS	37
C. DAS HARDWARE	37
1. COMPUTER HARDWARE	39
a. PDP 11/23 CPU	39
b. MEMORY	39
c. RLO1 DISK DRIVES	40

TABLE OF CONTENTS (CONTINUED)

	<u>Page</u>
d. INTERFACE CARDS	40
e. VT100 TERMINAL	40
f. UNINTERRUPTIBLE POWER SUPPLY	40
g. LA36 LINE PRINTER	40
h. UDS 103LP MODEM	40
i. ANALOG TO DIGITAL CONVERTER CARDS	41
2. SENSORS AND SIGNAL CONDITIONERS	41
3. WIRING AND TERMINATION HARDWARE	42
D. DAS SOFTWARE	42
V. CONSTRUCTION PROBLEMS ENCOUNTERED	45
A. FIELD ORDER CHANGES	45
1. STRUCTURAL REVISIONS	45
2. STAINLESS STEEL FLASHINGS	45
3. COLLECTOR END PIPING MODIFICATION	46
4. MODIFY PYLON DETAIL TO ATTACH EXISTING CROSS BRACES	46
5. RELOCATION OF COMPUTER SYSTEM	46
6. PAINTING MODIFICATION	46
7. REPLACE COMPUTER SYSTEM TRANSFORMER	46
8. RELOCATE ELECTRICAL PENETRATIONS	46
9. WATTMETER MODIFICATION	47
10. CHIPPED COLLECTOR RECEIVER GLASS	47
11. RELOCATE FLOW SWITCHES	47
12. MODIFY ALARM PANEL WIRING	47

TABLE OF CONTENTS (CONTINUED)

	<u>Page</u>
B. COLLECTOR HARDWARE PROBLEMS	47
1. CHANGE IN RECEIVER TUBE DESIGN	47
2. EQUIPMENT DELIVERY	48
3. REPLACE COLLECTOR TEMPERATURE SWITCHES	48
4. SEGRAGATION OF 480V AND 120V IN ROW CONTROL PANEL	48
5. COLLECTOR PYLON/MIRROR INTERFERENCE	48
6. MISCELLANEOUS DRIVE AND CONTROL PROBLEMS	49
7. RUSTY HOSE/RECEIVER FITTINGS	49
8. SPOT WELD DEFECTS IN RECEIVER MOUNTING BRACKETS	49
VI. RECOMMENDED MODIFICATIONS	50
1. MOVE EXISTING TRACKER HEAD FROM THE MIRROR EDGE TO THE RECEIVER	50
2. CONTROL UPGRADE	50
3. UPGRADE HYDRAULIC DRIVE	50
4. THERMAL STORAGE	51
VII. CONSTRUCTION COST COMPARISON	52
VIII. ASSESSMENT OF PERFORMANCE	53
IX. AS-BUILT DRAWINGS	54

LIST OF FIGURES

<u>Figure No.</u>		<u>Page</u>
1	PROCESS HOT WATER FLOW DIAGRAM	4
2	SYSTEM SCHEMATIC	11
3	PIPING AND INSTRUMENTATION DIAGRAM (P&ID)	12
4	SYSTEM ELEMENTARY DIAGRAM	15
5	AERIAL VIEW OF THE COLLECTOR FIELD	17
6	SINGLE COLLECTOR ROW	18
7	PIPING BETWEEN COLLECTOR ROWS	20
8	COLLECTOR DRIVE PYLON	21
9	COLLECTOR ROW CONTROL PANEL	22
10	COLLECTOR ROW TEMPERATURE SWITCH	23
11	COLLECTOR ROW TRACKER HEAD	24
12	COLLECTOR ROW END PIPING	25
13	SYSTEM OUTLET PIPING WITH TRV	26
14	ELECTRICAL POWER DISTRIBUTION PANEL	27
15	SOLAR MASTER CONTROL PANEL	28
16	PUMP CONTROL PANEL	29
17	COMPUTER DATA ACQUISITION SYSTEM	31
18	SOLAR RADIATION MEASUREMENT SENSORS	32
19	WEATHER STATION	33
20	BLOCK DIAGRAM	38
21	SENSOR CURRENT LOOP WIRING	43

LIST OF TABLES

<u>Table No.</u>		<u>Page</u>
I	PROCESS HEATING HOT WATER LOAD	5
II	CLIMATOLOGICAL DATA FOR SAN LEANDRO	8
III.	SOLAR RADIATION DATA FOR SAN LEANDRO	9

INTRODUCTION

I. INTRODUCTION

This document is a phase report for the construction activities on DOE Project No. DE-FC03-79CS30309 (SwRI Project No. 02-5821). This program was conducted as a cooperative agreement between the U. S. Department of Energy (DOE) and Southwest Research Institute (SwRI) with Caterpillar Tractor Co. (CTCo.) acting as the industrial partner.

From a financial point of view the project was cost-shared between DOE and CTCo. The financial arrangements were somewhat unique with DOE funding 75% of construction and CTCo. funding 25%, but CTCo. would finance 100% of any overruns. The original construction phase (DOE Phase II) was budgeted in design as \$2.8 million. After the design package went out for bid, the total bid came in at \$2.832 million which is within 1.2% of the design estimate. As will be detailed under the construction problems and the cost comparison sections of this report, the construction field orders issued to solve construction problems pushed the construction budget to \$2.938 million. This additional \$138,000 cost growth was authorized and funds were provided by CTCo. The construction budget was eventually underrun by \$110,000 so that the final construction cost was \$2.828 million. This \$110,000 underrun was a tribute to the excellent construction management provided by Rudolph and Sletten, Inc., the project general contractor. The net result was that the project was completed on time (considering the original 2-year construction phase) and within the construction bid price of \$2.832 million. It was also within 1% of the original design estimate.

The solar industrial process heating (SIPH) system is a very simple open loop hot water system that takes 195°F water and heats it to 235°F under clear sky conditions. This system consists of 50,400 ft² of Solar Kinetics, Inc. T-700 parabolic trough solar collectors. The collector array is composed of 60 drive rows each 120 ft long by 7 ft wide. This array is divided into two fields, a north field of 16 rows (13,440 ft²) and a south field of 44 rows (36,960 ft²). Within each field these rows are assembled with two rows in series so that 30 delt-T strings are configured in parallel.

The remainder of this report is organized to provide a detailed description of the plant process interface, details of construction, outline of problems encountered, construction cost comparison, recommended system changes, assessment of performance, and as-built drawings.

INDUSTRIAL PLANT

II. INDUSTRIAL PLANT

A. Plant Site

The facility at which this solar industrial heat system is installed is the Caterpillar Tractor Company's San Leandro Plant. This plant produces a variety of fuel injection components for use on Caterpillar diesel engines. In this manufacturing operation the major portion of energy consumed is for industrial parts washing. These washers are required to clean parts after critical machining operations so that inspection can be performed for quality control. The impact of energy consumption of these parts washers has necessitated a major effort to investigate ways of reducing the total energy required. A major effort has been underway to replace a large number of high-temperature washers with medium- to low-temperature washers and, wherever possible, with room temperature washers. This investigation has centered on testing the effectiveness of lower temperature detergents. Unfortunately, some of the final machining operations prior to priming the end product still require the high-temperature washers. The process water temperature of 235°F is, therefore, the minimum possible.

A drawing of the process heat supply system at the San Leandro plant is shown in Figure 1. Basically, hot water is generated in the hot water "boilers" and is then pumped through a hot water supply header that encircles the building. Every 40 feet there is a 2-inch valved outlet for connection to process equipment and an accompanying 2-inch valved inlet to the hot water return header. The cooled process water is then returned to the "boilers" via boiler feed pumps. The building circulation pump system consists of four hot water pumps piped in parallel; likewise, the boiler feed pump system also consists of four hot water pumps piped in parallel. The maximum required flow rate is 1672 gpm for 20°F temperature difference through the process equipment and 836 gpm for a 40°F temperature difference. The process hot water generating system is comprised of two natural gas fired hot water heaters (or "boilers") rated at 500 boiler horsepower which is equal to 16,738 MBH (10^3 Btu/hr). A list of the process heating loads is shown in Table I. The maximum total load is 32,528 MBH with a 10% (3000 MBH) reserve. Since most of the process equipment is intermittent service, past plant experience indicates a 14,000 MBH design criteria for the manufacturing process.

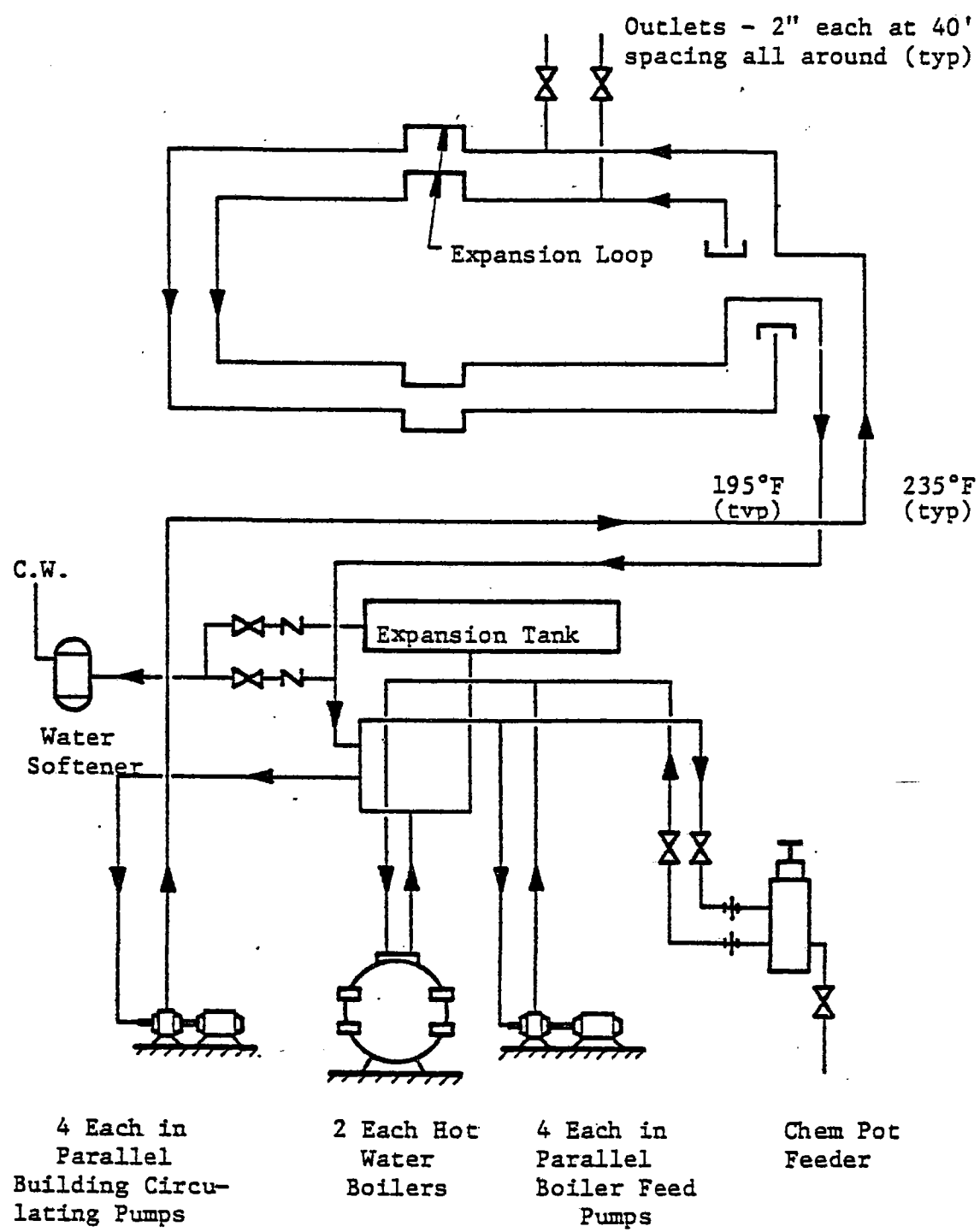


FIGURE 1. PROCESS HOT WATER FLOW DIAGRAM

TABLE I. PROCESS HEATING HOT WATER LOAD

Description	Connected Load*				
	Quantity	Flow Duration	System Type	Heating (MBH)	Water Flow (gpm)
Process washer	1 each	Intermittent	Closed	10,508	525
Process washer	6 each	Intermittent	Closed	8,407	420
Office heating	52,000	Intermittent	Closed	7,800	390
Tumbling area	2 each	Intermittent	Closed	1,201	60
Tacco H.T. unit	4 each	Intermittent	Closed	1,201	60
Wash and test - Met Lab	1 lot	Intermittent	Closed	300	15
Insulation line loss	1 lot	Continuous	N.A.	111	0
Reserve	10%			3,000	150
Total				32,528	1,620

Caterpillar Tractor Co. design criteria (including diversity)
 manufacturing process

14,000

* Process heating hot water boiler ratings. Each boiler (500 boiler horsepower) equals 16,737.5 MBH, 1672 gpm flow rate for 20°F temperature difference, or 836 gpm flow rate for 40°F temperature difference.

This manufacturing operation is located in a two-story factory with a flat roof of 360 ft by 1092 ft (393,120 ft²). The support structure for this roof consists of a truss structure between support columns spaced on 40-ft centers with steel 10-inch I-beam purlins on 6-2/3 ft centers. These purlins are oriented in the north/south direction so that the installation of the collector field is oriented with the collector axis of rotation in the north/south direction.

Since the collector field is proposed to be installed on the second story roof top of the industrial plant, factors pertaining to topography, geologic stability, hydrologic conditions, adequate open land area, and land use restrictions are not relevant. As with any other application in a large metropolitan area, however, the collector field will be visible to air traffic, but since the type of collector chosen will either be facing the factory roof or pointing directly at the sun focusing all the rays from the sun onto an absorber tube, there is no danger of glare from the collectors causing a hazard to aircraft or vehicular traffic. The only potential problem with the location selected is the severe seismic zone that the plant is located in. The type of collector selected has a much larger horizontal wind load design requirement than the maximum expected seismic load, therefore, no problem is anticipated.

B. Climatological Summary

The climatological characteristics of this site have three outstanding features: mild year-round temperatures; low overcast, clearing by noon with almost no rain during the summer; and copious rains during the winter.

Located on the east shore of San Francisco Bay, San Leandro enjoys a climate more equable than would be expected if only latitude were considered. Because of the prevailing westerly winds from the Pacific, where temperature varies very little between winter and summer, winters are mild and summers are cool. On an average of about 4 days a year, when northeasterly winds have overcome the prevailing westerly wind, daytime temperatures may reach into the nineties, and on rare occasions (6 times since 1928) temperatures of 100° or higher have been recorded. Although during the

winter about 6 days with minimum temperatures of 32° or below can be expected, some flowers are usually in bloom, and hardy shrubs seldom are damaged due to any prolonged hard freezing. The average date of the last freeze in the spring is February 3, but freezing temperatures have been reported as late as April 6. The average date of the first freeze in the fall is December 12, although temperatures of 32° or lower have been observed as early as November 4.

Since 1928 the total annual rainfall has ranged from a low of 8.34 inches in 1929 to a high of 29.54 inches in 1941. About 90% of the annual total rainfall is received in the six months, November through April. During the 100-day period, June 15-September 22, the normal rainfall is only 0.07 inch. In spite of the almost rainless summers, however, cooling sea breezes, morning overcast and rather high relative humidity prevent any semblance of a desert climate.

Separating San Leandro both geographically and climatically from its neighboring communities to the north and east, is a range of hills 700 to 1900 feet in height, roughly paralleling the Bay shore and lying about 4 miles inland. East of these hills, summers are normally free of fog, have low humidities, and afternoon temperatures 15° to 25° higher than San Leandro. In winter, local variations in temperature are not so apparent, with the entire East Bay area registering daily high and low temperatures comparable to those of San Leandro.

The long-term climatological data for San Leandro is shown in Table II. Since long-term solar radiation has not been measured at San Leandro, the SOLMET weather table for Oakland was used for determining the estimated solar radiation. A summary of the total solar radiation on a horizontal surface is shown in Table III.

TABLE II. CLIMATOLOGICAL DATA FOR SAN LEANDRO

Latitude: 37°44' Longitude: 122°12' Elevation: 6'													
	Jan	Feb	Mar	Apr	May	Jun	Jul	Aug	Sep	Oct	Nov	Dec	Annual
TEMPERATURE(°F)													
average monthly	48.6	51.9	53.7	56.1	58.9	61.9	63.1	63.5	64.5	61.1	55.3	49.9	57.4
average daily $\frac{\text{max}}{\text{min}}$	$\frac{55}{43}$	$\frac{58}{46}$	$\frac{60}{47}$	$\frac{63}{49}$	$\frac{65}{52}$	$\frac{69}{55}$	$\frac{70}{56}$	$\frac{70}{57}$	$\frac{72}{57}$	$\frac{69}{53}$	$\frac{62}{49}$	$\frac{56}{44}$	$\frac{64}{51}$
extreme $\frac{\text{max}}{\text{min}}$	$\frac{74}{32}$	$\frac{74}{37}$	$\frac{82}{35}$	$\frac{88}{39}$	$\frac{98}{43}$	$\frac{94}{50}$	$\frac{99}{52}$	$\frac{89}{50}$	$\frac{96}{49}$	$\frac{89}{42}$	$\frac{78}{37}$	$\frac{73}{26}$	$\frac{99}{26}$
DEGREE DAYS													
heating (base 65°F)	508	367	350	270	193	114	80	74	59	135	291	468	2909
cooling (base 65°F)	0	0	0	0	0	21	21	28	44	14	0	0	128
WIND													
Mean speed (mph)	6.7	7.3	9.0	9.5	10.0	10.0	9.3	9.0	7.8	6.8	6.3	6.5	8.2
Max. speed* (mph)	46	49	45	35	38	42	28	29	33	43	46	48	49
Prevailing direction	SE	W	W	W	W	W	WNW	WNW	WNW	WNW	WNW	E	W
FREEZE DAYS PER MONTH													
	<0.5	0	0	0	0	0	0	0	0	0	0	1	1
PRECIPITATION (in. water)													
average	4.03	2.83	2.32	1.58	0.55	0.14	0.01	0.03	0.18	1.08	2.37	3.57	18.69
$\frac{\text{max}}{\text{min}}$	$\frac{8.90}{0.65}$	$\frac{8.85}{0.02}$	$\frac{5.69}{0.04}$	$\frac{4.60}{T}$	$\frac{3.42}{T}$	$\frac{1.21}{0.00}$	$\frac{0.80}{0.00}$	$\frac{0.34}{0.00}$	$\frac{3.27}{0.00}$	$\frac{8.56}{T}$	$\frac{7.42}{0.00}$	$\frac{11.3}{0.28}$	$\frac{11.3}{0.00}$
RELATIVE HUMIDITY(%)													
4 AM	83	81	80	80	83	85	87	87	83	80	82	82	83
10 AM	77	75	72	68	71	74	76	76	73	72	75	75	74
4 PM	72	69	66	63	65	68	68	68	64	64	69	71	67
10 PM	80	79	76	76	79	82	84	84	80	77	78	80	79

*"fastest mile"; speed is fastest observed 1-minute value.

Source of climatological data: NWS climatic summary.

TABLE III. SOLAR RADIATION DATA FOR SAN LEANDRO

<u>Month</u>	<u>Radiation, KBTU/ft²*</u>
Jan	26.2
Feb	25.3
Mar	44.7
Apr	61.2
May	70.4
Jun	71.8
Jul	71.5
Aug	64.7
Sep	47.4
Oct	33.7
Nov	25.3
Dec	18.3
Yearly	560.7 KBTU/ft ² yr
Average	1536.0 BTU/ft ² day

*Total solar radiation on a horizontal surface based
on Standard Year Solmet Data for Oakland California
(1962)

THERMAL SYSTEM

III. THERMAL SYSTEM

A. System Description

The solar process heating system is a simple open loop hot water preheat system. A schematic of this system is shown in Figure 2. Water is pumped from the plant hot water water return header (HHWR) through the collector array and returned to the HHWR at an elevated temperature. Under clear sky conditions and at the plant design load, the collector array inlet temperature is typically 195°F and the outlet temperature is typically 235°F. Since the HHWR temperature is a function of process load this temperature fluctuates between 195°F at design load to 235°F at minimum load. With the constant flow system utilized in this design, the temperature difference across the collector system is primarily dependent on solar input. So for a peak solar condition the system delta-T is approximately 40°F, therefore, the maximum collector outlet temperature is 275°F, which brought about some unforeseen control problems. These problems are discussed in a separate section.

Figure 3 shows the system Piping and Instrumentation Diagram (P&ID). As can be seen from this drawing, water at a rate of 450 gpm is pumped from the HHWR split between the system north field at 120 gpm and the south field at 330 gpm. This water then passes through each system delta-T string via a reverse return piping system. Each delta-T string consists of two 125 ft long collector drive rows piped in series. The flow rate through each delta-T string is 15 gpm. After exiting the delta-T string the solar heated water is then returned to the HHWR.

The pumping system consists of two parallel pumps that alternately operate to provide full flow from a single pump. The control logic for this pump operation will be discussed later in this section. Operational instrumentation consists of mercury thermometers, and pressure gauges at the system inlet and outlet of each bank with a Venturi flow meter on the inlet to each bank, outfitted with pressure gauges marked in units of gpm to give a direct indication of flow.

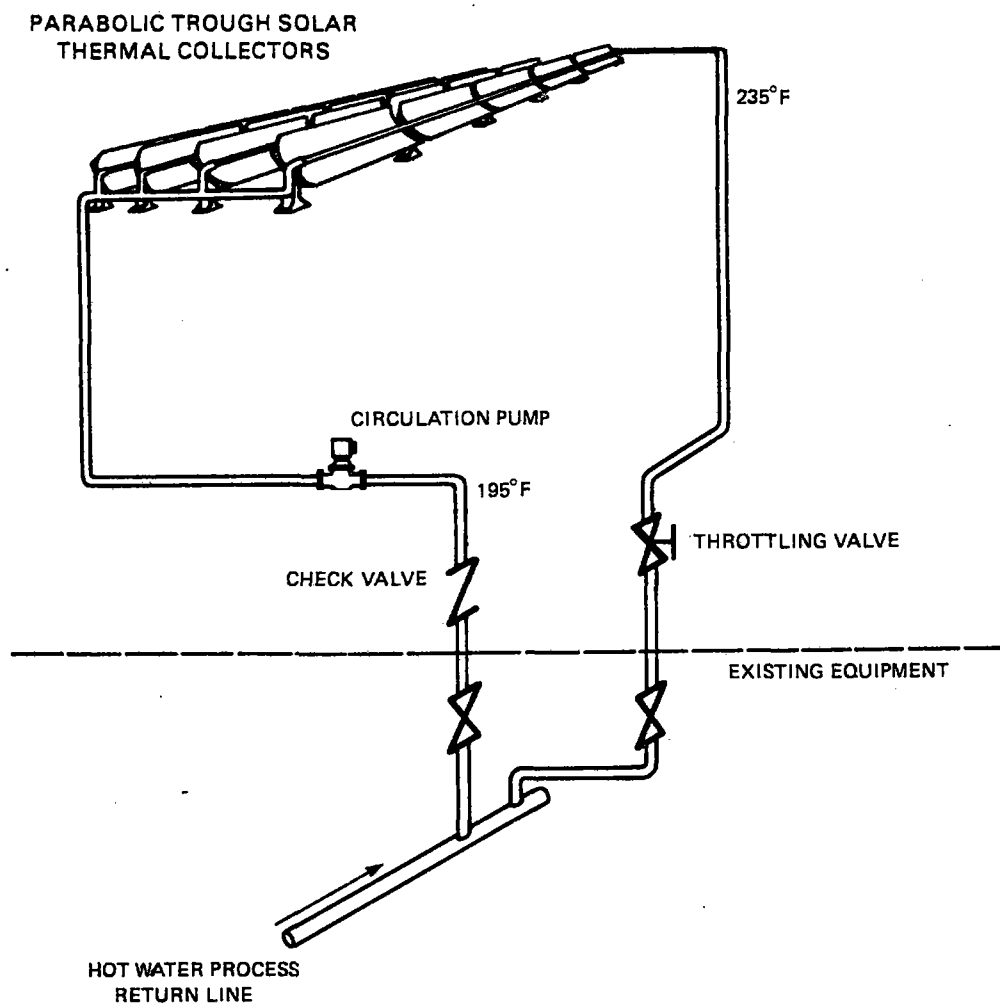
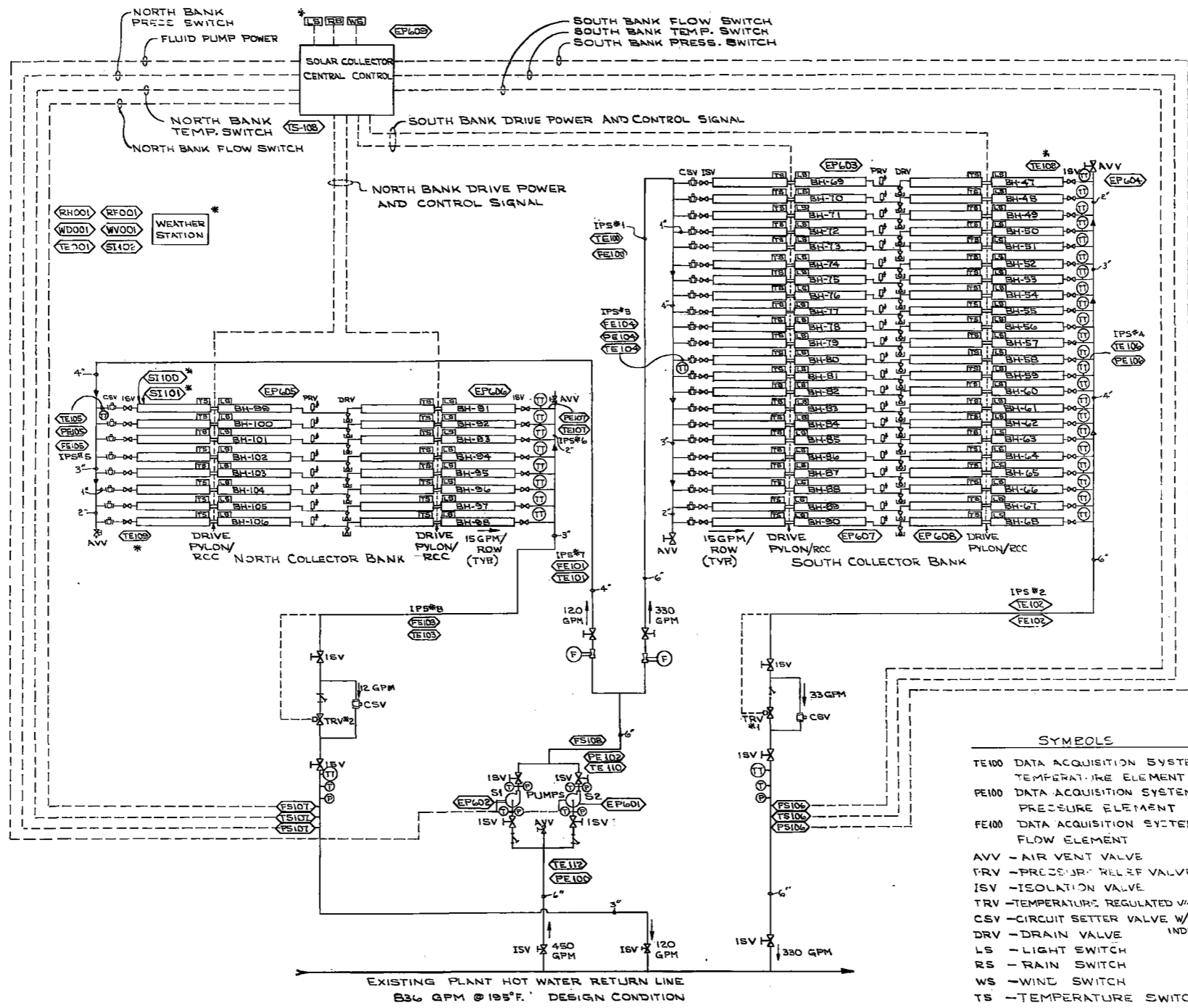


FIGURE 2. SYSTEM SCHEMATIC



BOILER ROOM, BLDG. N-N
 FE202
 FE200

* MOUNTED ON ROOF

SYMBOLS

- TE100 DATA ACQUISITION SYSTEM TEMPERATURE ELEMENT
- PE100 DATA ACQUISITION SYSTEM PRESSURE ELEMENT
- FE100 DATA ACQUISITION SYSTEM FLOW ELEMENT
- AVV - AIR VENT VALVE
- PRV - PRESSURE RELIEF VALVE
- ISV - ISOLATION VALVE
- TRV - TEMPERATURE REGULATED VALVE
- CSV - CIRCUIT SETTER VALVE W/FLOW INDICATOR
- DRV - DRAIN VALVE
- LS - LIGHT SWITCH
- RS - RAIN SWITCH
- WS - WIND SWITCH
- TS - TEMPERATURE SWITCH
- FS - FLOW SWITCH
- PS - PRESSURE SWITCH
- Ⓣ - DIAL THERMOMETER
- Ⓟ - PRESSURE GAGE
- Ⓢ - VENTURI FLOWMETER WITH PRESSURE GAGE.
- Ⓜ - TEMPERATURE TAP
- HOT WATER LINE
- - - ELECTRICAL CONDUCTOR

EXISTING PLANT HOT WATER RETURN LINE
 836 GPM @ 195°F. DESIGN CONDITION

- IPS - INSTRUMENTED PIPE SECTION
- EP - ELECTRICAL POWER
- RH - RELATIVE HUMIDITY
- RF - RAIN FALL
- WD - WIND DIRECTION
- WV - WIND VELOCITY
- SI - SOLAR RADIATION



Stephen M. Schubert, Jr. 11/19/80

1-81 BID ISSUE
 CATERPILLAR
 SAN LEANDRO SAN LEANDRO, CA.
 SOLAR IPH SYSTEM
 PIPING & INSTRUMENTATION DIAGRAM

SOUTHWEST RESEARCH INSTITUTE
 6202 GARDNER ROAD
 SAN ANTONIO, TEXAS 78284
 E.Z. 4/80 NOT-TO SCALE
 A.A. 7/10 02-55-1 CI-270

At each delta-T string a circuit setter is installed at the inlet to provide the capability to both set the flow rate in each string as well as measure the resultant flow. At the outlet of each string a thermometer well is provided so that the outlet temperature can be measured by inserting one of the six spare thermometers in these wells. Each delta-T string also is provided with shut-off valves at each end, a pressure relief valve and a drain. Each drive row is supplied with a temperature switch and a light switch for individual protection and control.

At the exit of each bank of collectors is a temperature regulating valve (TRV) with a by-pass line set at 10% of design flow. The TRV's are activated by a temperature probe set at the HHWR design temperature. Operationally, when the system starts up water is passed from the collector field at 10% flow as the first slug of hot water from the plant reaches the system outlet, where the TRV temperature probe is located, the TRV opens and full design flow is initiated. The objective of this TRV is, therefore, to minimize the thermal shock on the plant HHWR.

B. Initial System Start-Up

The start-up sequence can best be described by referring to Figure 3. The first step in the start-up sequence is to open the isolation valve between the HHWR line and the pumps. The plant operating pressure fills the line up to the pumps, venting the air via the air vent in the pump suction line. The next step is to verify that all upstream shut-off valves for the collectors are closed and the downstream valves are open. The ball valve leading to the south field is open and the ball valve leading to the north field is closed. After all of the tests and inspection for the pump are performed per the mechanical and electrical specifications, the pump is turned on and all the air between the pump and the collectors is evacuated via the air vent located in the deadend of the inlet manifold. The isolation valve between the exit manifold and the plant HHWR line is opened with the next step being to open the isolation valves on each of the inlet sections of the collector rows one at a time, the idea being to flush the air from each receiver tube individually. Since the exit manifold is sloped up to the deadend, which has an air vent, the air from each receiver flows "uphill" to the air vent and the water flows "downhill" to the

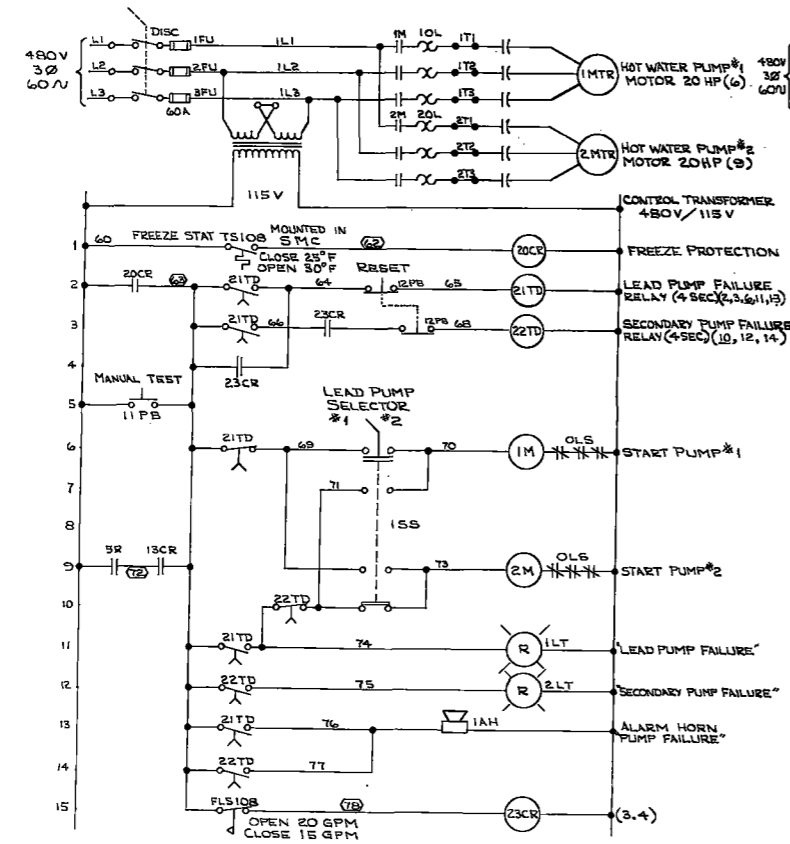
plant return line. After each row is cleared, the inlet isolation valve is closed; this provides a high velocity through each row. Once all of the rows in the south bank are cleared, then the north bank isolation valve is opened, the south bank valve is closed, and the same process is followed for the north field as was followed for the south field. The system outlet valve at the HHWR line is now opened for system operation.

C. System Flow Balancing

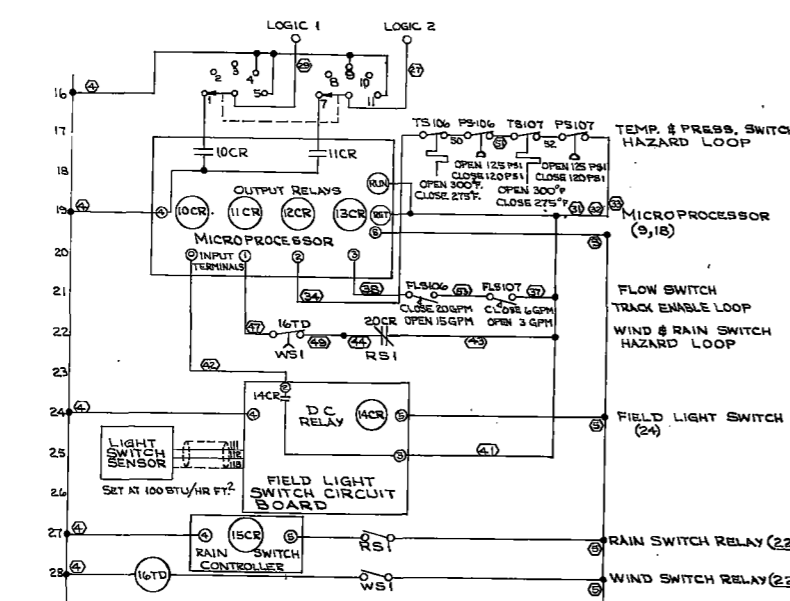
Once the flow in the entire field is stabilized, the ball valves to each field are adjusted to give the proper ratio of flow between the two fields. The flow rate to each field is as high as possible with the proper ratio. The measured flow rate, therefore, is higher than that indicated for final operation. The next step in balancing is to adjust the circuit settler valves for each collector row (note this process is conducted with the collectors in the stow position). Once all of the collector row flow rates are set, the total flow to each bank is checked. The total system is now balanced for the cold condition. The next step is to focus the collectors and allow adequate time for the temperature rise in the system to stabilize. A set of mercury thermometers are mounted in the thermowells provided at the exit of each collector row. Final adjustment of the circuit settlers is made to provide a constant temperature output for all rows under clear sky conditions. This step is only a check because the cold condition flow balancing should provide a constant outlet temperature. Once the balancing has been accomplished, the system is shut-down and allowed to undergo the standard automatic start-up.

D. System Operation Sequence

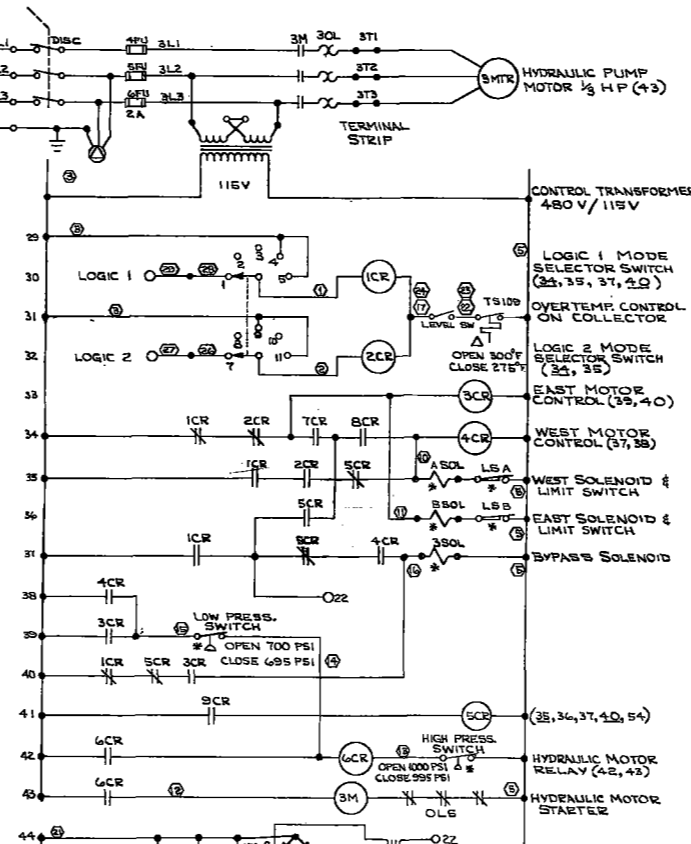
The system sequence of operation can best be understood by referring to the system elementary diagram shown in Figure 4. The Solar Process Heat System will only operate if the plant process hot water system is operating. If this process hot water system is operating, then the collector system central controller takes over when the central controller's direct normal light switch indicates minimum present direct normal levels for a minimum period of 5 minutes. The central controller issues a "track ready" command, if the wind speed is below 40 mph and there is no rainfall, to start



PUMP CONTROL PANEL ELEMENTARY DIAGRAM
NOTE: SUPPLIED BY CONTRACTOR



SOLAR MASTER CONTROL PANEL ELEMENTARY DIAGRAM
NOTE: PROVIDED BY OTHERS, WIRED AND INSTALLED BY CONTRACTOR



ROW COLLECTOR CONTROL
SEQUENCE OF OPERATION

- Relays 1 and 2CR (line 20 and 22) are energized by the logic 1 and logic 2 outputs of the solar master control. When 1 and 2CR are energized, contacts 1CR and 2CR (line 21 and 23) engage and actuate the west and bypass solenoids (line 33 and 37).
- These solenoids will remain actuated for 1 min or until the row light threshold sensor (line 25) deactuates the collector has acquired the sun. The light threshold relay 1CR (line 20) energizes relay 2CR (line 41) which opens contact 2CR (line 21, 22, 40) and deactuates the west and bypass solenoids (line 33, 37).
- As the time the collector is in the automatic track mode, the tracker head (line 54) contains 2 phototransistors, one located on the west side and one on the east side. The outputs of these transistors are directly proportional to the amount of light they are exposed to.
- The outputs from the phototransistors are input to OA1 (Operational Amplifier 1 line 52). OA1 is configured as an analog subtractor. Its output is the difference between the outputs of the phototransistors.
- The output of OA1 is input to OA2 and OA3 (line 52 and 53) which are configured as comparators. They compare the output of OA1 to the high and low bounds of the deadband. The deadband is a range of voltage (set by R1 line 53) that does not produce an output from either comparator. This feature is necessary to prevent the collector from oscillating.
 - If the output of OA1 is greater than the high bound of the deadband (i.e., the west phototransistor is irradiated significantly more than the east phototransistor) then OA2 (line 52) will produce an output which will energize 2CR (line 22). When contacts 2CR close (line 22) relay 4CR (the west motor control line 20) and the west solenoid (line 33) are actuated causing the collector to track west.
 - If the output of OA1 is less than the low bound of the deadband (i.e., the east phototransistor is irradiated significantly more than the west phototransistor), then OA3 (line 53) will produce an output which will energize 1CR (line 20). When contacts 1CR close (line 20) relay 4CR (the east motor control line 20) and the east solenoid (line 37) are actuated causing the collector to track east.
- When either motor control relay 1CR or 2CR is energized the appropriate contact 3CR or 4CR (line 20 or 22) is closed which will energize relay 6 (line 42) which closes contact 6CR (line 42) thereby actuating the hydraulic motor start/stop if the hydraulic pressure is less than 200 psi (set by the low pressure switch (line 25)). When the pressure exceeds 1000 psi as determined by the high pressure switch (line 40), relay 6CR (line 42) is de-energized, contact 6CR (line 42) is opened and the hydraulic motor start/stop (line 42) is turned OFF.

- NOTES:**
- Unenergized contactors are on a normal circuit break.
 - When all three transistors in a given collector pump is series. Carry 2 conductors each group down to solar distribution panel.
- A on collector

PUMP CONTROL PANEL
SEQUENCE OF OPERATION

- Power will be supplied to the field pumps only when contacts 58 and 13CR (line 5) are closed.
 - Contact 58 (line 5) is closed by relays to the boiler room on the MCC-4 control panel when the plant process hot water is operating.
 - Contact 13CR (line 5) is closed by relay 13CR (line 13) in the Solar Master Control.
- Power is supplied to the selected lead pump (known as pump #1) by energizing relay 18 (line 2) which closes contact 18, in the primary motor starter circuit thereby starting pump #1.
 - Power is also supplied to relay 23CR (line 10) through normally closed FLS10B (line 10) which closes contact 23CR (line 3 & 4). This provides power to these delay relay 23TD (line 2). If flow is not established, as indicated by FLS10B, within the 4 sec. time delay time:
 - contacts 23TD on line 2 close, latching relays 23TD (line 2) and 23TD (line 3)
 - contacts 23TD on line 6 open, disconnecting power to the lead pump
 - contacts 23TD on line 13 close, to power the alarm horn
 - contacts 23TD on line 11 close, illuminating the lead pump failure light (11L) (line 11) and energizing relay 28 (line 8) whose contacts provide power to the secondary motor starter
 - When power is supplied to pump #2, flow delay relay 22TD (line 2) is also energized. If flow does not begin 4 sec. from the time 22TD is energized (line 2) then:
 - contacts 22TD on line 10 open disconnecting power to 28 (the secondary pump starter)
 - contacts 22TD on line 12 close to illuminate the secondary pump failure light 22L (line 12)
 - contacts 22TD on line 14 close to power the alarm horn 14H (line 12)
- If any time freeze stat TS10B (line 1) indicates an ambient temperature of 20°, relay 20CR (line 1) is energized which provides power to relay 18 (line 2) thereby starting the lead pump.
- The lead pump can be changed from pump #1 to pump #2 by manually actuating the lead pump selector switch (line 6).

SOLAR MASTER CONTROL
SEQUENCE OF OPERATION

- When the field light switch sensor (line 25) indicates minimum present direct normal irradiance for a period of 15 minutes, relay 13CR (line 13) is energized (track ready command) and the field pump control circuit is actuated.
- Five minutes after the track ready command has been issued, relays 1CR and 2CR (line 10) Logic 1 and Logic 2 energize the two collector contact wires a "-" signal which deactuates the collectors out of the stow position by actuating the west solenoid (line 33) and the east solenoid (line 37). This signal is continued for five minutes which will allow each row to acquire the sun.
- After five minutes, the microprocessor (line 18) will de-energize 1CR thereby opening contact 1CR (line 20) giving a "-" signal. The "-" signal is the automatic track signal and is maintained until the minimum direct normal light level is not met.
- If the minimum direct normal light level is not met, then 20CR is released and 1CR is energized providing the signal for control dead band "-" signal and all collectors will remain in dead band until the control controller receives the automatic track signal "-" signal.
- Each tracker has sufficient acquisition aperture to reacquire the sun if the signal is replaced within one hour. If direct normal irradiance are not met for a period of one hour, the control controller will provide a "-" signal which de-energizes 1CR (line 20) and 2CR (line 22). The collectors will be driven to stow position at this time less Row Collector Control sequence of operation).
- Other conditions which will cause the control controller to provide a "-" signal to stow the collectors are:
 - detected by 13CR (line 13) and high wind speed (detected by 10TB (line 25)). The accumulated, pressurized hydraulic fluid in the tracking system has sufficient power to stow the collectors in the stow A/C power line loss, which will obviously provide a "-" signal.
- In the event of a loss of flow as FLS10B or 10T (line 21), overtemperature at 13TB or 13T (line 17), or overpressure at 10PB or 10P (line 17), the heated loop will be opened which will cause a "-" signal.

1-B-BID ISSUE

DATE: _____ REASON FOR ISSUE: _____

RECORD OF ISSUANCES

CATERPILLAR TRACTOR CO.

PLANT: SAN LEANDRO, CALIFORNIA

SECTION: _____

DESCRIPTION OF OPERATION: BB ELEMENTARY DIAGRAM

FIELD RELEASE: _____ DATE: _____

APPROVED: _____

SOUTHWEST RESEARCH INSTITUTE

DATE: _____

APPROVED: _____

E-242

the system flow pumps. After a 2-minute delay to allow fluid flow to be established, the collectors are directed out of the stow position which takes about 30 seconds for early morning conditions. As each collector row approaches the sun and falls within 20° of focus, one of the row controller's light sensors will switch the row to automatic track. This signal is maintained as long as the minimum light level is met and the receiver tube temperature is below the critical value. The temperature regulating valve on each bank will open when its temperature sensor indicates a temperature in excess of the HHWR design temperature. Prior to the opening of the regulator, a 10% by-pass is provided for cold start-up. If direct normal radiation minimums are not met and the outlet temperature falls below the HHWR line temperature, the temperature regulator closes and the flow drops to the 10% level. In the event that this continues for a preset period (adjustable up to 45 minutes), the central collector controller will stow the collectors and shut off the pump. The collectors will remain in this position until the original automatic start-up sequence is reinitialized.

The only exception to the above operating scenario is when the field temperature switch senses a freeze condition and the above automatic sequence is overridden. When this occurs the system pump turns on and the 10% by-pass flow is pumped through the collectors. The pumps will cycle on and off throughout the freeze condition based on a predetermined timing cycle to prevent damage to the system. The number of times that this occurs is anticipated to be only one day during an average year.

E. System Photographs

With this description of operation in mind, the following set of pictures can be better understood. Figure 5 shows an aerial view of the plant roof top with the north collector bank at the left side of the photograph and the larger south collector bank at the right side. The solar master control panel and the weather station are both located in the upper left portion of the roof. A single collector row is shown in Figure 6 with the observation platform located to the upper left of the collector. The view from the observation platform looking between rows

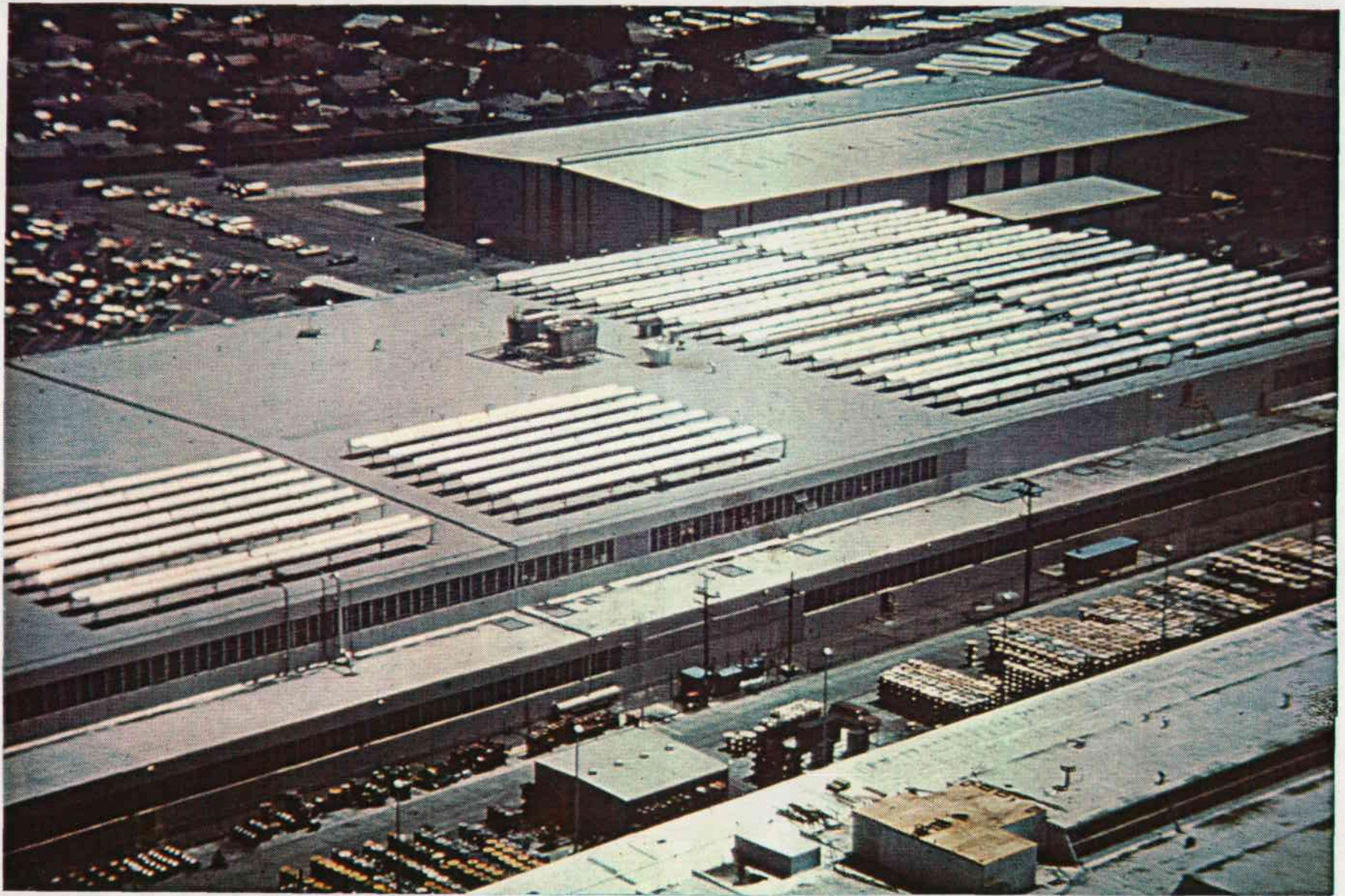


FIGURE 5. AERIAL VIEW OF THE COLLECTOR FIELD

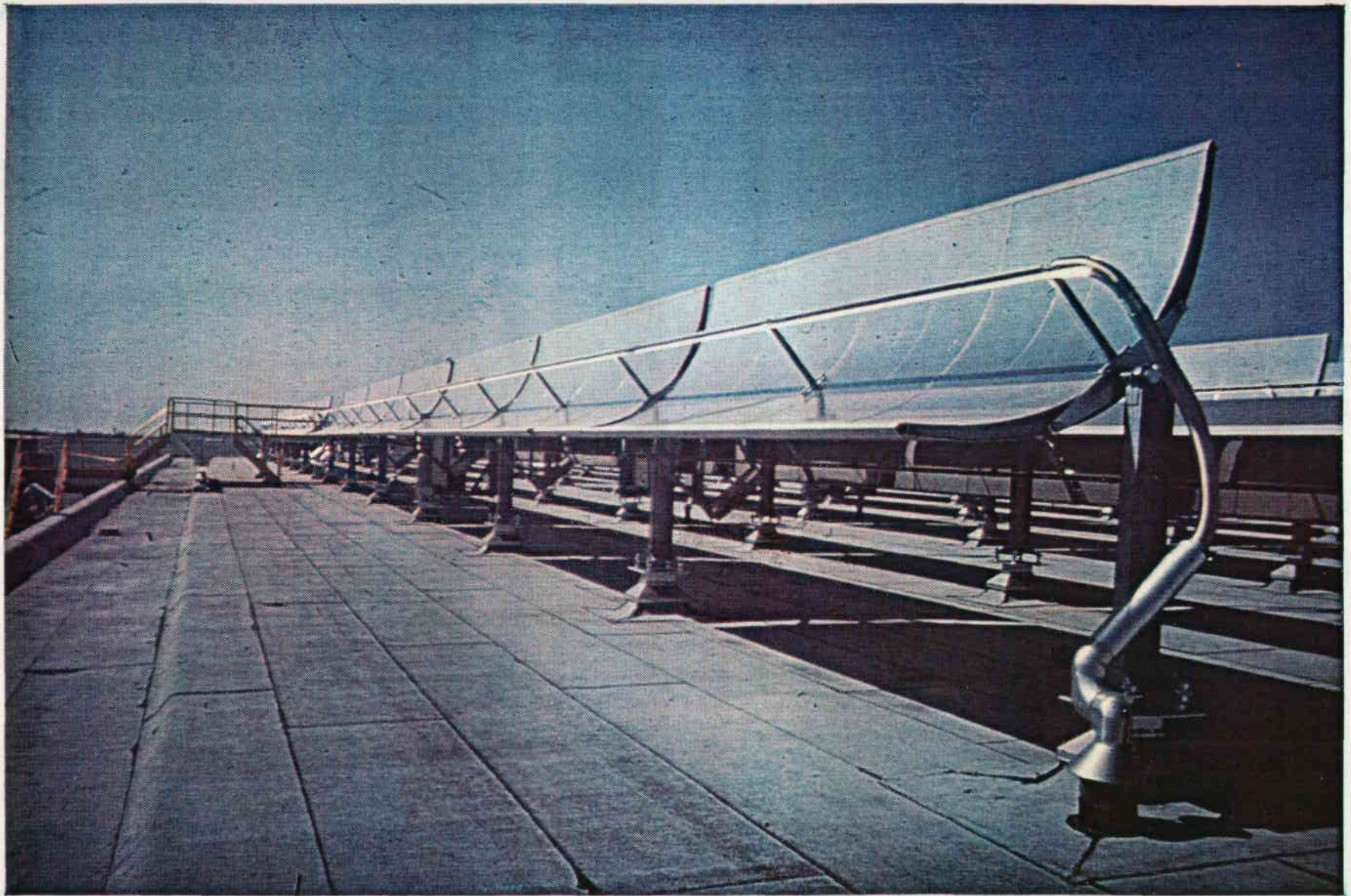


FIGURE 6. SINGLE COLLECTOR ROW

of the delt-T string, showing the row piping, is presented in Figure 7. Figure 8 shows a row drive pylon with control panel along with structural mounting hardware. An interior view of the row control panel is shown in Figure 9. The high voltage (480 VAC) motor control hardware is located to the right of the partition and the low voltage (120 VAC and 12 VDC) control board to the left. The individual row temperature switch is shown in Figure 10 and the row tracker head is shown in Figure 11. The collector row end piping is shown in Figure 12 with the collector in focus. Note the number stenciled on the end pylon, each drive row has its own unique number to facilitate operation and maintenance records. Figure 13 shows one of the system outlet piping downcomers. This downcomer is located on the second floor of the plant and includes (starting from the top) the TRV temperature probe; flow, temperature and pressure switches; straining; TRV; and by-pass loop with circuit setter. The electrical power distribution panel, located on the second floor, is shown in Figure 14. The upper section houses the data acquisition sensor terminal blocks and the lower section houses the high voltage power switch gear. Figure 15 shows the solar master controller with the central light switch, wind switch, rain switch, and freeze sensor mounted on the exterior. The pump control panel is shown in Figure 16 with the Venturi flow gauges (in the upper right hand corner), and pump capacitors (in the lower right hand corner).

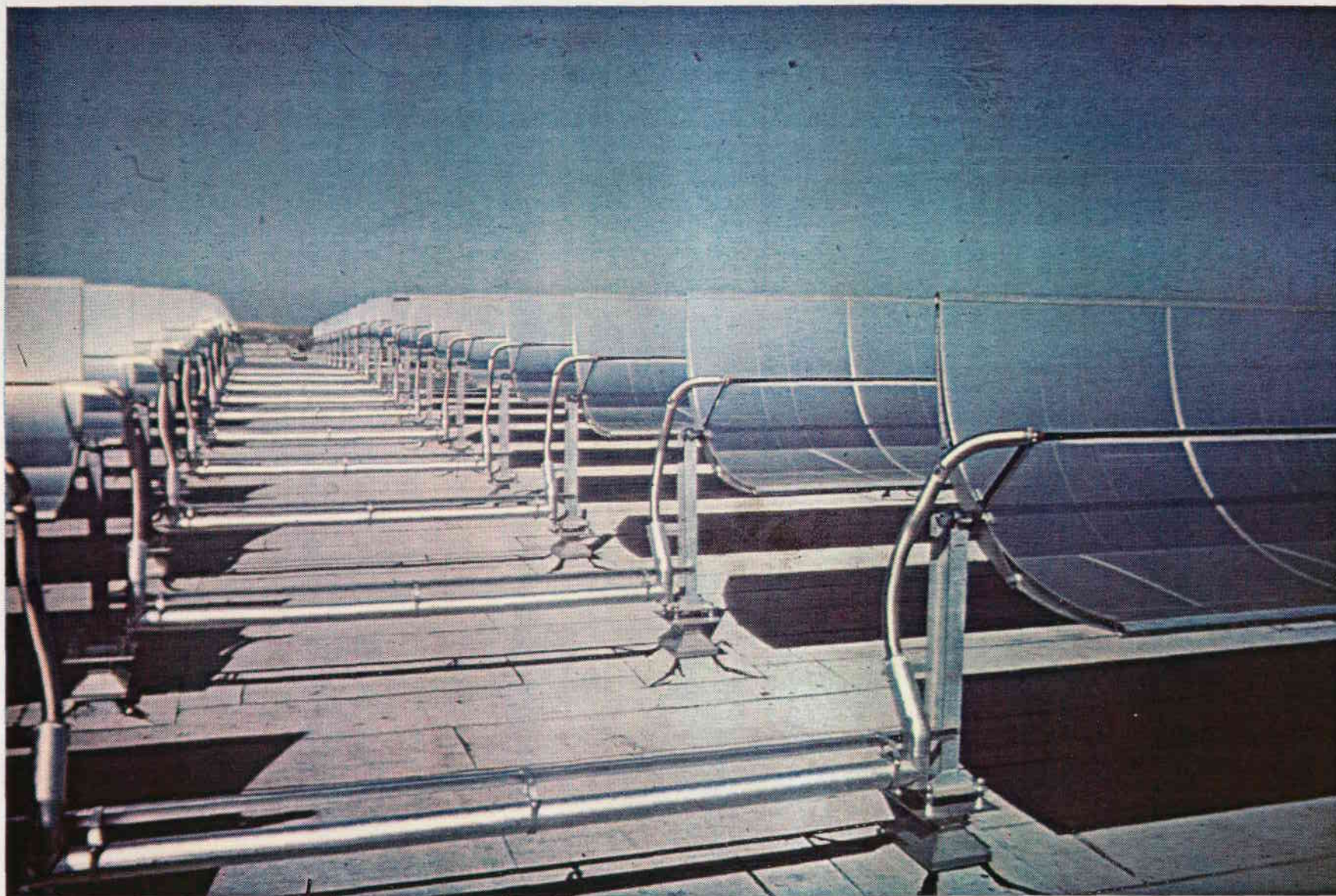


FIGURE 7. PIPING BETWEEN COLLECTOR ROWS

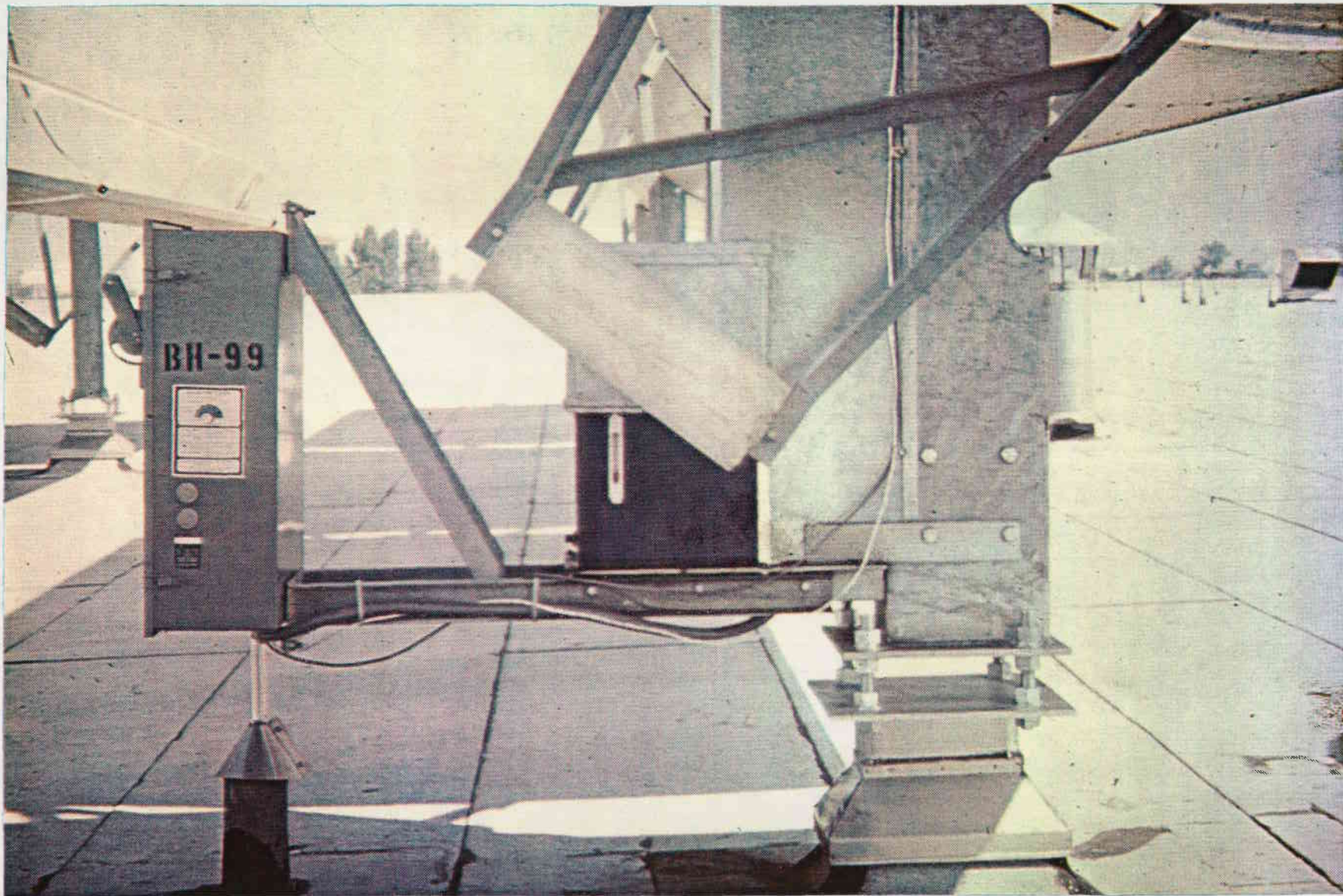


FIGURE 8. COLLECTOR DRIVE PYLON

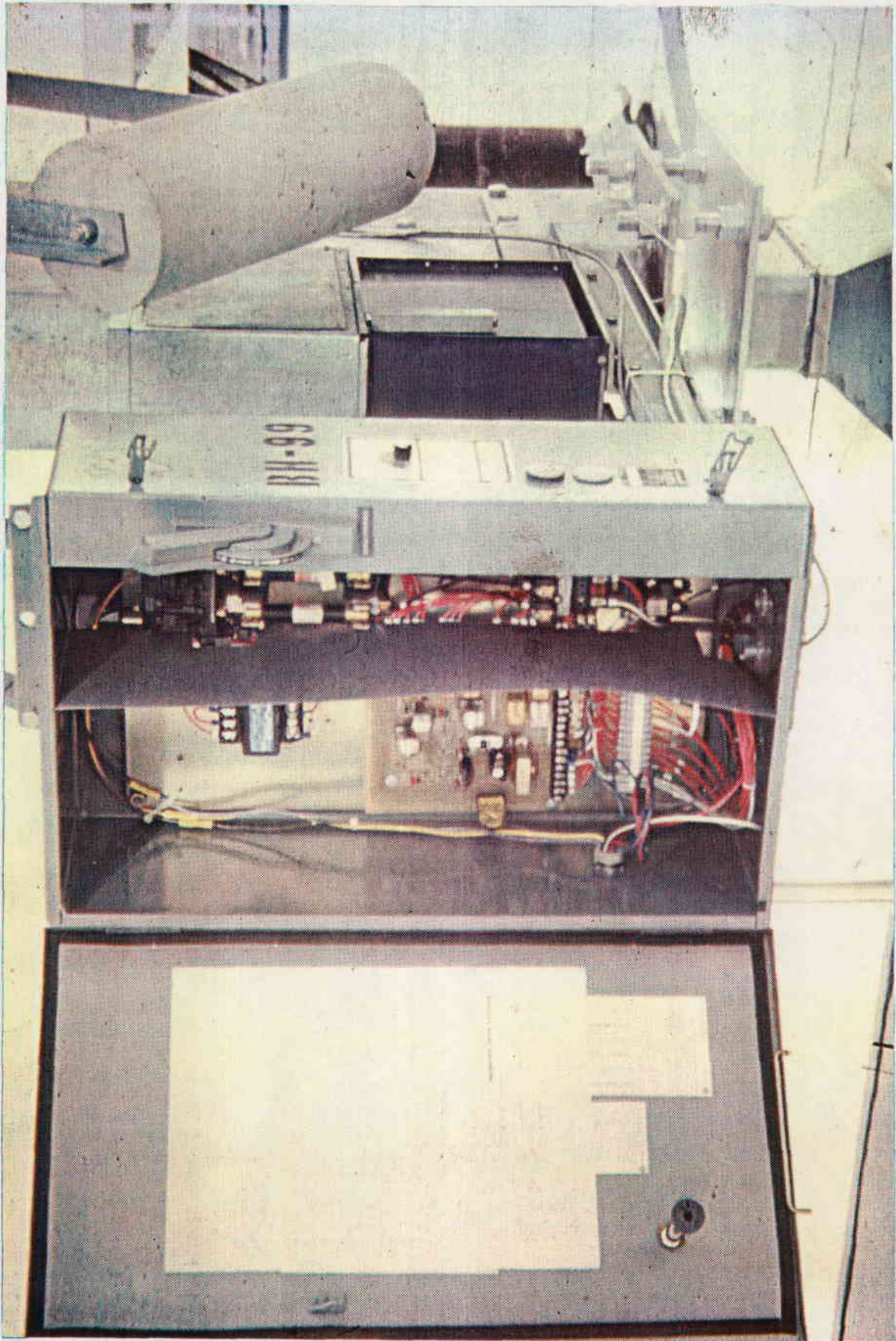


FIGURE 9. COLLECTOR ROW CONTROL PANEL

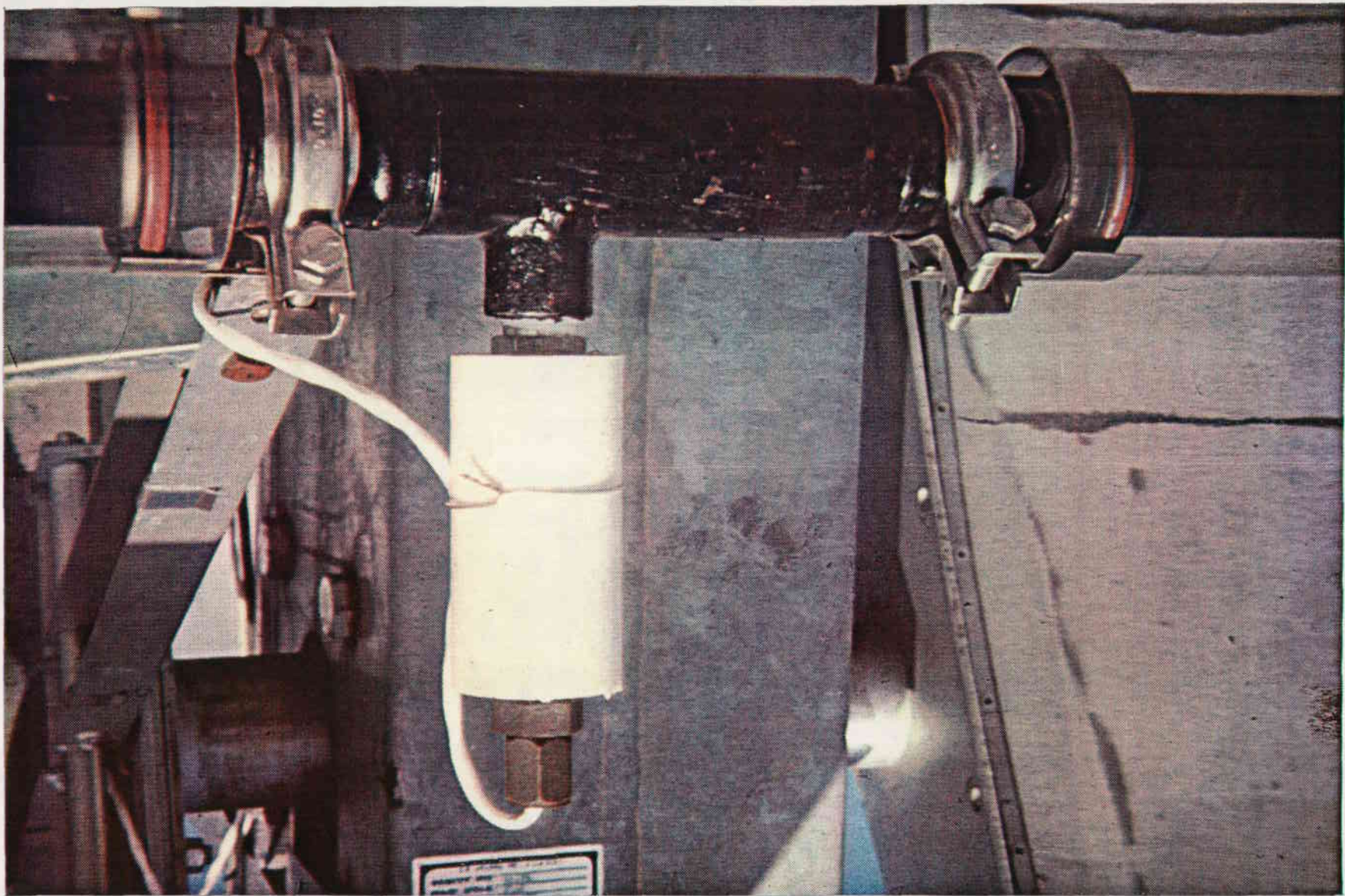


FIGURE 10. COLLECTOR ROW TEMPERATURE SWITCH

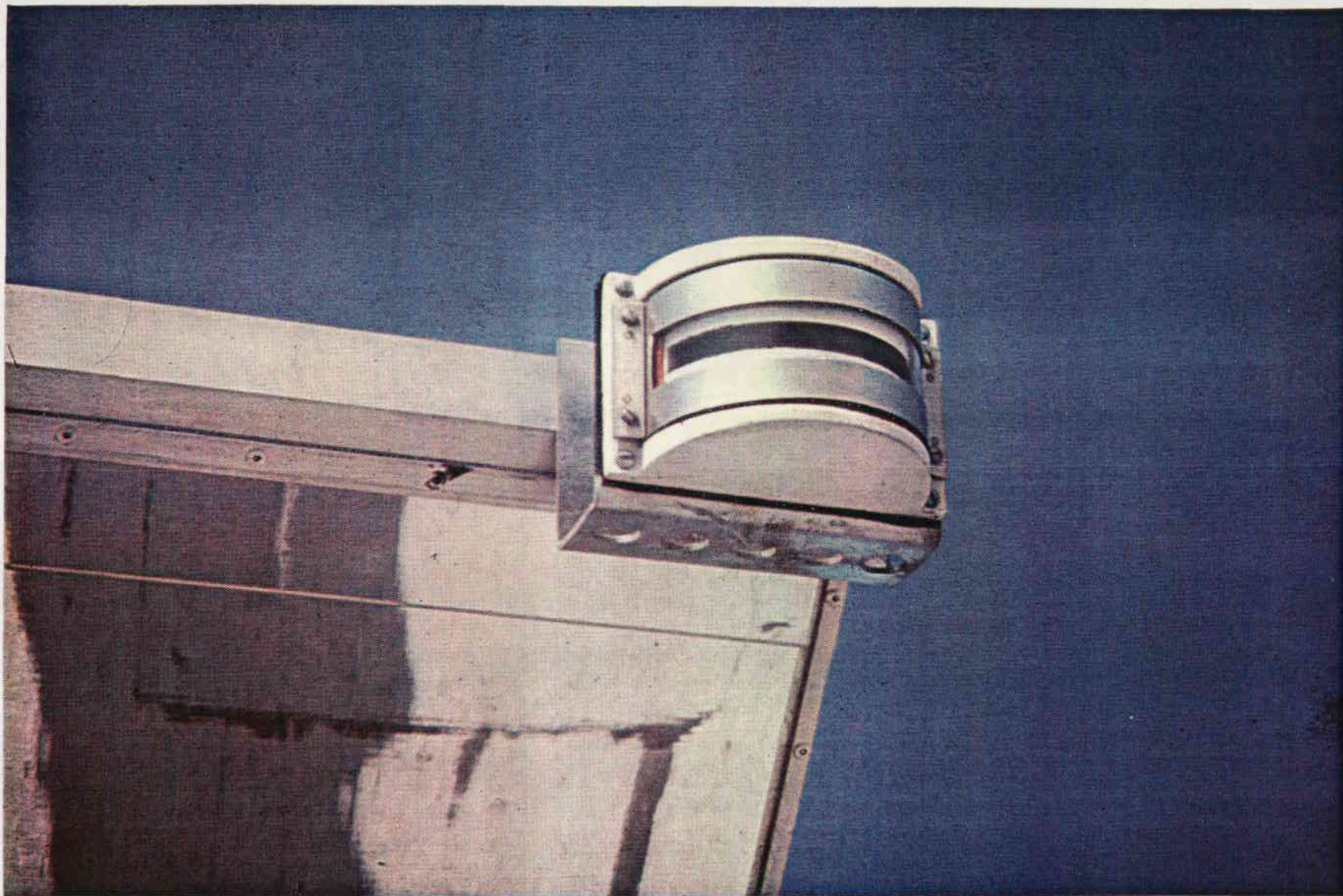


FIGURE 11. COLLECTOR ROW TRACKER HEAD

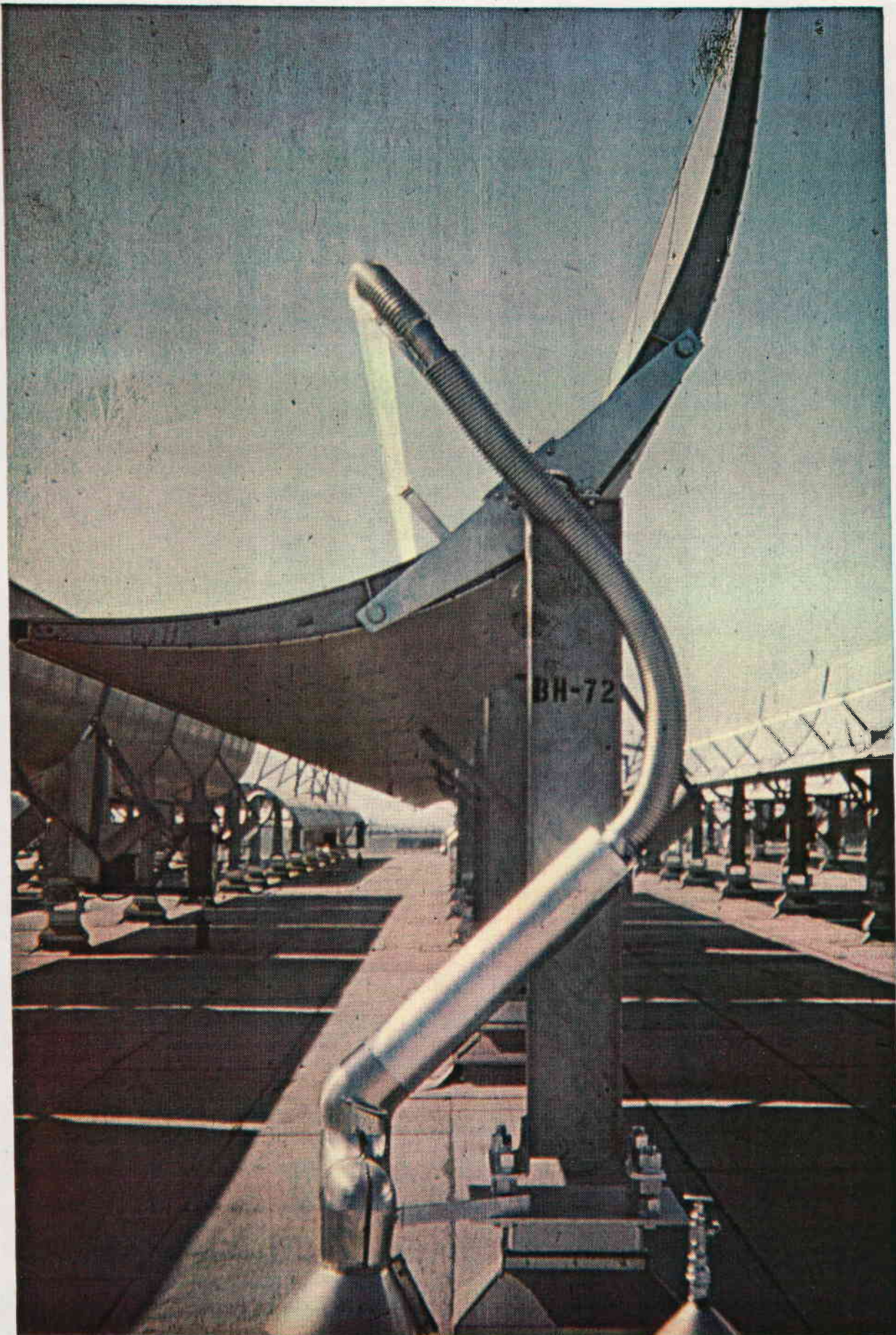


FIGURE 12. COLLECTOR ROW END PIPING

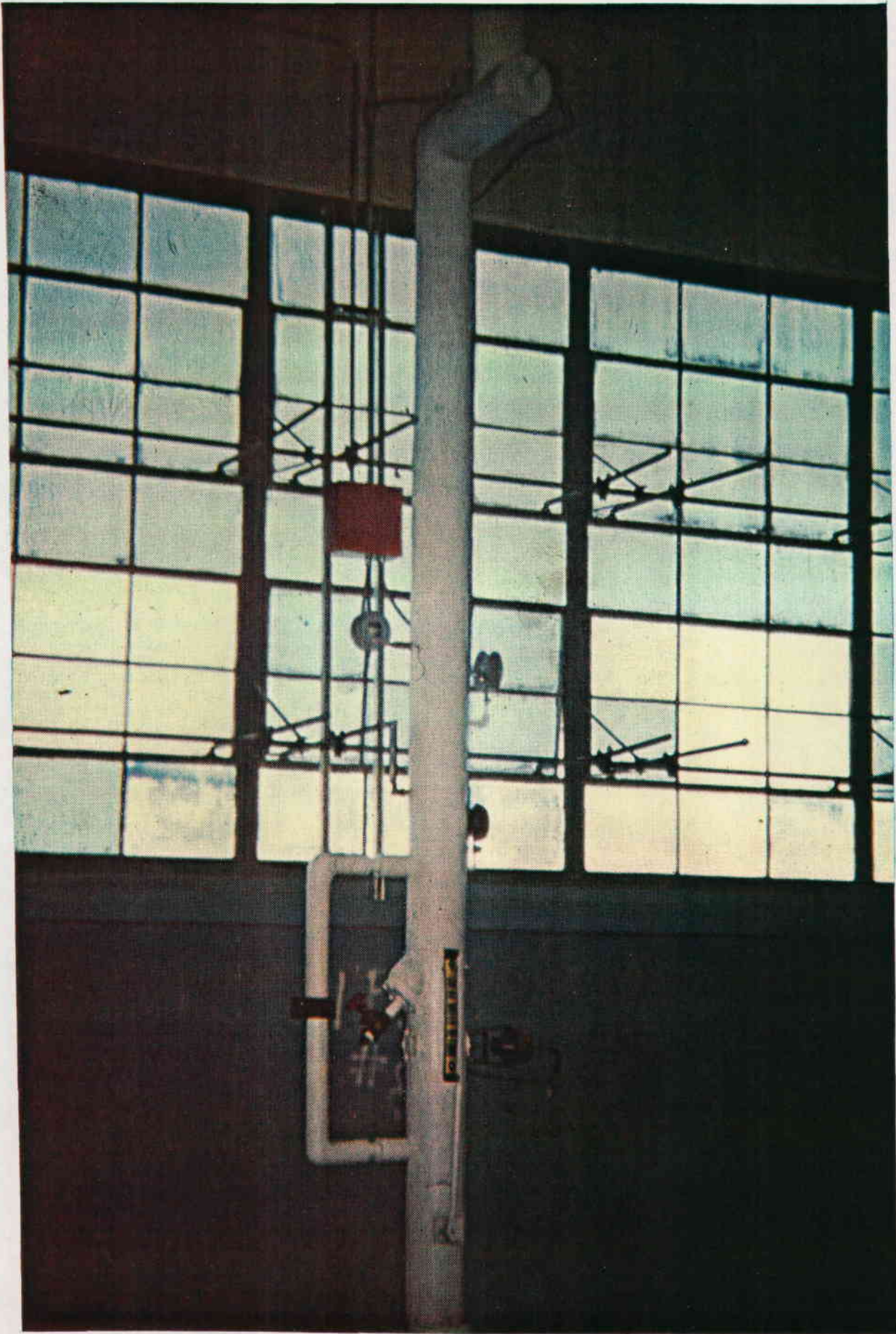


FIGURE 13. SYSTEM OUTLET PIPING WITH TRV

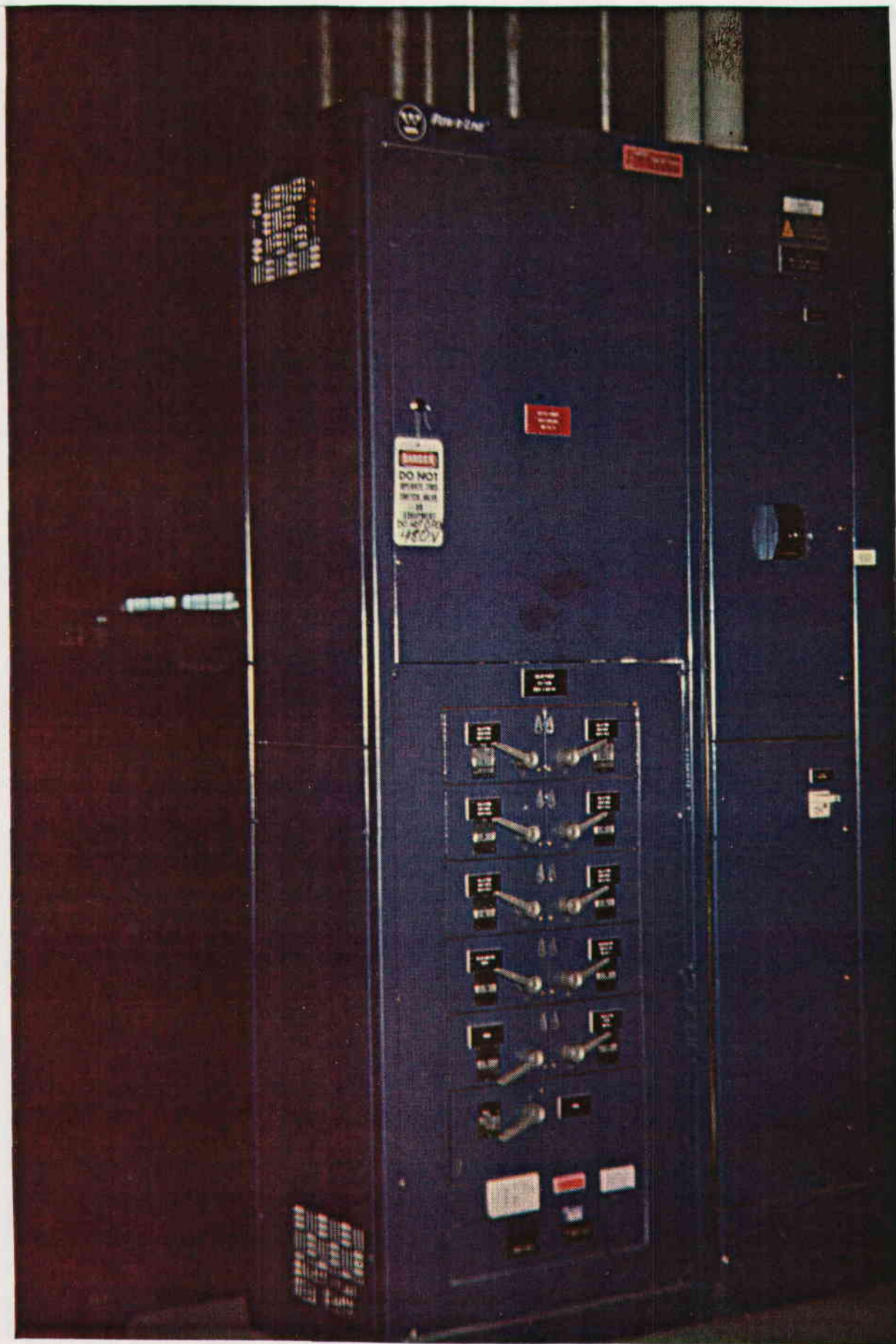


FIGURE 14. ELECTRICAL POWER DISTRIBUTION PANEL

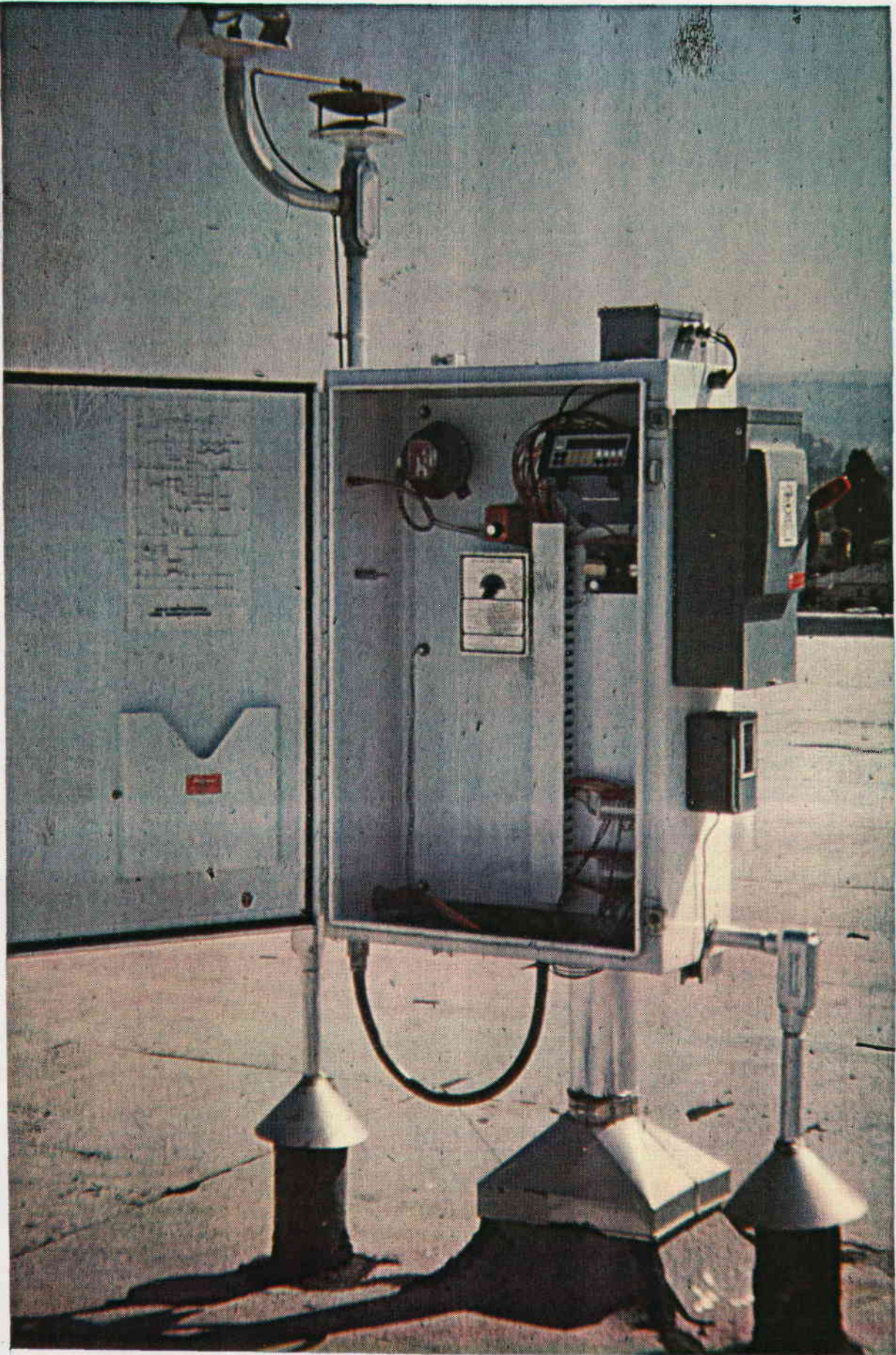


FIGURE 15. SOLAR MASTER CONTROL PANEL

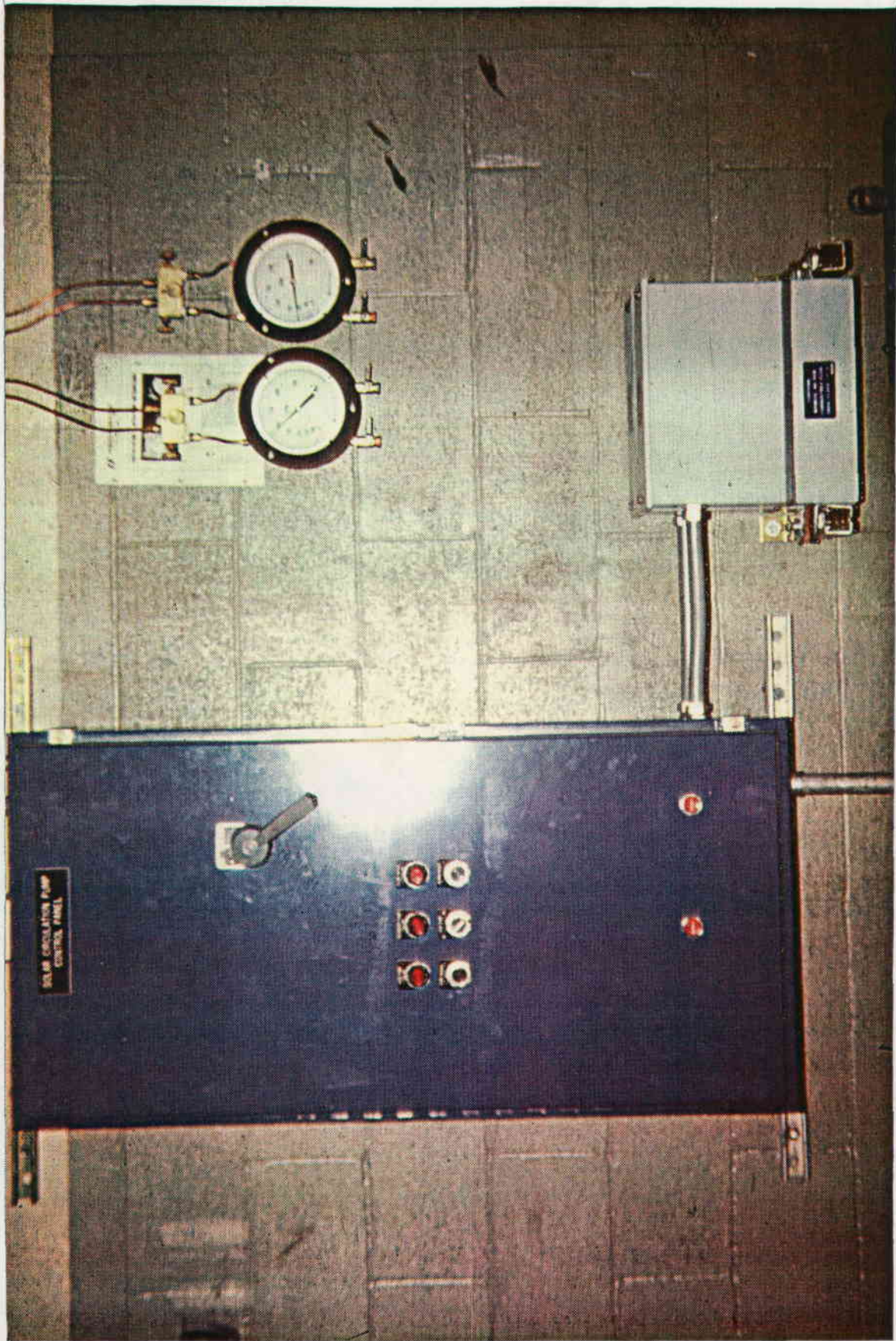


FIGURE 16. PUMP CONTROL PANEL

INSTRUMENTATION

INSTRUMENTATION

IV. AUTOMATIC DATA ACQUISITION SYSTEM

A. Introduction

A computer based data acquisition system (DAS) was designed and installed to monitor the performance of the solar system. This DAS collects data from various sensors that measure temperature, flow, etc., and processes these data to produce complete summaries of system thermal performance.

By way of introduction, it may be helpful to present photographs of certain facets of the system so the reader is familiar with the hardware before the DAS is discussed.

Photographs of specific portions of the DAS hardware are shown in Figures 17 through 19. Figure 17 shows the computer hardware. On the left is the LA36 line printer for obtaining "hard copy" of desired data lists and graphs. Next to this is a cabinet which supports the VT100 terminal, 11/23 CPU, and both disk drives. Third from the left is the power supply cabinet, and last is the first floor terminal box for the sensor wiring.

Figure 18 shows the two pyranometers mounted on a collector to measure total radiation and diffuse radiation in the collector plane (SI100 and SI101).

Finally, Figure 19 shows the weather station mount. The anemometer (WV001, WD001) and the ambient temperature sensor (T001) are mounted on this structure.

B. Data Acquisition System (DAS) Objectives

The selection of parameters for the performance evaluation is based on a set of objectives established in the "Data Acquisition and Analysis Guidelines for IPH Demonstration Projects" by Kutsler and Kearney from SERI. These objectives are as follows:

- o Determine the energy delivered to the process by solar collector system on a monthly and an annual basis.



FIGURE 17. COMPUTER DATA ACQUISITION SYSTEM

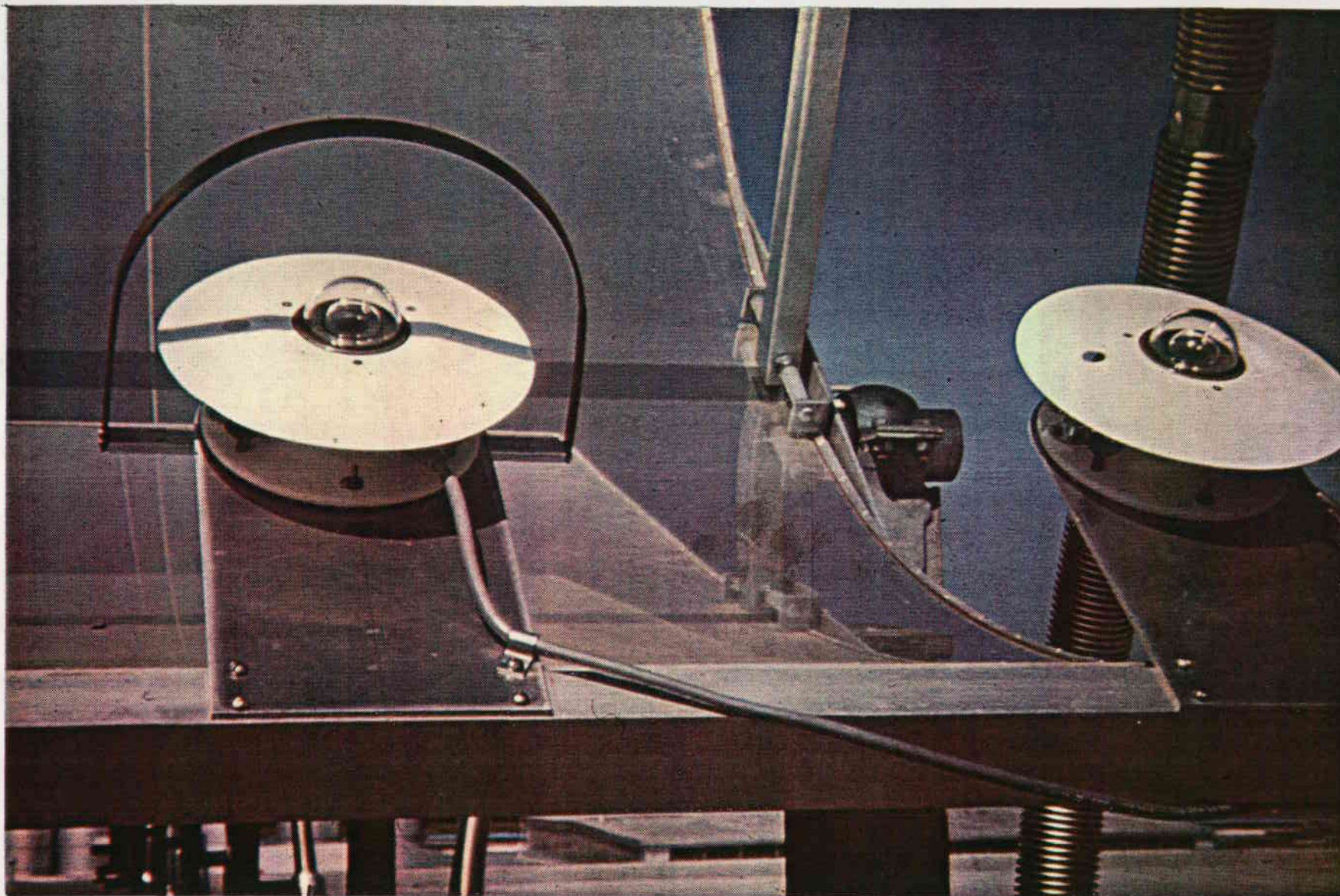


FIGURE 18. SOLAR RADIATION MEASUREMENT SENSORS

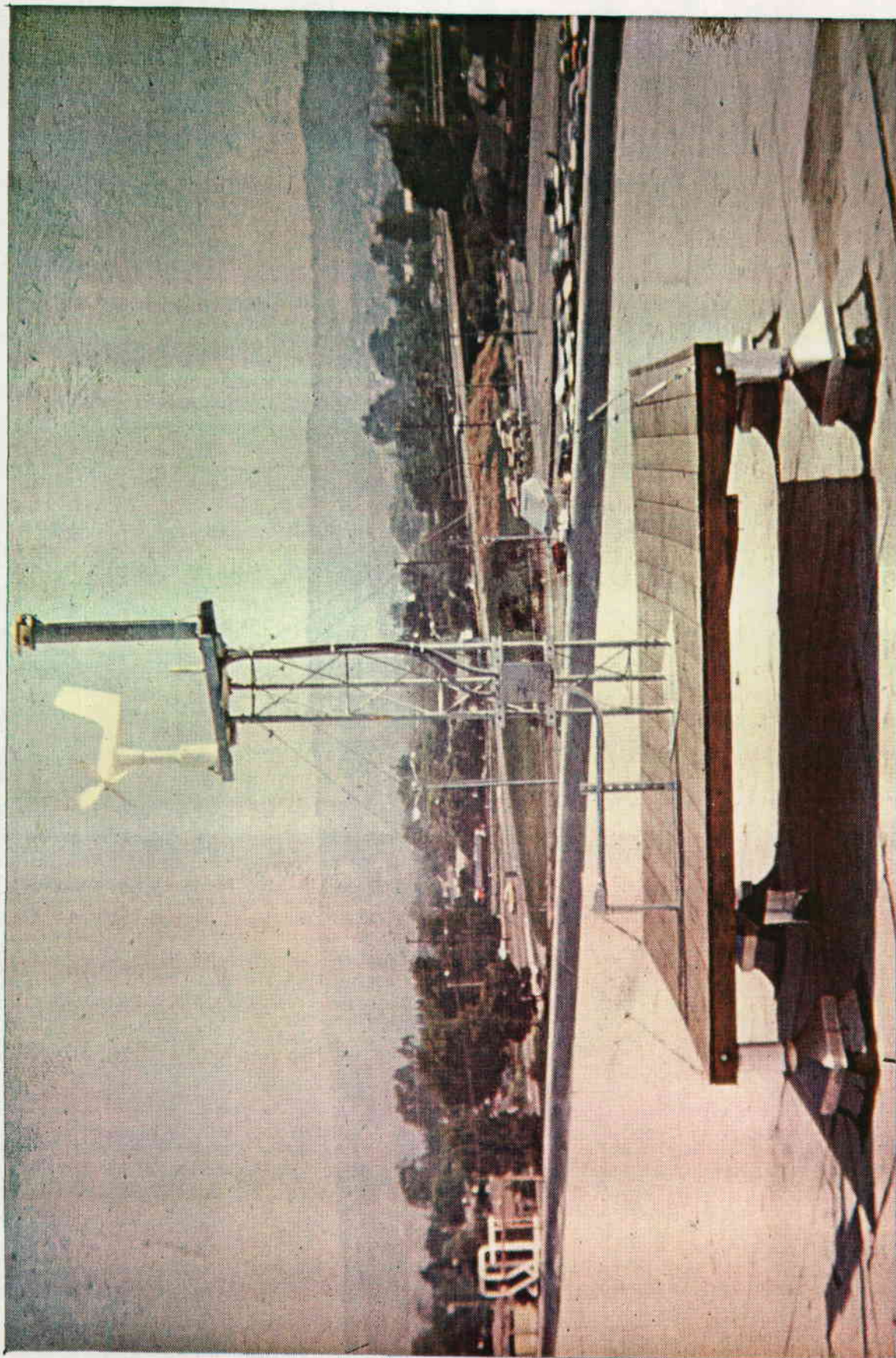


FIGURE 19. WEATHER STATION

- o Determine parasitic energy used by the solar collector tracking and pumping system on a monthly and an annual basis.
- o Determine the percent of solar energy to other fuel sources on a monthly and annual basis.
- o Determine collector array efficiency on a "instantaneous", daily, weekly, and annual basis.
- o Determine significant losses (piping runs, etc.).
- o Determine changes in collector system operational characteristics with weather exposure.
- o Determine long-term reliability in terms of materials, components, and system performance.

To achieve the objectives, a set of parameters must be measured and used to determine the following:

- o Short-wave solar radiation available at the collector field.
- o Thermal energy collected by the collector field.
- o Solar-thermal energy transferred to the process.
- o Thermal energy losses from the system.
- o Non-solar thermal energy transferred to the process.
- o Parasitic energy required for collector tracking and pumping.
- o Environmental conditions affecting the thermal loss characteristic of the collector field.

A discussion of each of the above topics to be addressed by the DAS follows below. For purposes of this discussion and the remaining subsections, the titles of each of the required transducers are introduced here.

1. Solar Radiation

Short-wave solar radiation measurements consist of three categories: direct beam, diffuse horizontal, and total horizontal. The direct beam component is the focusable component of energy included within a $1/2^\circ$ cone about the sun's center. When passing through a turbid atmosphere, with

large aerosols, a significant amount of energy is translated into a cone of about $\pm 5^\circ$. This energy is designated as the circumsolar component. This circumsolar component has the same general angular time variations as the direct component and results from forward scattering of the sun's rays. The diffuse component ("sky radiation") results from atmospheric scattering. This component requires a measurement with a stationary, horizontal, absorbing surface. Radiation which is available to the collectors is limited to direct, circumsolar, and a portion of the diffuse. The available radiation is limited by the collector acceptance angle. Thus, to measure the total radiation seen by the collector, two pyranometers were mounted to track with a collector row. One will provide total radiation as a function of collector angular position, and the other will have a shadow band to block radiation in the collector aperture; thus, the radiation at the collector is the difference between the total and the shadowed measurements. The specific designations for each pyranometer are:

- SI100 - Solar Radiation in the Plane of the Collector
- SI101 - Solar Radiation in the Plane of the Collector with
Shadow Band
- SI102 - Total Horizontal Solar Radiation

2. Thermal Energy

To determine the thermal performance of the solar collector system, temperature and volumetric flow rates will be measured. These measurements will allow the determination of the solar energy transferred to the process, and thermal losses from the solar collector system, piping, and non-solar thermal energy transferred to the process. The temperature and flow measurements required to categorize the thermal performance are as follows:

- TE100, TE101 - North and South Collector Bank Inlet Temperatures,
Respectively
- TE102, TE103 - North and South Collector Bank Outlet Temperatures,
Respectively
- TE104, TE105 - North and South Collector Row Inlet Temperatures,
Respectively

- TE106, TE107 - North and South Collector Row Outlet Temperatures,
Respectively
- TE110 - Supply Pump Outlet Temperature
- TE112 - Supply Pump Inlet Temperature
- FE100, FE101 - North and South Collector Bank Inlet Flow Rates,
Respectively
- FE102, FE103 - North and South Collector Bank Outlet Flow Rates,
Respectively
- FE104, FE105 - North and South Collector Row Flow Rates,
Respectively
- FE200, FE202 - Natural Gas Boiler Flow Rates

With these measured quantities, the thermal energy transferred for each of the specific cases can be calculated using the following equation:

$$Q = m C_p (T_{f,o} - T_{f,i})$$

The thermal energy from the solar collectors, non-solar energy, and thermal pipe losses require the calculation of mass flow rate, m , by multiplying the volume flow rate, w , by the density, ρ , at the average fluid temperature. This result is then multiplied by the fluid specific heat (C_p) at the average fluid temperature and then multiplying by the temperature differential. Thermal losses are given by comparison of single row performance and collector bank performance after flow balancing is verified. Non-solar energy supplied is derived by measuring gas flow rate to the existing boilers. The use of multiple flow meters in each loop provides redundancy in the measurements. Each temperature location will contain dual RTD sensors to provide redundancy in the event of a sensor failure. A set of pressures across the collector banks will also be measured. These sensors provide information on abnormal system conditions (i.e., ruptured collector tube). The pressure sensors are designated as follows:

- PE100 - Supply Pump Inlet Pressure
- PE102 - Supply Pump Outlet Pressure
- PE104 - South Field Single Row Inlet Pressure
- PE105 - North Field Single Row Inlet Pressure

PE106 - South Field Single Row Outlet Pressure

PE107 - North Field Single Row Outlet Pressure

3. Parasitic Losses

Parasitic losses result from the energy required to power fluid transfer pump motors and the tracking system hydraulic pump drive motors. The electrical power will be measured by A.C. wattmeter transducers. The transducers are:

EP601 - Power to Primary Pump

EP602 - Power to Secondary Pump

EP603 - Power to Pylons BH 69-80

EP604 - Power to Pylons BH 47-58

EP605 - Power to Pylons BH 99-106

EP606 - Power to Pylons BH 91-98

EP607 - Power to Pylons BH 81-90

EP609 - Power to Controls

4. Environmental Conditions

Several environmental conditions other than solar radiation affect the operation of the collector field. The parameters are as follows:

Wind Speed - WV001

Wind Direction - WD001

Ambient Temperature - TE001

Wind speed and direction not only affect the convective loss from the absorber tube, but also tracking accuracy of the reflector. Ambient air temperature is a standard measurement and also provides information on losses from the collector tube, as well as external piping.

The following subsections describe the DAS hardware and software which were used to accommodate the goals discussed above.

C. DAS Hardware

The DAS hardware configuration is shown in the block diagram given in Figure 20. Sensor-signal conditioner combinations are located appropriately throughout the solar collector system. Their outputs are run in shielded cable

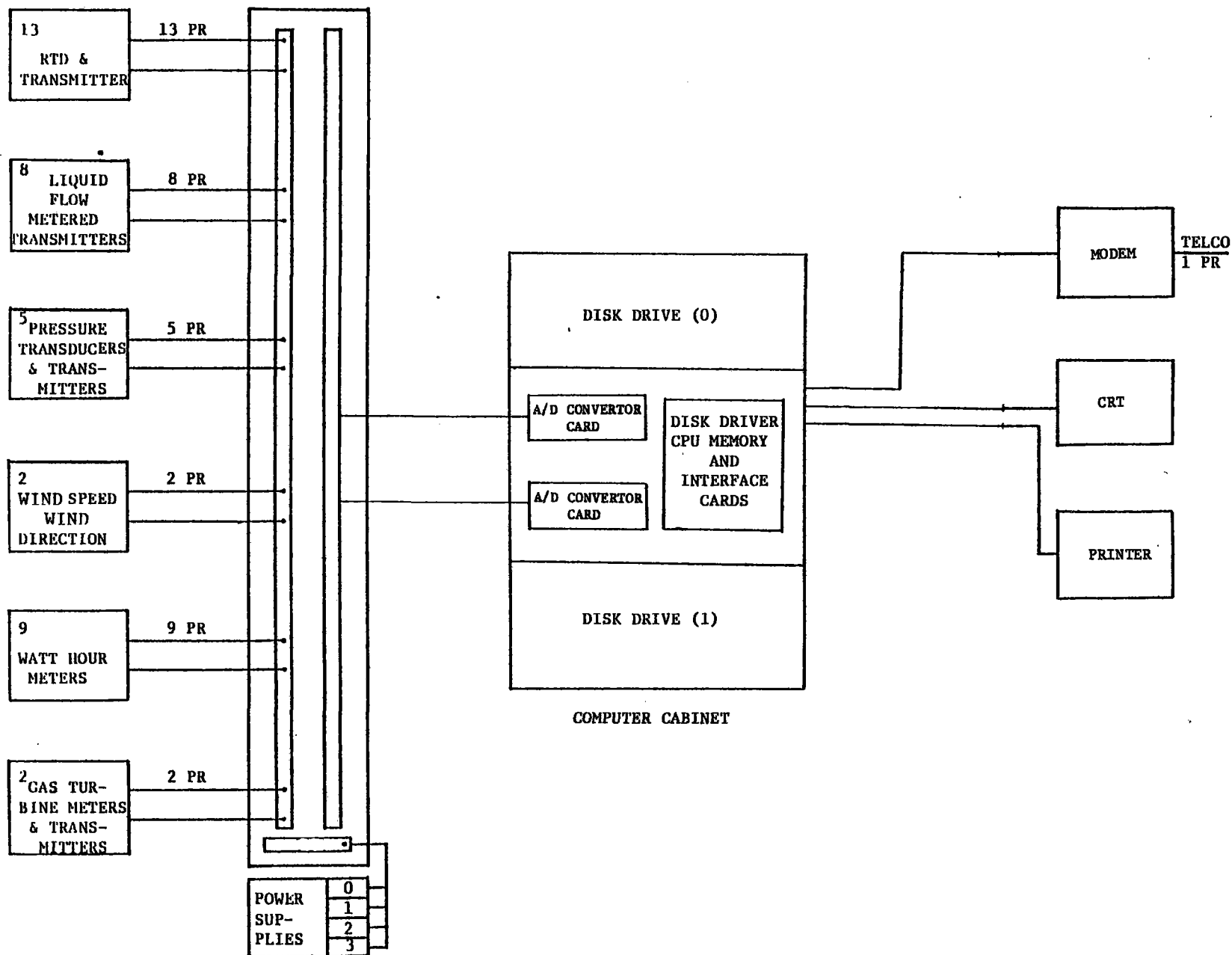


FIGURE 20. BLOCK DIAGRAM

to the computer, which periodically scans, processes, and records the signals and certain computed information. The DAS hardware can logically be broken into three sections:

- o computer hardware
- o sensors and signal conditioners
- o wiring and termination hardware

1. Computer Hardware

The DAS is based on the model SM-WXLLA BX PDP-11/23 micro-computer system. This basic system is comprised of the following:

- o PDP-11/23 CPU
- o 32k words of memory
- o two RL01 5 megabyte disk drives
- o interface cards
- o VT100 terminal (modified for graphics)

The following additional peripheral equipment is interfaced to complete the computer hardware package:

- o uninterruptible power supply (UPS)
- o LA36 line printer (modified for graphics)
- o UDS 103LP automatic answer modem
- o analog to digital converter cards

a. PDP 11/23 CPU

The PDP 11/23 is the heart of the computer hardware. This CPU provides the capability to perform all the functions necessary for collecting, processing, and storing the required data. The RSX-11M operating system is implemented with the 11/23 to provide user-oriented system capabilities. This operating system is relatively easy to learn and uncomplicated to use, as far as microcomputer operating systems are concerned.

b. Memory

The 32K words of memory supply space to hold the DAS software tasks and data for processing the data. The memory will not hold the entire DAS software, so an overlay structure was implemented, as discussed below.

c. RL01 Disk Drives

The 5 megabyte RL01 disk drives provide permanent storage of the DAS software, RSX-11M operating system, and system data. One drive is set aside for storage of data so that data disks can be readily changed with no affect on system operation.

d. Interface Cards

Various circuit board cards are necessary to interface the computer to the disk drives, line printer, CRT terminal, the analog/digital converters, and the modem for phone line hookup.

e. VT100 Terminal

A VT100 which was modified for graphics capability is used for controlling the computer hardware and for user interface with the system.

f. Uninterruptible Power Supply

The UPS consists of two packages. One contains a group of sealed maintenance-free batteries. The other is an inverter which converts the DC voltage to 110 volt AC when input power is interrupted. The batteries will support the system for 6-minutes without power. Since the UPS is connected to the building's emergency power, the system should only have to utilize the batteries for a few seconds while the emergency generator is started.

g. LA36 Line Printer

The LA36 is the DEC standard 300 baud hardcopy terminal, however, the DAS has been configured to treat the terminal as a line printer and ignore input from the LA36 keyboard. The LA36 has also been modified to operate as a graphics printer. This was accomplished by purchasing special hardware and software from the Selemar Corporation.

h. UDS 103LP Modem

The modem allows a user with a compatible modem and terminal to call and interact with the DAS over the phone.

i. Analog to Digital Converter Cards

The two RTI 1250 cards provide the interface between the computer and the analog signals output by the sensors and signal conditioners. Input signals are connected from the first floor termination box to a 50 wire ribbon cable which plugs into the 1250 card. There are 32 channels on each card numbered 0 to 31. The cards are set to receive 0 to 10 volt inputs. They return to the computer a number between 0 and 4096 which is directly proportional to the input voltage.

2. Sensors and Signal Conditioners

Making accurate measurements in an industrial environment poses many problems. Vibration, noise and electromagnetic interference are but a few of the difficulties to be contended with. RTD's, flow meters and other sensing devices typically output signals which are less than one-tenth of a volt. These signals are easily corrupted by the aforementioned factors and are also greatly affected by the resistance of the wires running out to the sensors. In order to deal with these problems, a signal conditioner was mounted at each sensor. The signal conditioners convert/clean-up the millivolt input signal into a linearized amplified current signal. The amplified current signal has greater noise immunity and is unaffected by the resistance of the wires running from the sensor to the computer.

All of the signal conditioners in this system are of the "two wire" variety. This means that the power and the output signal are one and the same. Therefore, it is not necessary to have both power and signal wires. The greater the input stimulus, the more current the signal conditioner draws. Although the signal conditioners for temperature, flow, radiation and wind sensors are mounted physically next to the sensors they are separate items and may be calibrated and serviced separately from the sensor. On the other hand, signal conditioners for the pressure and electrical power sensors are enclosed inside the sensor housing. These sensor-signal conditioner combinations, referred to as transducers or transmitters, were purchased as a single unit and must be serviced as such. The 38 sensor designations are listed in the previous subsection. The location of each of the sensors is shown in the system P&ID (Figure 3).

3. Wiring and Termination Hardware

The wiring and termination hardware is that equipment necessary to provide power to the sensors and to route the sensor output signals to the computer.

The sensors are located throughout the solar system and manufacturing plant, so that the signals must be routed from each of the sensors to a terminal box located on the second floor. This second floor box is connected to a terminal box located near the computer on the first floor. The conduit routing is as shown in the as-built drawings (Section IX).

The wiring for each sensor can be represented by the same general schematic, shown in Figure 21. Twenty-four VDC power is supplied to each sensor via the wiring. The signal conditioner controls the current through the wiring at a level proportional to the input from the sensor. The 500 Ω precision resistor provides a voltage differential due to the current forced through it. This voltage is sensed by the A/D cards in the computer hardware and is converted to engineering units during the data processing operations of the DAS.

D. DAS Software

The DAS software is comprised of 23 separate operating tasks. Each of these tasks is a block of executable code made up of one or more programs which performs a specialized function or process on the solar system data. These processes range from the collection of the raw data from the sensors to plotting a monthly summary of system performances seen in the following list:

- o realtime display and analysis of data
- o listings of historical data
- o plots of historical data
- o daily performance table
- o daily summary graph
- o monthly performance table
- o monthly performance graph
- o permanent storage file of recorded data

All 23 tasks are not listed here since several of the tasks may be necessary to provide any one of the above services.

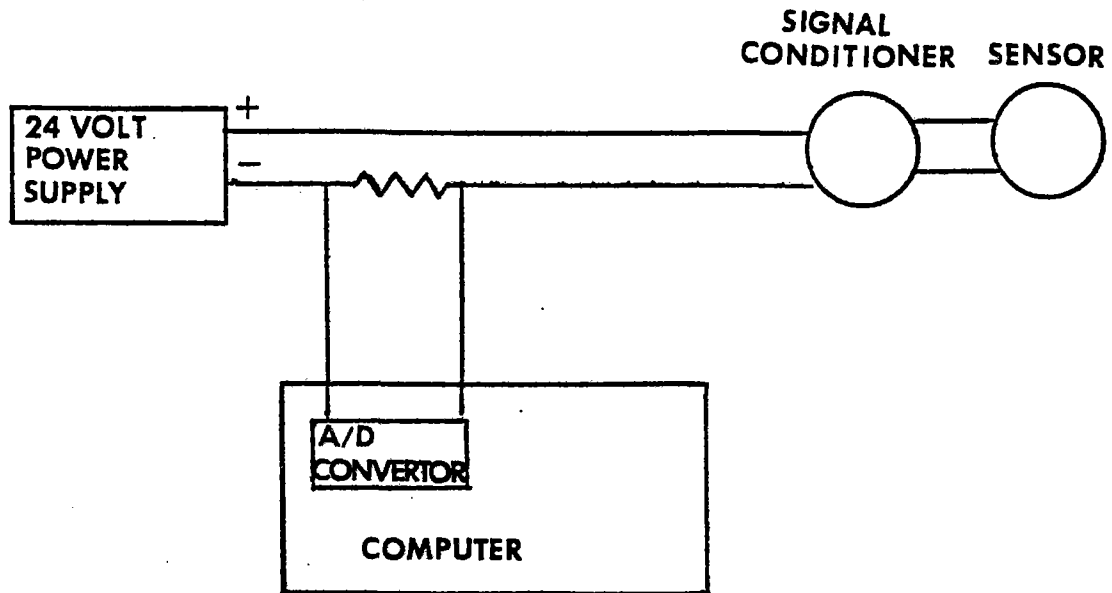


FIGURE 21. SENSOR CURRENT LOOP WIRING

The complete software system has been broken down in this manner so that only 32K words of memory are required for task storage at any given time. This means that tasks are brought into memory as required, to perform its operation. The RSX-11M operating system is well suited to provide this capability. This operating system can support various task priorities, so that data acquisition is not delayed for the sake of, say, plotting performance summaries.

The tasks in this system are divided into two major groups: the data acquisition tasks and the user interface tasks.

The data acquisition tasks collect, process, and store the data from the signal conditioners. These tasks receive the highest priority of all the system tasks. Whenever the A/D's need to be scanned and data needs to be processed for storage, the DAS stops any user interface operation, performs this function, and returns to the user interface task. In this manner no data is lost or missed.

The user interface tasks allow the user to list or plot raw data, construct hourly, daily, or monthly summaries in the form of tables or graphs, and to halt and maintain the system.

The listing of raw data and the printing or plotting of performance summaries are given low priority with deference to the data acquisition tasks. The DAS halt and maintenance tasks bring the system to an orderly halt so that the hardware can be maintained, disks may be changed, etc.

In summary, the data acquisition system supplied for this project provides a highly flexible, reliable system for data acquisition and processing requirements.

CONSTRUCTION PROBLEMS

V. CONSTRUCTION PROBLEMS ENCOUNTERED

The problems encountered during construction were of two broad class: installation problems and collector hardware problems. The installation problems will be discussed by reviewing the field orders submitted by the contractor. Since the solar collectors are the only prototype equipment on the job, it was expected that this equipment be a significant source of problems. This expectation was indeed realized; therefore, these problems will be discussed separately.

A. Field Order Changes

1. Structural Revisions

This change was necessitated by a number of separate conditions. One conflict arose when the local code authority reviewed the structural calculations and questioned a number of the simplifying assumptions. In addition to this, there were a number of structural members involved in providing load carrying capabilities for the collector supports that were damaged prior to this work that needed to be repaired. While this damage did not effect the integrity of the existing structure, it did prevent the required modifications. Other problems were due to miscellaneous field conflicts with previous modifications and existing hardware. It should be pointed out that since the structural modification does cover approximately a five acre area with 420 support pylons, it was not practical to cover all of the field conflicts in the initial design effort. The last area covered in this field change accounted for a number of locations where the roof support members were displaced from their original location. In summary, this particular field order constituted the largest field order encountered during construction in terms of cost, schedule and effort.

2. Stainless Steel Flashings

Due to the large number (540) of roof penetrations, an effort was made to improve the sealing technique. It was determined during construction that changing the galvanized flashing to stainless steel would provide a higher quality seal.

3. Collector End Piping Modification

The collector manufacturer changed the receiver design between the time the bid package was completed and the equipment delivered. This resulted in a change in piping connection location. All 120 end connections had to be modified to account for this change.

4. Modify Pylon Detail to Attach Existing Cross Braces

This change order consists of increasing the notches in the support tubing to accommodate the existing gusset plates. This modification was required on approximately 200 pylon supports.

5. Relocation of Computer System

The original computer location was designated to be on the second floor adjacent to the system pumps and control panels. A more suitable office area was identified during construction. The change order covered all wiring necessary to account for this change. The original terminal blocks located above the power distribution station on the second floor were to remain and a second set of terminal blocks were added in the first floor office area.

6. Painting Modification

Since the entire second floor truss members will eventually be repainted under a future renovation, it was decided that to keep the painting subcontract within budget after all the structural steel modification in change orders one and four, all finish coats of paint for the structural steel were deleted and all new steel would only be primed.

7. Replace Computer System Transformer

It was determined after a transformer failure, that the 1KVA electrical load of the computer system required a 3KVA transformer due to a condition that occurred when the UPS system was simultaneously providing power to the computer and charging batteries after a power failure.

8. Relocate Electrical Penetrations

The row control panel on the collector drive pylons were relocated from the front of the pylon to the back when it was determined that it was not possible to rotate the mirrors with the panel door open.

The change occurred at the vendor's shop before delivery, but after electrical conduit and roof penetrations for this conduit had been made. This change order covered the relocation of these conduits and penetrations.

9. Wattmeter Modification

This change order was initiated to provide a terminal block and disconnect for the wattmeter wiring so that maintenance could be performed on this meter without the meter being "hot." Since the power wiring is 480 VAC, this change order removed a potential safety problem.

10. Chipped Collector Receiver Glass

A significant number of receiver tubes were received on site and installed when it was determined that minor chips in the glass covers could lead to larger glass breakage problems. This change order covered removal of those receivers previously installed and crating them for return to the vendor. This problem will be outlined in more detail under collector problems.

11. Relocate Flow Switches

The original design called for a horizontally mounted flow switch. After catalog cuts were received from the subcontractor, it was determined that a vertically mounted switch would be better. This change order covered the relocation of the flow switch threadollets to accommodate this change.

12. Modify Alarm Panel Wiring

The alarm panel includes indicators for collector stow position as provided by contacts on existing stow switches. It was determined that the signal from this switch required power and would, therefore, be a source of foreign power in the collector row control box unless it was isolated by a transformer. The change order was initiated to accommodate the rewiring necessary for this modification.

B. Collector Hardware Problems

1. Change in Receiver Tube Design

Due to problems on previous installations the vendor redesigned the collector receiver tube. The new design appears to be far superior to

the previous design. We were not notified by the vendor of this change until after the bid package was sent out to the bidders. This affected the labor for installation as well as a change in piping location for the interface piping.

2. Equipment Delivery

A major problem arose with equipment delivery. The original order was placed with the vendor in October of 1980. The original schedule was to have all equipment on site by mid July 1981. The last of the receivers were not received on site until January 1982; however, 40% of the receivers delivered were chipped and the replacements for these receivers did not arrive until March 1982. This 8-month delay caused numerous problems on site with scheduling various subcontractors that had to install, provide piping and electrical connections to this equipment.

3. Replace Collector Temperature Switches

An estimate was made early in the design process that the setting on the temperature switches would be 250°F. This was conveyed to the vendor at that time. After the design was completed the new setting was identified as 300°F. This information was also conveyed to the vendor and appears on the control drawing mounted on each row control panel. This information, however, was not passed on to the manufacturing staff, so that all the switches supplied to the site were 250°F switches. This problem was identified in February but the replacement switches were not received until June.

4. Segregation of 480V and 120V in Row Control Panel

The vendor-supplied row control panel was inspected by the local code authority and deemed in violation of the electrical code. The source of the violation was the mixing of high voltage power wiring with the low voltage control wiring. A dielectric partition was added and cable insulation was included for the tracker head wiring to resolve the problem and receive approval from the building inspector.

5. Collector Pylon/Mirror Interference

Due to the thermal expansion of the mirrors, bearing assembly mounting plate deflections, and close mounting tolerances, a problem with

the mirror/bearing assembly mounting bolts hitting the support pylon occurred that damaged a number of mirrors and receivers. To solve this problem, collars were designed to prevent the bolts from contacting the pylons. The thermal expansion load would then be transmitted to the pylon through the bearing and result in a deflection of the pylon. This condition was deemed acceptable and no future problem is anticipated.

6. Miscellaneous Drive and Control Problems

There are a number of minor problems with the drive and control systems that have been identified. The results of these problems are hydraulic leaks and lack of dependable operation. All of these can be handled by the maintenance staff, but a long-term solution should be identified and implemented to reduce the maintenance cost. Specific recommendations will be made during operation as more experience is gained with this hardware. Some of the specific components have been replaced; some with identical components and some with higher quality components. The items that should be investigated are: hydraulic accumulators, hydraulic cylinders, by-pass valves and solenoids, pressure switches, four-way valves, mode sector switches, relays, control transformers, and hydraulic filters.

7. Rusty Hose/Receiver Fittings

The fittings that connect the collector flex hose to the receiver were not finished in the factory; therefore, these had to be painted on site.

8. Spot Weld Defects in Receiver Mounting Brackets

A number of receivers fell off of their mounting brackets. These were identified as a quality control problem with a spot welding process. These brackets were replaced.

RECOMMENDATIONS

VI. RECOMMENDED MODIFICATIONS

The problems that arose during construction were resolved as they were identified. A number of recommendations are outlined here to either increase performance or to decrease maintenance.

1. Move Existing Tracker Head from the Mirror Edge to the Receiver

With the tracker head in the current location at the mirror edge, the first thing that is shaded by adjacent mirrors in the afternoon is the tracker head. This deactivates the tracking system. The control light switch still signals adequate light level and so the pump remains on and thermal energy is dumped to the environment. If the tracker head is moved to the center of the mirror over the receiver, one-half of the mirror would have to be shaded before the tracker head is shaded. Since this would only happen early in the morning or late in the afternoon, the intensity would be much smaller and probably below the light threshold of the control light switch. To assure this condition, "blindners" should be added to the control light switch to prevent this condition from occurring. This modification has been implemented on a previous project and has been successful in increasing thermal output of the system.

2. Control Upgrade

In addition to the condition outlined above, an additional problem occurs when clouds or haze exist during system start-up. Since the sensitivity of the different row control electronics and tracker head light switch are not consistent, various collectors will miss the sun under unique cloud cover conditions. This problem can be resolved by implementing (1) a tracker head that operates on focused sunlight, i.e., a flux-line tracker; (2) a high grade row control package; and (3) a high grade central light switch and electronics

3. Upgrade Hydraulic Drives

The hydraulic fluid leak and malfunction problems outlined previously should be reduced or eliminated with a higher quality hydraulic package.

4. Thermal Storage

Due to a combination of reduced load resulting from recently implemented conservation techniques, waste heat from other sources, and idle plant operations on the weekend and holidays, the solar utilization could be increased by implementing a thermal storage system.

COST COMPARISON

VII. CONSTRUCTION COST COMPARISON

<u>ITEM</u>	<u>BID</u>	<u>ACTUAL</u>
Painting	27,248	27,608
Structural	282,446	379,186
Electrical	145,618	157,528
Mechanical	344,800	350,314
Sheet Metal	48,420	56,179
Roofing	42,950	47,495
General Contractor	310,972	176,226
SUBTOTAL	1,202,454	1,194,536
Collectors	1,242,535	1,246,144
SUBTOTAL	2,444,989	2,440,680
DAS	200,000	200,000
Management	187,000	187,000
TOTAL	2,831,989	2,827,680

PERFORMANCE

VIII. ASSESSMENT OF PERFORMANCE

Since the official acceptance test and checkout was not available at the time of publication, preliminary data will be presented to assess system performance. Instantaneous data for both the north field and south field were taken. The total radiation on the horizontal, flow rates and temperature differences were measured. These data were then used to compute the thermal efficiency of each field. The radiation level was not at a peak condition but at a normal operation level. The collector fine tuning had not yet been conducted and the collectors had not been washed since installation was complete. The following data are, therefore, typical of normal every day operation and not ideal or peak operation.

<u>Radiation</u>	<u>Area</u>	<u>Efficiency</u>	<u>Field</u>
219 BTU/hr ft ²	13,440 ft ²	33.0%	North
214 BTU/hr ft ²	36,960 ft ²	32.9%	South

AS-BUILT DRAWINGS

AS-BUILT DRAWINGS

IX. AS-BUILT DRAWINGS

CATERPILLAR TRACTOR CO. SOLAR PROCESS HEAT SYSTEM SAN LEANDRO, CALIFORNIA

COLLECTOR DRAWINGS

H-200 Collector Layout
H-201 Collector Row
H-202 Support Pylons
H-203 Mirror Module
H-204 Receiver Tube Assembly

MECHANICAL DRAWINGS

H-220 Collector Piping Schematic
H-221 Second Floor Piping Plan
H-222 Second Floor Piping Sections
H-223 First Floor Piping
H-224 Collector Piping - Roof
H-225 Solar HHW Pumps
H-226 Pump Outlet Piping
H-227 Piping Support Details
H-228 Cold Water Piping

ELECTRICAL DRAWINGS

E-240 Single Line, Block Diagram Legend & Abbreviations
E-241 Power Distribution Floor Plan
E-242 Elementary Diagram Description of Operation
E-243 Building Sections
E-244 Miscellaneous Details Plan & Elementary

STRUCTURAL DRAWINGS

S-280 Roof Truss Structural Reinforcement Plan (South Field)
S-281 Roof Truss Structural Reinforcement Plan (North Field)
S-282 Truss Reinforcement Details
S-283 Structural Details
S-284 Structural Details
S-285 Platform and Walkway Details

CONTROL AND INSTRUMENTATION DRAWINGS

CI-261 Control Floor Plan
CI-262 Sensor Element Location
CI-263 Enclosures Details
CI-267 Specifications List
CI-270 Piping and Instrumentation Diagram
CI-271 Solar Weather Station
CI-275 Sensor Connections Overview
CI-276 Power to Motor Controls

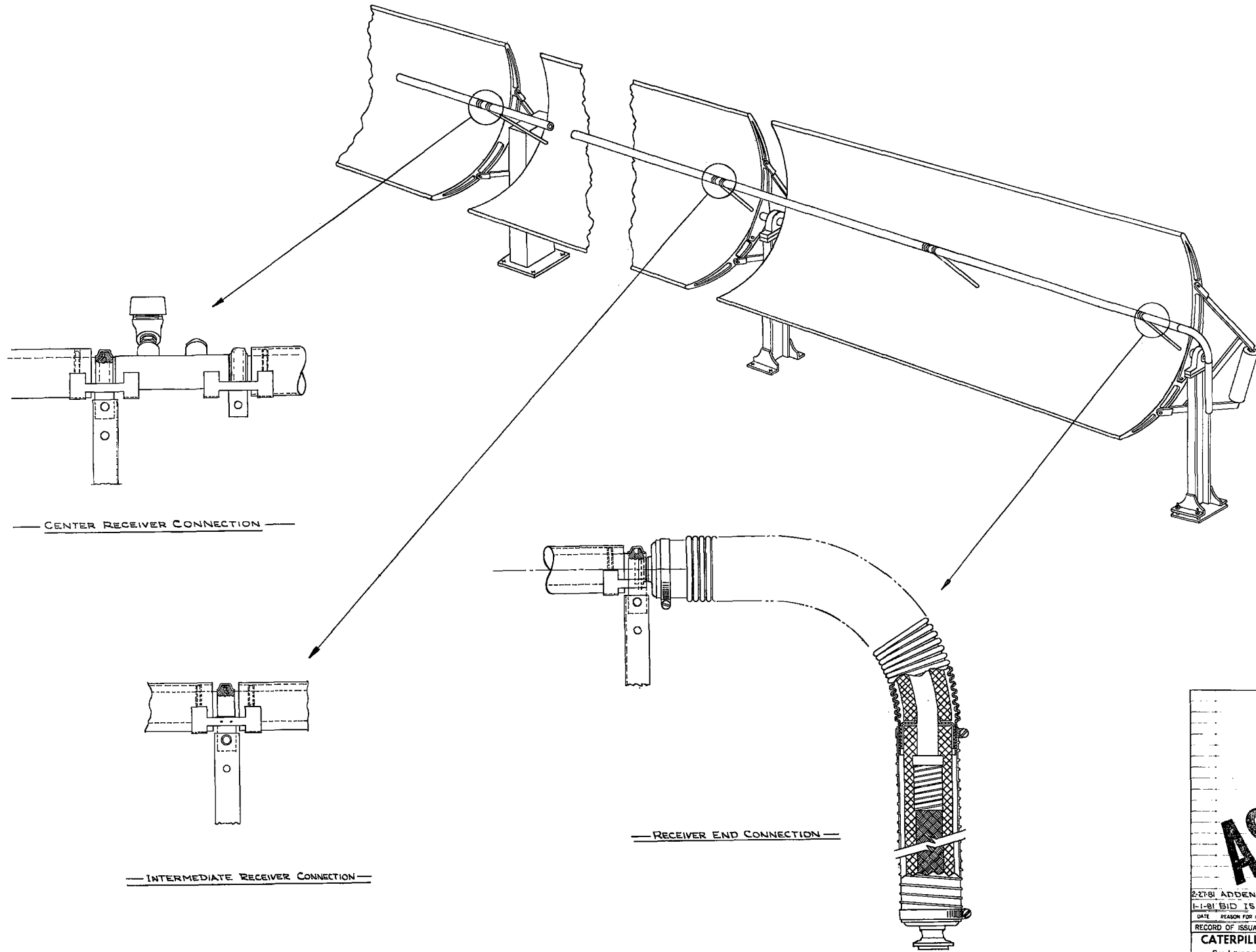
AS-BUILT

H-B BLD IT FOR

SAN LEANDRO SAN LEANDRO CA.
SOLAR IPH SYSTEM
B-B TITLE SHEET

 SOUTHWEST RESEARCH INSTITUTE
3650 CAMINO REAL
SAN ANTONIO, TEXAS 78241

EZ 7/80 T-100
7/80 02-5821



— CENTER RECEIVER CONNECTION —

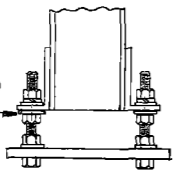
— INTERMEDIATE RECEIVER CONNECTION —

— RECEIVER END CONNECTION —

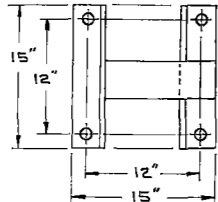
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 DATE REASON FOR ISSUE
 RECORD OF ISSUANCES
 CATERPILLAR TRACTOR CO.
 PLANT SAN LEANDRO SAN LEANDRO, CALIF.
 PROJECT SOLAR I.P.H. SYSTEM
 B-B COLLECTOR ROW
 FIELD RELEASE DATE D&C FILE NO. SC LOG NO.
 APPROVED DATE
 SOUTHWEST RESEARCH INSTITUTE
 4100 UNIVERSITY AVENUE
 PASADENA, CALIF. 91107
 SAN ANTONIO, TEXAS 78241
 DRAWN DATE 1-1-81
 CHECKED DATE 3-8-81 NOT TO SCALE
 APPROVED DATE 02-5821 H201
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SEE STRUCTURAL DWG. NO. S-233

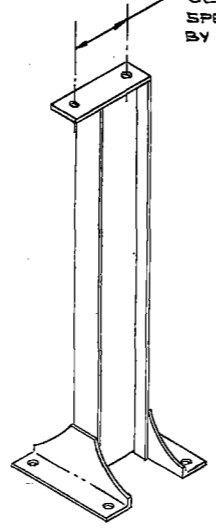


PYLON CONNECTION DETAIL



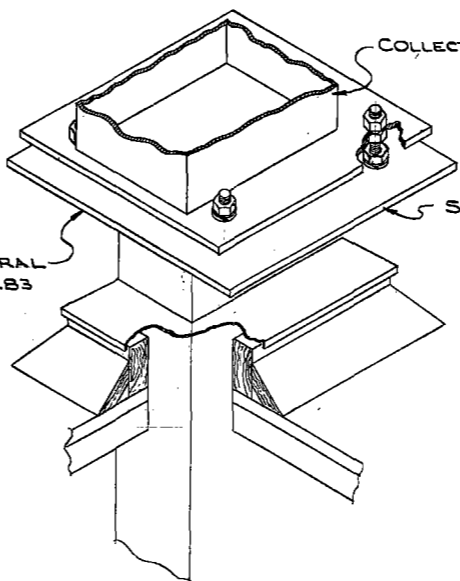
PYLON BASE DIMENSIONS FOR ALL INTERMEDIATE AND END PYLONS

CENTERLINE LOCATED WITH SPECIAL TARGETS FURNISHED BY THE COLLECTOR MANUFACTURER



SUPPORT PYLON FURNISHED BY COLLECTOR MANUFACTURER

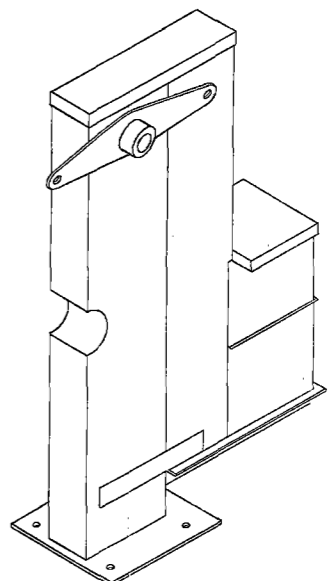
SEE STRUCTURAL DWG. NO. S283



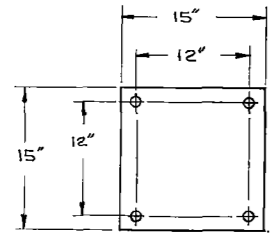
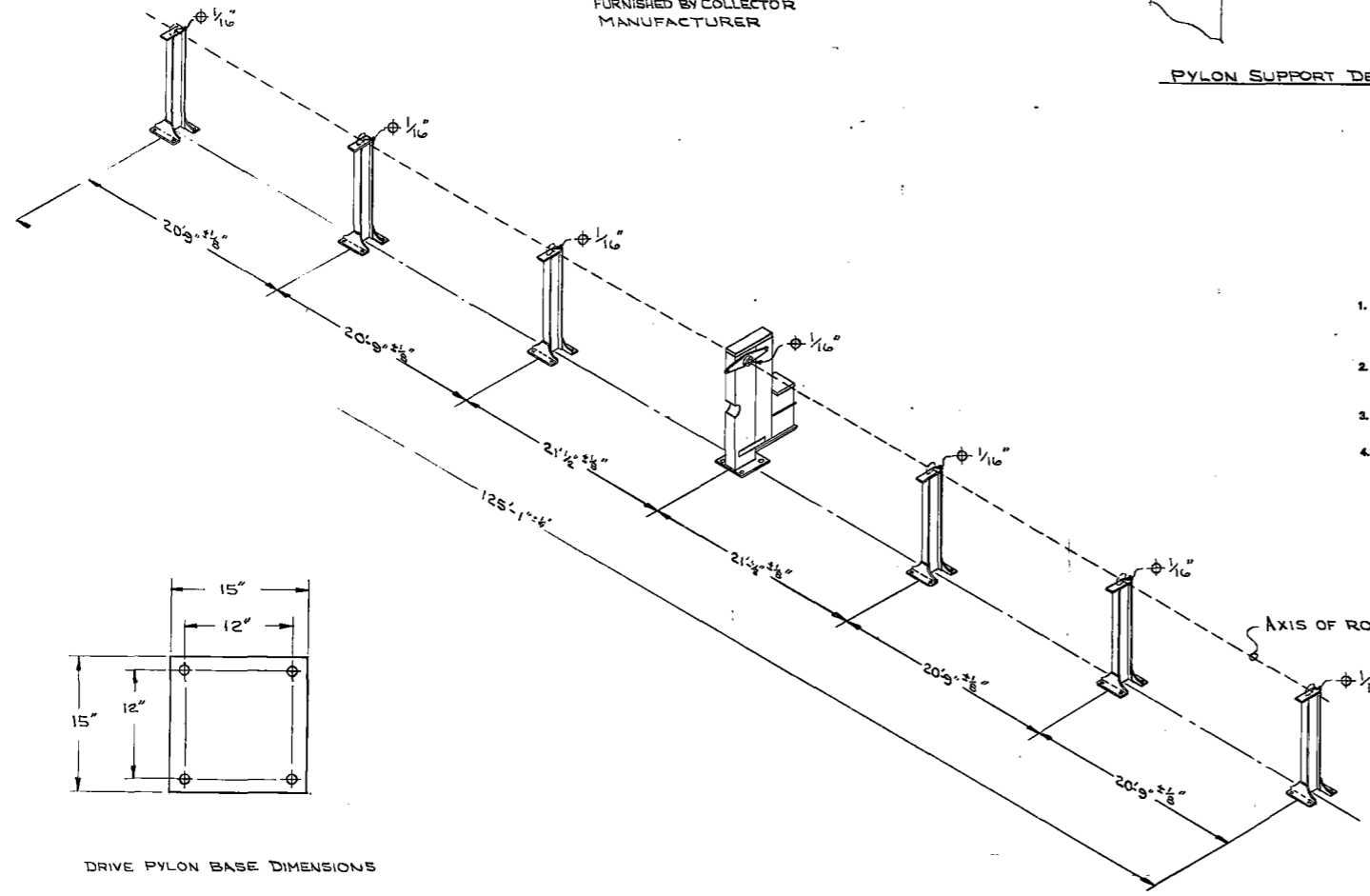
PYLON SUPPORT DETAIL

COLLECTOR PYLON BASE

SUPPORT PLATE



DRIVE PYLON FURNISHED BY COLLECTOR MANUFACTURER



DRIVE PYLON BASE DIMENSIONS

INSTALLATION AND ALIGNMENT OF SUPPORT AND DRIVE PYLONS

1. ROOF TOP MOUNTING PLATES SHALL BE PREPARED TO ACCEPT THE PYLON BOLT PATTERN AND SPACING PER STRUCTURAL DRAWINGS. THE DOUBLE NUT TECHNIQUE IS USED TO FASTEN THE BOTTOM OF THE PYLONS AND ALLOW FOR ADJUSTMENT AND ALIGNMENT.
2. PYLONS SHALL BE INSTALLED AND ALIGNED WITH A LASER TRANSIT. CARE SHOULD BE TAKEN TO OBTAIN A TRUE LINE OF SIGHT THROUGH THE CENTER OF THE AXIS OF ROTATION TO WITHIN $\pm 1/16"$.
3. DRIVE PYLONS SHALL BE IN THE STOW POSITION AND FILLED WITH HYDRAULIC FLUID TO PREVENT ROTATION.
4. MIRROR MODULES CANNOT BE INSTALLED UNTIL PYLONS ARE ALIGNED AND TIGHTENED TO THE SUPPORT PLATES AS INDICATED ABOVE.

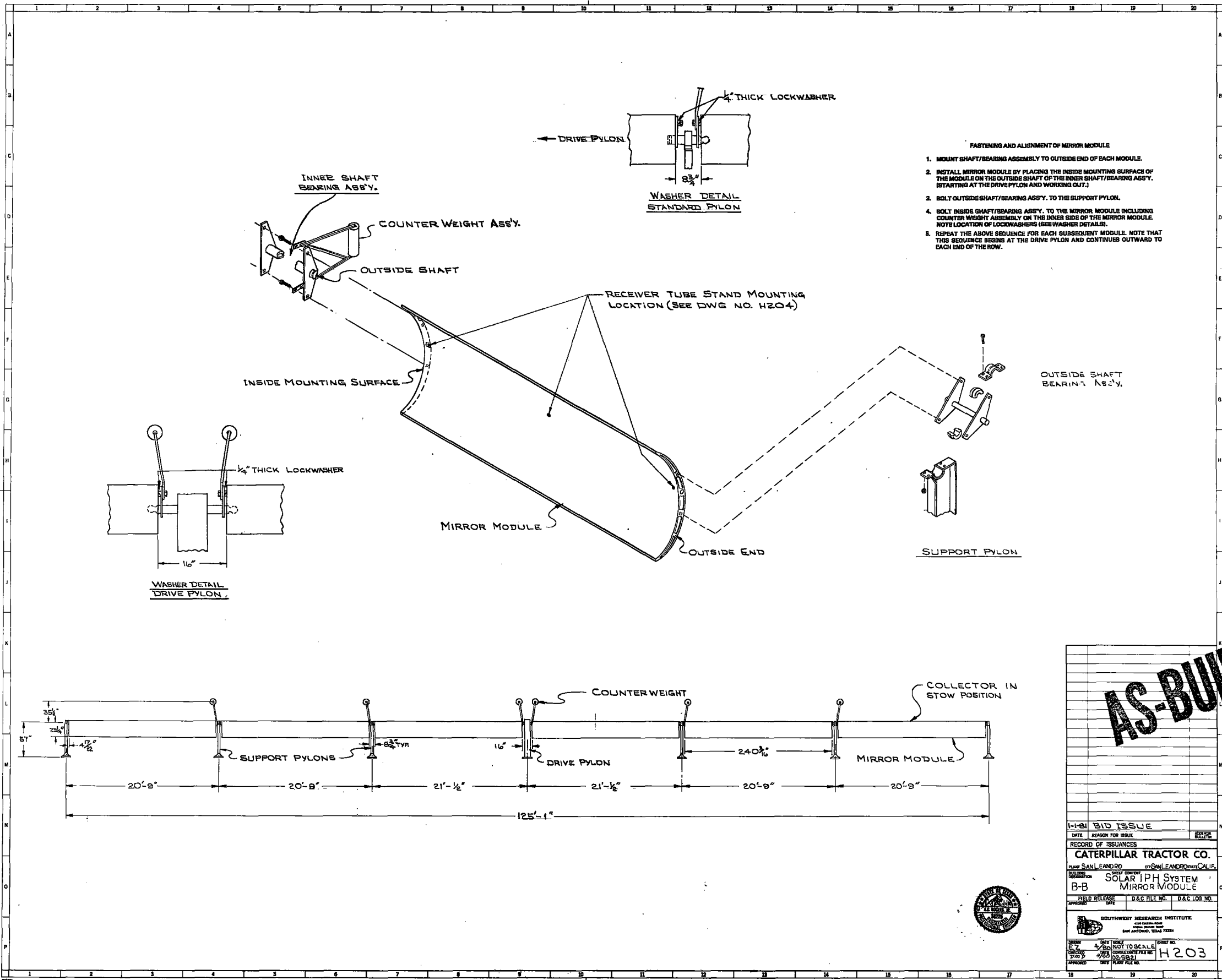
AXIS OF ROTATION

ALL CENTERLINES OF EACH PYLON MUST BE ALIGNED TO WITHIN $\pm 1/16"$ IN BOTH THE VERTICAL AND HORIZONTAL DIRECTIONS TO THE CENTERLINE OF THE DRIVE PYLON.

AS-BUILT



1-181 BID ISSUE			
DATE	REASON FOR ISSUE	APPROVED	REVISION
RECORD OF ISSUANCES			
CATERPILLAR TRACTOR CO.			
PLANT	SAN LEANDRO	CITY	SAN LEANDRO STATE CALIF.
PROJECT	SOLAR IPH SYSTEM		
DESCRIPTION	SUPPORT PYLONS		
FIELD RELEASE	DATE	D&C FILE NO.	D&C LOG NO.
APPROVED	SOUTHWEST RESEARCH INSTITUTE		
400 SOUTH MAIN SAN ANTONIO, TEXAS 78224			
DATE	SCALE	SHEET NO.	
12/2	1/8" = 1'-0"	H202	
DESIGNED	BY	DATE	FILE NO.
DMP	12/2	12/2	02-5521
APPROVED	DATE	FILE NO.	



- FASTENING AND ALIGNMENT OF MIRROR MODULE**
1. MOUNT SHAFT/BEARING ASSEMBLY TO OUTSIDE END OF EACH MODULE.
 2. INSTALL MIRROR MODULE BY PLACING THE INSIDE MOUNTING SURFACE OF THE MODULE ON THE OUTSIDE SHAFT OF THE INNER SHAFT/BEARING ASS'Y. (STARTING AT THE DRIVE PYLON AND WORKING OUT.)
 3. BOLT OUTSIDE SHAFT/BEARING ASS'Y. TO THE SUPPORT PYLON.
 4. BOLT INSIDE SHAFT/BEARING ASS'Y. TO THE MIRROR MODULE INCLUDING COUNTER WEIGHT ASSEMBLY ON THE INNER SIDE OF THE MIRROR MODULE. NOTE LOCATION OF LOCKWASHERS (SEE WASHER DETAILS).
 5. REPEAT THE ABOVE SEQUENCE FOR EACH SUBSEQUENT MODULE. NOTE THAT THIS SEQUENCE BEGINS AT THE DRIVE PYLON AND CONTINUES OUTWARD TO EACH END OF THE ROW.

AS-BUILT

1-181 BID ISSUE

DATE: REASON FOR ISSUE: REVISION: BUILDING:

RECORD OF ISSUANCES

CATERPILLAR TRACTOR CO.

PLANT SAN LEANDRO, CALIF.

PROJECT: SOLAR I-PH SYSTEM

B-B MIRROR MODULE

FIELD RELEASE DATE: D&C FILE NO.: D&C LOG NO.:

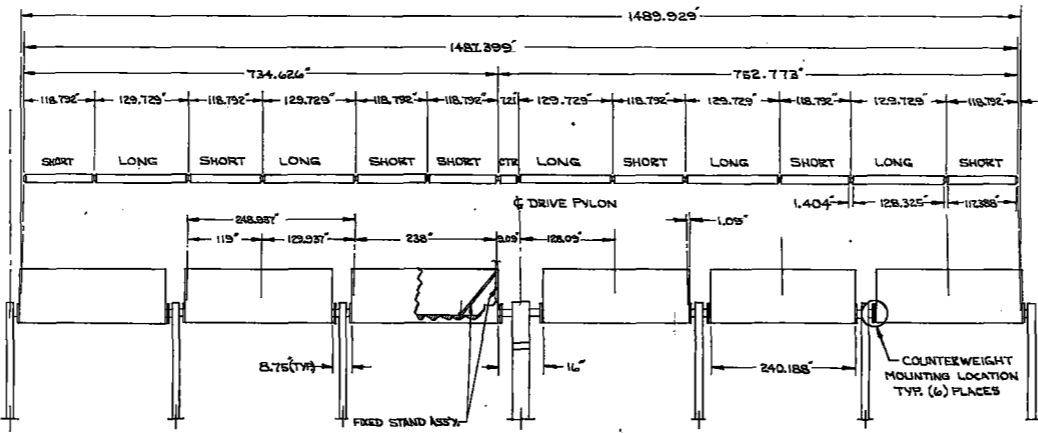
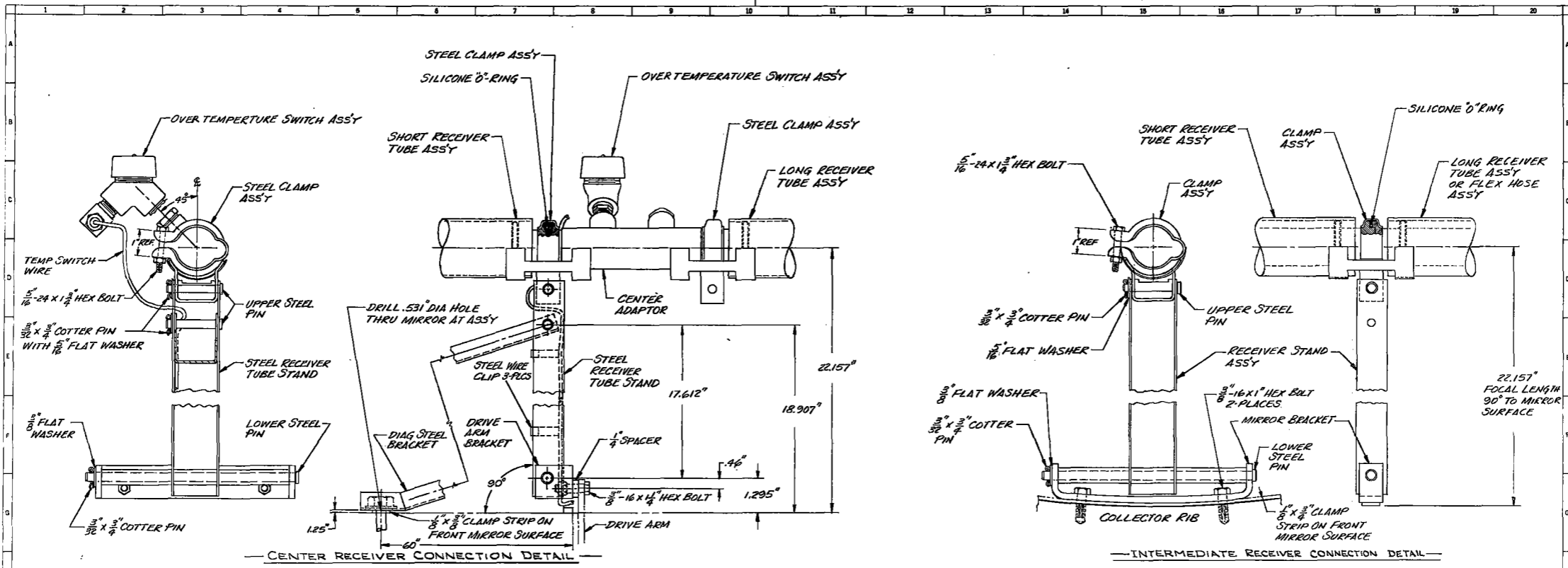
APPROVED: SOUTHWEST RESEARCH INSTITUTE

DATE: 1/27/77

NOT TO SCALE

COMPLETION FILE NO. H203



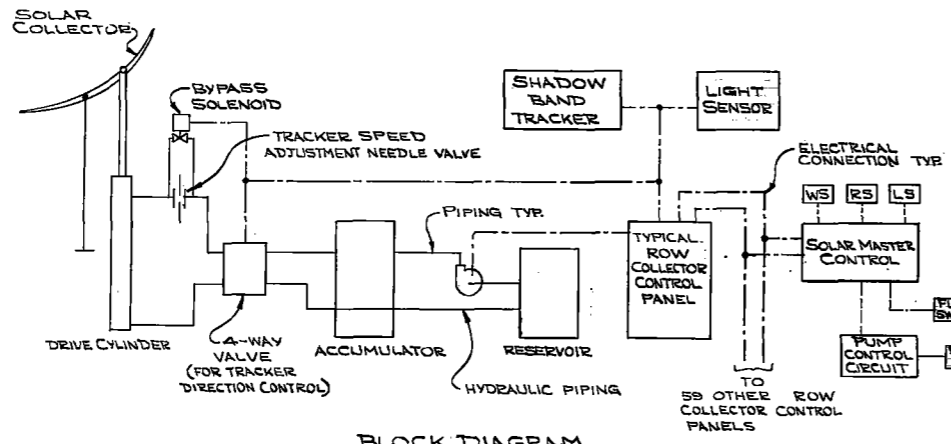


RECEIVER INSTALLATION

- The T-700 modular receiver stand features a swing arm design to allow for thermal expansion. Each mirror module requires two stands with the exception of the center (left) mirror, which requires three and a brace. One stand is mounted at the center of each mirror with two 3/8" bolts passing through the mounting brackets. The stand must be mounted to the curved bracket with the long clevis pin before bolting to the mirror. See Intermediate Receiver Connection Detail. The receiver tube stand is channel shaped and the flanges should always point away from the drive pylon. Each side of the row is the mirror image of the other.
The second stand is mounted at the end of the collector, away from the drive pylon. The bracket at this location is flat and is bolted to the drive arm with the flange pointed inside the mirror. At this point, the angle brace at the main center module should be mounted to locate the center stand, per Center Receiver Connection Detail. This fixed stand assembly is the location for the receiver and thermal expansion is from this point in both directions. A 1/2" hole should be drilled through the mirror in order to locate the lower point of the brace. Make certain that the receiver stand is perpendicular to the mirror when this hole is drilled.
- The receiver flange clamp is now mounted to the top of each receiver tube stand with the short clevis pin and cotter pin. The opening of the clamp should be pointed up to hold each end of the receiver during installation. The clamp uses one 1/4" bolt and nut and must be forced open to accept the flange.
- The entire receiver assembly is made up of five long and seven short receivers and a center adaptor section. The center adaptor makes up the difference in mirror gap at the drive pylon and contains the overtemperature switch. Both ends of the center adaptor are made with the female half of the "V" flange and the receivers have a male on one end and a female on the other end. In this way both ends of the receiver assembly terminate in a female flange with the top hose flange being male.
- The "V" flanges are sealed with an "O" ring. Before placing the seal in the flange, support both sealing surfaces well to insure that no nicks, burrs or scratches are present.
Assembly must begin at the center, fixed location receiver stand, installing the two short receivers on that center left module with the male ends pointed to the drive pylon. A seal should be installed at the center point of the mirror where the two receivers meet and the other ends of each receiver should rest in the "V" clamp which has been opened for that purpose. Care should be taken to not allow either end to fall out of the clamp since damage will occur to the receiver assembly.
Next, the center receiver adaptor should be installed with the temperature switch already mounted to avoid any unnecessary loads due to tightening. The seal is placed between the male end of the center short receiver and one female end of the center adaptor and the clamp at the center tightened. The temperature switch should be located as in the center receiver connection detail in order to avoid fouling of the drive pylon at the stow position. The balance of the receivers are installed in the same way from the center out to the ends so that each end of the row is the mirror image with the exception of the one odd short receiver at the center.
The thermal, insulated flex hoses should be installed next. The top part of the assembly is forward to a 90 degree bend and the hose is not flexible in this area. The male fitting on the end of the hose mates to the female end of the receiver at each end of the row. Tighten the clamp with the 90 degree bend aligned with the receiver stand as shown on Drawing M201.
The lower connection of the hose should be made next. A torsional load must not be placed on the hose at any time and care should be taken to align the hose properly. Align the hose with hose installed. Rotate the collector with the receiver counter to insure that the hose is not fouled or bound at any position. Do not pressure with the collector near focus as overheating and damage to the receiver will occur.
The receiver and hose connections should now be checked for leaks. If pressure is applied to the receiver and hose assembly, the hose should be inspected at both ends or a sudden pressure will straighten out the hose. A hydrostatic pressure test up to 250 psi is recommended and, if water is used, a corrosion inhibitor is required.

AS-BUILT

E27-81 ADDENDUM #1
 1-181 BID ISSUE
 DATE REASON FOR ISSUE
 RECORD OF ISSUANCES
CATERPILLAR TRACTOR CO.
 PLANT SAN LEANDRO SAN LEANDRO, CALIF.
 BUILDING REGISTRATION SHEET NO. 1
SOLAR TPH SYSTEM
B-B RECEIVER TUBE ASSEMBLY
 FIELD RELEASE DATE FILE NO. D&C LOG NO.
 APPROVED DATE
 BOUTINWORTH RESEARCH INSTITUTE
 400 CAPITAL ROAD
 FORT WORTH, TEXAS 76102
 SHEET NO. 1 OF 1
 DATE 3-81
 SCALE NOT TO SCALE
 DRAWN 4/77
 CHECKED 6/77
 APPROVED 8/77
 SHEET NO. H-204



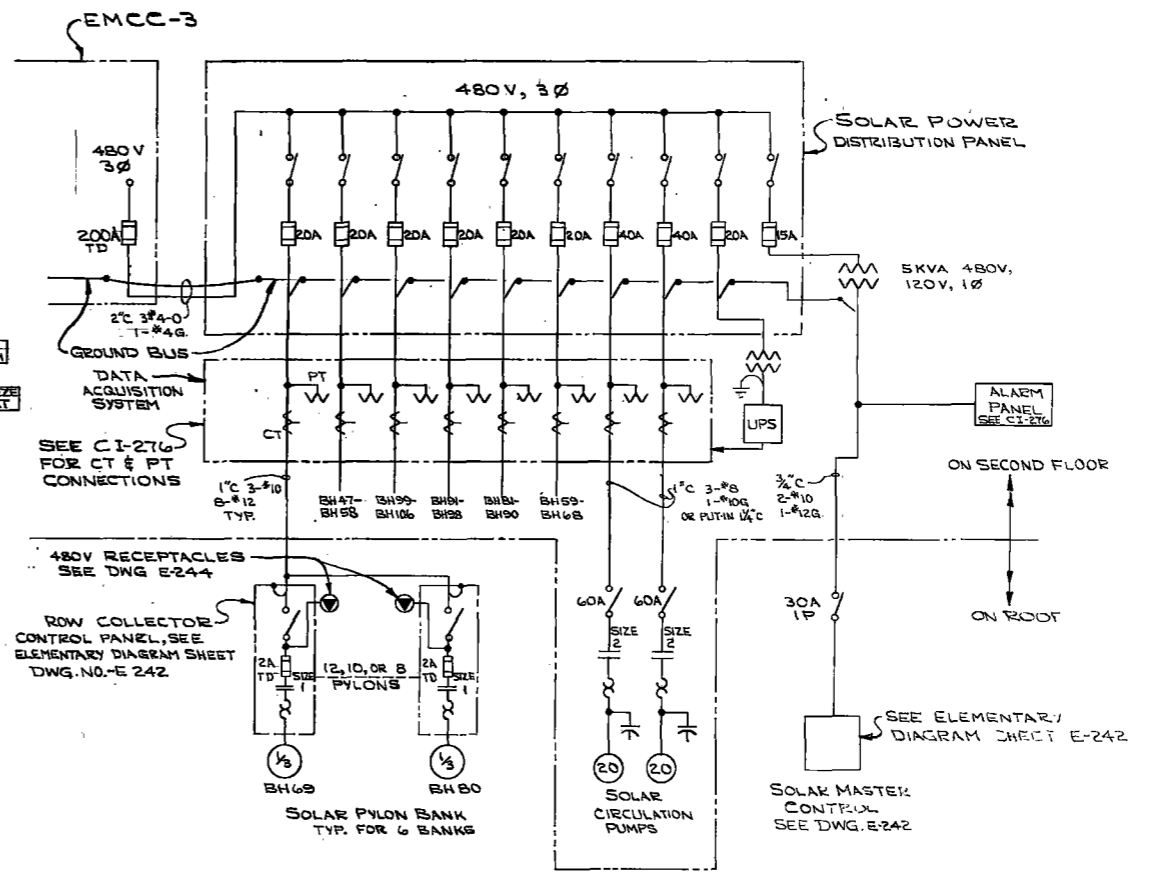
BLOCK DIAGRAM
TYPICAL COLLECTOR CONTROL OPERATION
NO SCALE

COLLECTOR CONTROL OPERATION

1. WHEN SUFFICIENT LIGHT IS AVAILABLE, SOLAR MASTER CONTROL TELLS THE ROW COLLECTOR CONTROL PANEL TO UNSTOW AND COMMENCE TRACKING THE SUN.
2. BYPASS SOLENOID OPERATES TO PROVIDE RAPID MOVEMENT INTO TRACKING POSITION.
3. SHADOW BAND TRACKER TRACKS SUN FOR MAXIMUM INPUT RADIATION.
4. SOLAR MASTER CONTROL OVERRIDES ALL SIGNALS IN EVENT OF RAIN, WIND, HIGH WATER TEMPERATURE AND STOWS ALL COLLECTORS

ABBREVIATIONS FOR E & CI DWGS.

- FE - FLOW ELEMENT
- TE - TEMPERATURE ELEMENT
- PE - PRESSURE ELEMENT
- WV - WIND VELOCITY
- RF - RAIN FALL
- RH - RELATIVE HUMIDITY
- WD - WIND DIRECTION
- FS - FLOW SWITCH
- AVV - AIR VENT VALVE
- PRV - PRESSURE RELIEF VALVE
- ISV - ISOLATION VALVE
- TRV - TEMPERATURE REGULATED VALVE
- CSV - CIRCUIT SETTER VALVE WITH FLOW INDICATOR
- DRV - DRAIN VALVE
- LS - LIGHT SWITCH
- RS - RAIN SWITCH
- WS - WIND SWITCH
- TS - TEMPERATURE SWITCH
- FS - FLOW SWITCH
- PS - PRESSURE SWITCH
- ⊕ - THERMOMETER
- ⊙ - PRESSURE GAGE
- ⊖ - VENTURI FLOWMETER / PRESSURE GAGE
- ⊙ - TEMPERATURE TAP
- IPS - INSTRUMENTATED PIPE SECTION
- EP - ELECTRICAL POWER (WATTMETER)
- SET - SENSOR ELEMENT TERMINATION
- PB - PULL BOX
- RDC - REMOTE DATA COLLECTION
- HHWR - HEATING HOT WATER RETURN
- ID - INNER DIAMETER
- RCC - ROW COLLECTOR CONTROL
- SPD - SOLAR POWER DISTRIBUTION
- CT - CURRENT TRANSFORMER
- PT - POTENTIAL TRANSFORMER
- UPS - UNINTERRUPTIBLE POWER SUPPLY
- SMC - SOLAR MASTER CONTROL
- BCG - BARE COPPER GROUND



SINGLE LINE OF SOLAR POWER DISTRIBUTION
NO SCALE

SINGLE LINE LEGEND

- ⊗ - SWITCH, 3 POLE UNLESS NOTED
- ⊞ - FUSE, SIZE AS NOTED
- ⊙ - MOTOR, HORSE POWER AS NOTED
- ⊞ - MAGNETIC STARTER
- ⊞ - MISCELLANEOUS DEVICE AS NOTED
- ⊞ - POWER FACTOR CAPACITOR
- ⊞ - CURRENT TRANSFORMER
- ⊞ - POTENTIAL TRANSFORMER
- ⊙ - SPECIAL RECEPTACLE AS NOTED
- ⊞ - GROUND WIRE CONNECTION TO CIRCUIT

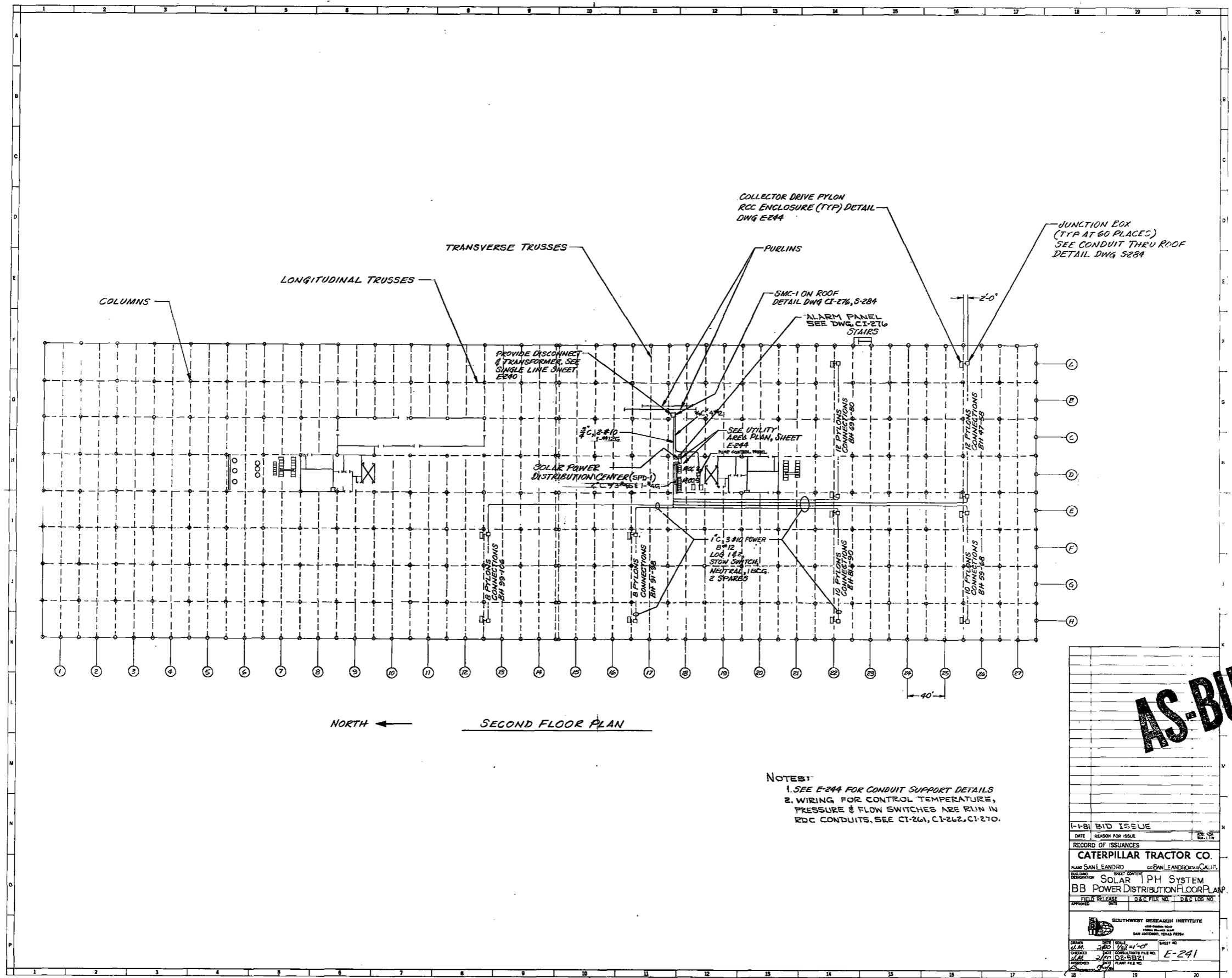
PLANS LEGEND

- EXPOSED CONDUIT
- ⊞ - FLEX CONDUIT CONNECTION
- ⊞ - JUNCTION BOX, TYPE FS OR FD
- ⊞ - COMBINATION STARTER
- ⊞ - MISCELLANEOUS DEVICE AS NOTED

AS-BUILT

1-18' BID ISSUE
CATERPILLAR MOTOR CO.
SAN LEANDRO SAN LEANDRO CA.
SOLAR IPH SYSTEM
B-B SINGLE LINE BLOCK DIAGRAM
LEGEND AND ABBREVIATIONS

SOUTHWEST RESEARCH INSTITUTE
4800 Canyon Blvd
SAN ANTONIO, TEXAS 78244
E.Z. 11-22-80
A.H. 12-80
E-240

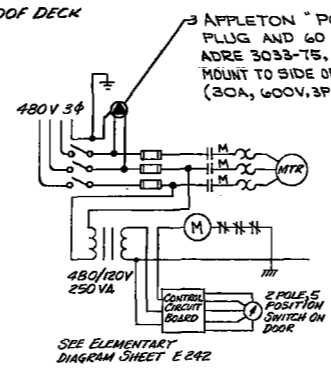
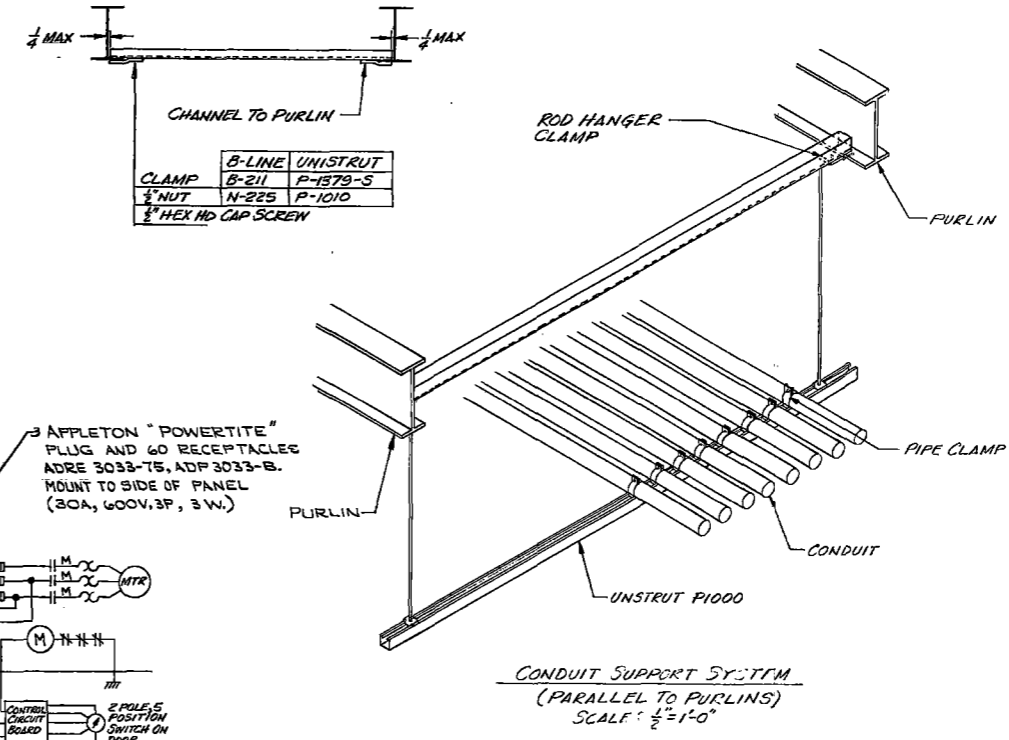
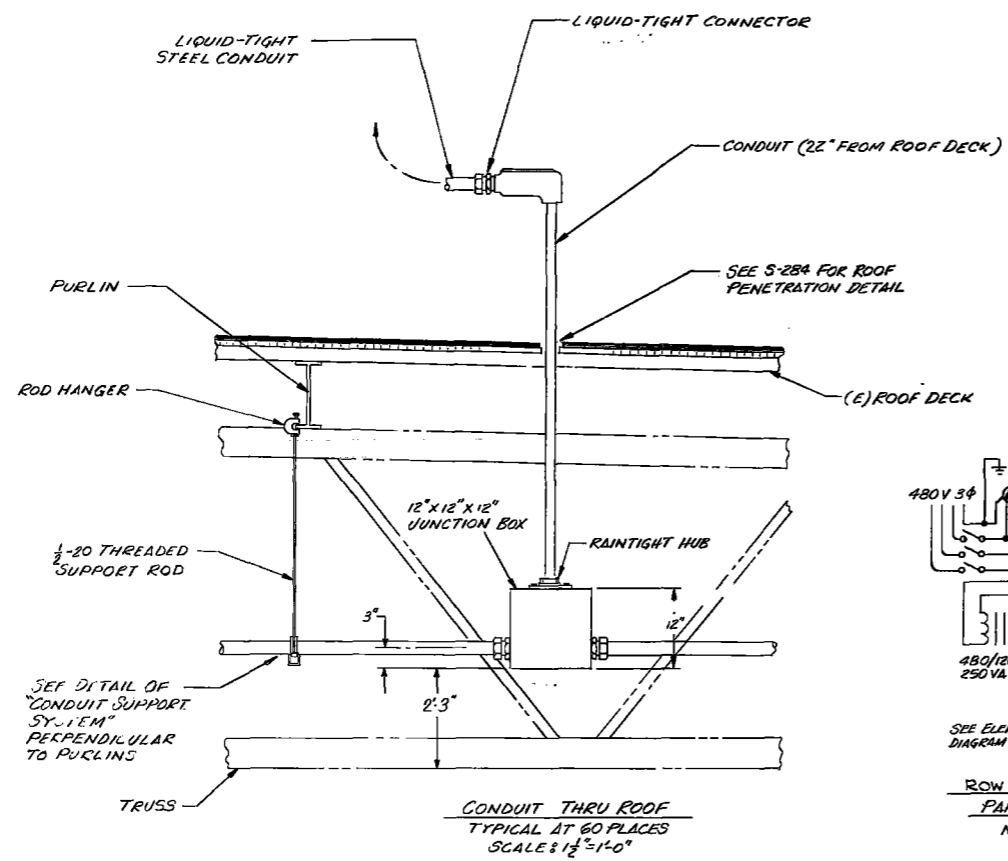


NORTH ← SECOND FLOOR PLAN

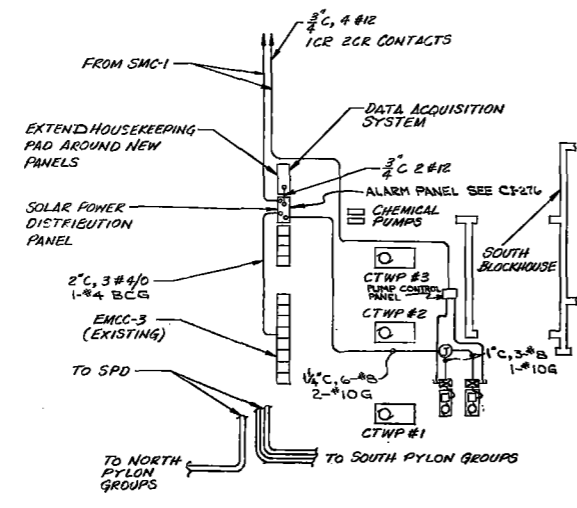
- NOTES:
1. SEE E-244 FOR CONDUIT SUPPORT DETAILS
 2. WIRING FOR CONTROL TEMPERATURE, PRESSURE & FLOW SWITCHES ARE RUN IN RDC CONDUITS. SEE CI-261, CI-262, CI-270.

AS-BUILT

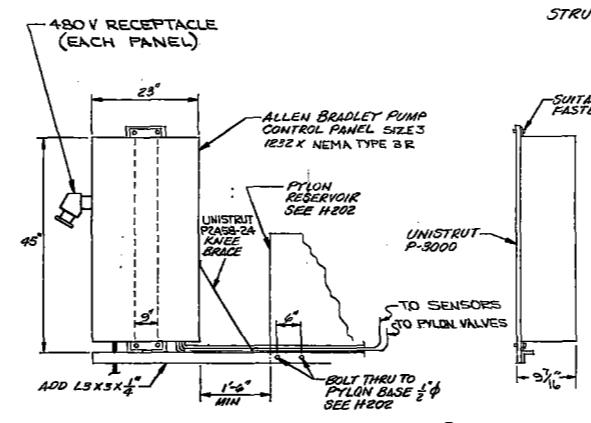
1-1-B BID ISSUE			
DATE	REASON FOR ISSUE	BY	CHKD BY
RECORD OF ISSUANCES			
CATERPILLAR TRACTOR CO.			
PLANT	SAN LEANDRO	ENGINEER	LEONARD CALIF.
DESCRIPTION	SOLAR 1 PH SYSTEM BB POWER DISTRIBUTION FLOOR PLAN		
FIELD RELEASE DATE	D&C FILE NO.	D&C LOG NO.	
APPROVED			
SOUTHWEST RESEARCH INSTITUTE 4000 RIVER ROAD SAN ANTONIO, TEXAS 78244			
DRAWN	DATE	SCALE	SHEET NO.
J.M.	3/80	1/8" = 1'-0"	E-241
CHECKED	DATE	CONDUIT DATE FILE NO.	
J.M.	2/80	02-5821	
REVISIONS	DATE	BY	REASON



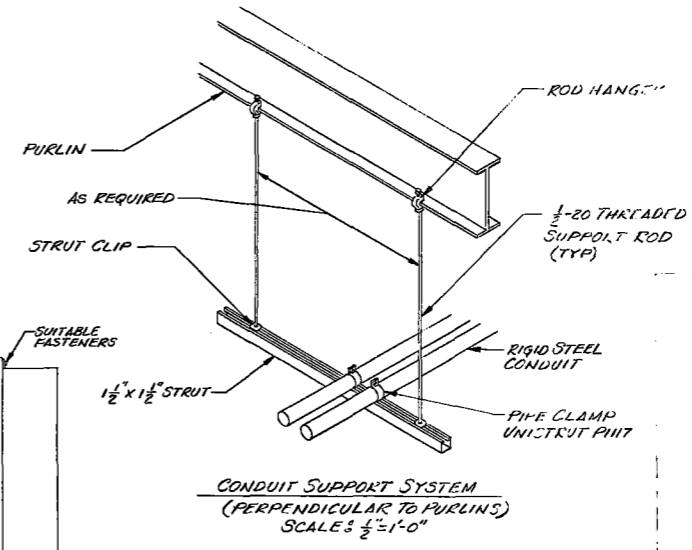
ROW COLLECTOR CONTROL PANEL WIRING
NO SCALE



UTILITY AREA PLAN
SCALE: 1/8\"/>



ROW COLLECTOR CONTROL PANEL SUPPORT
NO SCALE

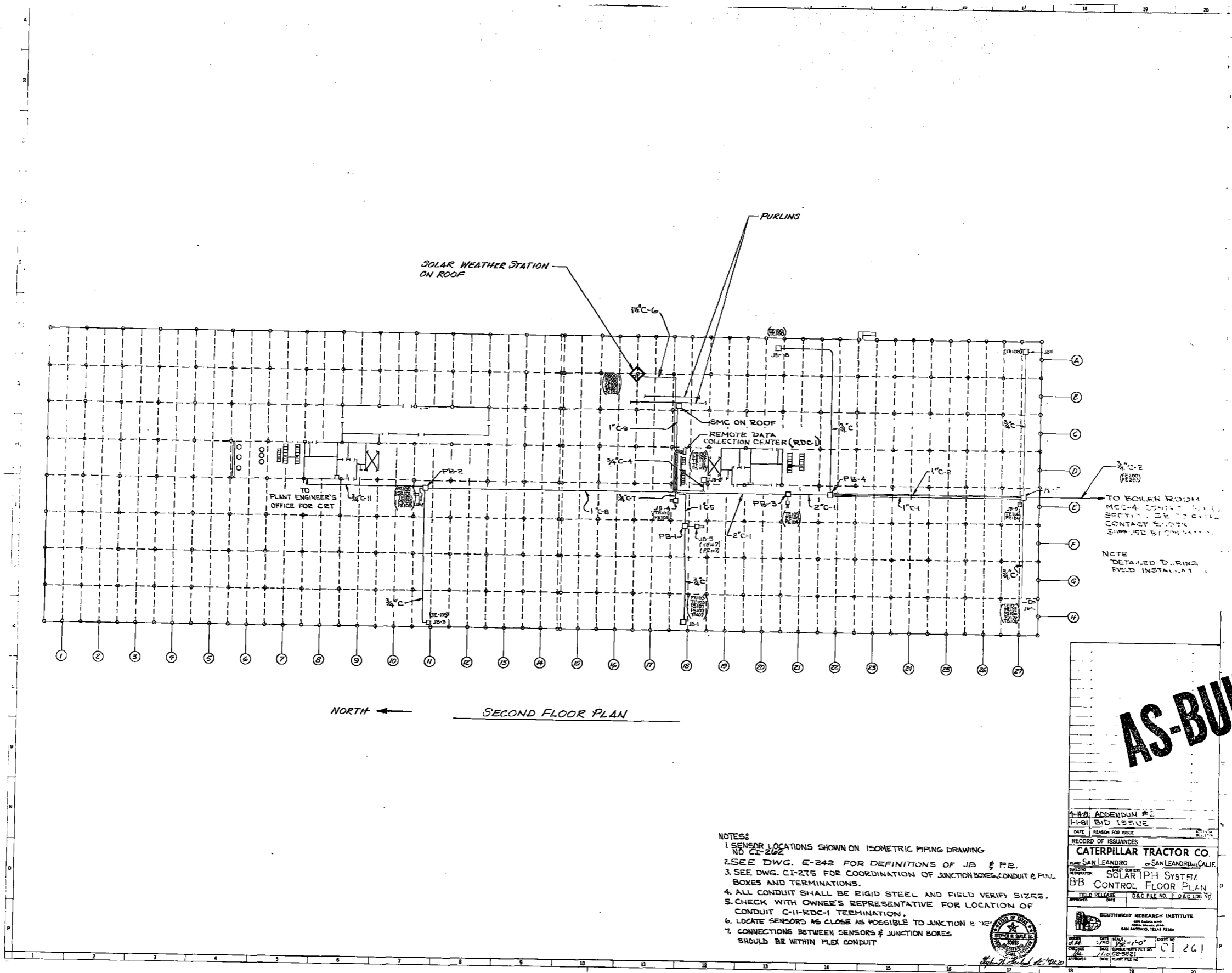


CONDUIT SUPPORT SYSTEM (PERPENDICULAR TO PURLINS)
SCALE: 1/2\"/>

NOTE: PROVIDE THIS INSTALLATION 60 PLACES

AS-BUILT

1-181 BID ISSUE
CATERPILLAR TRACTOR
SAN LEANDRO SAN LEANDRO CALIF.
SOLAR IPH SYSTEM
MISCELLANEOUS DETAILS
PLAN, ELEMENTARY
SOUTHWEST RESEARCH INSTITUTE
4400 GARDEN ROAD
SAN ANTONIO, TEXAS 78229
P.G. 3/10 NOTED E 244
J.L.M. 3/10 02-5521



NORTH ← SECOND FLOOR PLAN

TO BOILER ROOM
MCC-A CONTACT BLOCK
SECTION DE TO BE
CONTACT BLOCK
SUPPLIED BY OWNER

NOTE
DETAILED DURING
FIELD INSTALLATION

- NOTES
1. SENSOR LOCATIONS SHOWN ON ISOMETRIC PIPING DRAWING NO CI-202
 2. SEE DWG. E-242 FOR DEFINITIONS OF JB & PE.
 3. SEE DWG. CI-275 FOR COORDINATION OF JUNCTION BOXES, CONDUIT & PULL BOXES AND TERMINATIONS.
 4. ALL CONDUIT SHALL BE RIGID STEEL AND FIELD VERIFY SIZES.
 5. CHECK WITH OWNER'S REPRESENTATIVE FOR LOCATION OF CONDUIT C-II-RDC-1 TERMINATION.
 6. LOCATE SENSORS AS CLOSE AS POSSIBLE TO JUNCTION BOXES.
 7. CONNECTIONS BETWEEN SENSORS & JUNCTION BOXES SHOULD BE WITHIN FLEX CONDUIT



AS-BUILT

4-88 ADDENDUM #2	
I-BI BID ISSUE	
DATE	REASON FOR ISSUE
RECORD OF ISSUANCES	
CATERPILLAR TRACTOR CO.	
PROJECT LOCATION	PLANT SAN LEANDRO, SAN LEANDRO, CALIF.
DESCRIPTION	SOLAR IPH SYSTEM
BB CONTROL FLOOR PLAN	
FIELD RELEASE DATE	D&C FILE NO. D&C LOG NO.
SOUTHWEST RESEARCH INSTITUTE	
4000 GARDEN AVENUE SAN ANTONIO, TEXAS 78244	
DATE	SCALE
11/10/80	1/4" = 1'-0"
DATE	ISSUED
11/10/80	11/10/80
DATE	PLANT FILE NO.
11/10/80	CI 261

LENGTH	MANUFACTURE * AND MODEL *	RDC TERMINAL BLOCK	CONDUIT	TRANSDUCER / FUNCTION	DESCRIPTION
430'	BELDON 8760	TB-3	C-1	FE-100-DP	SOLAR COLLECTOR FIELD "A" INLET FLOW
430'	8760	TB-3	C-1	TE-100-R	SOLAR COLLECTOR FIELD "A" INLET TEMPERATURE
570'	8760	TB-3	C-2	FE-102-DP	SOLAR COLLECTOR FIELD "A" OUTLET FLOW
570'	8760	TB-3	C-2	TE-102-R	SOLAR COLLECTOR FIELD "A" OUTLET TEMPERATURE
190'	8760	TB-3	C-1	FE-104-DP	SINGLE COLLECTOR ROW FIELD "A" FLOW
190'	8760	TB-3	C-1	TE-104-R	SINGLE COLLECTOR ROW FIELD "A" INLET TEMPERATURE
190'	8760	TB-3	C-1	FE-104-SG	SINGLE COLLECTOR ROW FIELD "A" INLET PRESSURE
450'	8760	TB-3	C-1	TE-106-R	SINGLE COLLECTOR ROW FIELD "A" OUTLET TEMPERATURE
450'	8760	TB-3	C-1	FE-106-SG	SINGLE COLLECTOR ROW FIELD "A" OUTLET PRESSURE
90'	8760	TB-2	C-4	FE-100-SG	SOLAR FIELD SUPPLY PUMP INLET PRESSURE
90'	8760	TB-2	C-4	FE-102-SG	SOLAR FIELD SUPPLY PUMP OUTLET PRESSURE
90'	8760	TB-2	C-4	TE-112-R	SOLAR FIELD SUPPLY PUMP INLET TEMPERATURE
90'	8760	TB-2	C-4	TE-110-R	SOLAR FIELD SUPPLY PUMP OUTLET TEMPERATURE
1000'	8760	TB-3	C-3	FE-200DP	TURBINE METER PICKOFF FOR BOILER #1 NATURAL GAS FLOWRATE
1000'	8760	TB-3	C-3	FE-202DP	TURBINE METER PICKOFF FOR BOILER #2 NATURAL GAS FLOWRATE
620'	8760	TB-3	C-2	TE-108-R	COLLECTOR FIELD "A" AMBIENT TEMPERATURE
150'	8760	TB-2	C-7	FE-101-DP	SOLAR COLLECTOR FIELD "B" INLET FLOW
150'	8760	TB-2	C-7	TE-101-R	SOLAR COLLECTOR FIELD "B" INLET TEMPERATURE
210'	8760	TB-1	C-5	FE-103-DP	SOLAR COLLECTOR FIELD "B" OUTLET FLOW
210'	8760	TB-1	C-5	TE-103-R	SOLAR COLLECTOR FIELD "B" OUTLET TEMPERATURE
340'	8760	TB-1	C-8	FE-105-DP	SINGLE COLLECTOR ROW FIELD "B" INLET FLOW
340'	8760	TB-1	C-8	TE-105-R	SINGLE COLLECTOR ROW FIELD "B" INLET TEMPERATURE
300'	8760	TB-1	C-8	FE-105-SG	SINGLE COLLECTOR ROW FIELD "B" INLET PRESSURE
200'	8760	TB-1	C-5	TE-107-R	SINGLE COLLECTOR ROW FIELD "B" OUTLET TEMPERATURE
200'	8760	TB-1	C-5	FE-107-SG	SINGLE COLLECTOR ROW FIELD "B" INLET PRESSURE
475'	8760	TB-1	C-8	TE-109-R	COLLECTOR FIELD "B" AMBIENT TEMPERATURE
150'	8621	TB-2	C-6	WV-001-DP	WIND VELOCITY OPEN ROOF
150'	9365	TB-2	C-6	RF-001-DC	RAIN FALL
150'	8690	TB-2	C-6	RH-001-AM	RELATIVE HUMIDITY
150'	8621	TB-2	C-6	WD-001-P	WIND DIRECTION ON OPEN ROOF
150'	8760	TB-2	C-6	TE-001-R	AMBIENT AIR TEMPERATURE
150'	8760	TB-2	C-6	SI-102-AM	SOLAR INSOLATION TOTAL HORIZONTAL
150'	8760	TB-1	C-8	SI-100-AM	SOLAR INSOLATION TOTAL TRACKED
150'	8760	TB-1	C-8	SI-101-AM	SOLAR INSOLATION TOTAL TRACKED WITH SHADOW BAND
570'	8760	TB-3	C-2	FS-106-NO	FLOW SWITCH FIELD "A" OUTPUT
570'	8760	TB-2	C-4	FS-108-NO	FLOW SWITCH FIELD "A" OUTPUT
200'	8760	TB-1	C-5	FS-107-NO	FLOW SWITCH FIELD "B" OUTPUT
30'	8760	TB-4	C-10	EP-601-A	ELECTRICAL POWER PUMP MOTOR PRIMARY
30'	8760	TB-4	C-10	EP-602-A	ELECTRICAL POWER PUMP MOTOR BACKUP
30'	8760	TB-4	C-10	EP-603-A	ELECTRICAL POWER SOLAR COLLECTOR PYLONS (BH69-BH80)
1060'	8723		C-11	ENGINEER CRT	DEC VT 100 ENGINEER'S DISPLAY CRT
1060'	8723			MAINT. PRINTER	DEC LA-120 MAINTENANCE PRINTER FOR PERFORMANCE EVALUATION
420'	8723			MAINTENANCE CRT	DEC VT 100 MAINTENANCE DISPLAY CRT
	TELCO		C-12	TELEPHONE LINE	TELCO RJ455 COMMUNICATION LINK FOR REMOTE MODEN OPERATION
550'	8760	TB-3	C-2	TS-106-NC	OVERTEMPERATURE SWITCH FOR HAZARD LOOP FIELD "A"
200'	8760	TB-1	C-5	TS-107-NC	OVERTEMPERATURE SWITCH FOR HAZARD LOOP FIELD "B"
150'	8760		C-9	TS-108-NC	FREEZE-STAT FOR PUMP CONTROL
550'	8760	TB-3	C-2	PS-106-NC	OVER PRESSURE SWITCH FOR HAZARD LOOP FIELD "A"
200'	8760	TB-1	C-5	PS-107-NC	OVER PRESSURE SWITCH FOR HAZARD LOOP FIELD "B"
30'	8760	TB-4	C-10	EP-604-A	ELECTRICAL POWER SOLAR COLLECTOR PYLONS (BH47-BH58)
30'	8760	TB-4	C-10	EP-605-A	ELECTRICAL POWER SOLAR COLLECTOR PYLONS (BH99-BH106)
30'	8760	TB-4	C-10	EP-606-A	ELECTRICAL POWER SOLAR COLLECTOR PYLONS (BH91-BH98)
30'	8760	TB-4	C-10	EP-607-A	ELECTRICAL POWER SOLAR COLLECTOR PYLONS (BH81-BH90)
30'	8760	TB-4	C-10	EP-608-A	ELECTRICAL POWER SOLAR COLLECTOR PYLONS (BH59-BH68)
30'	8760	TB-4	C-10	EP-609-A	ELECTRICAL POWER TO ALL CONTROLS

* SUPPLIED BY ELECTRICAL CONTRACTOR

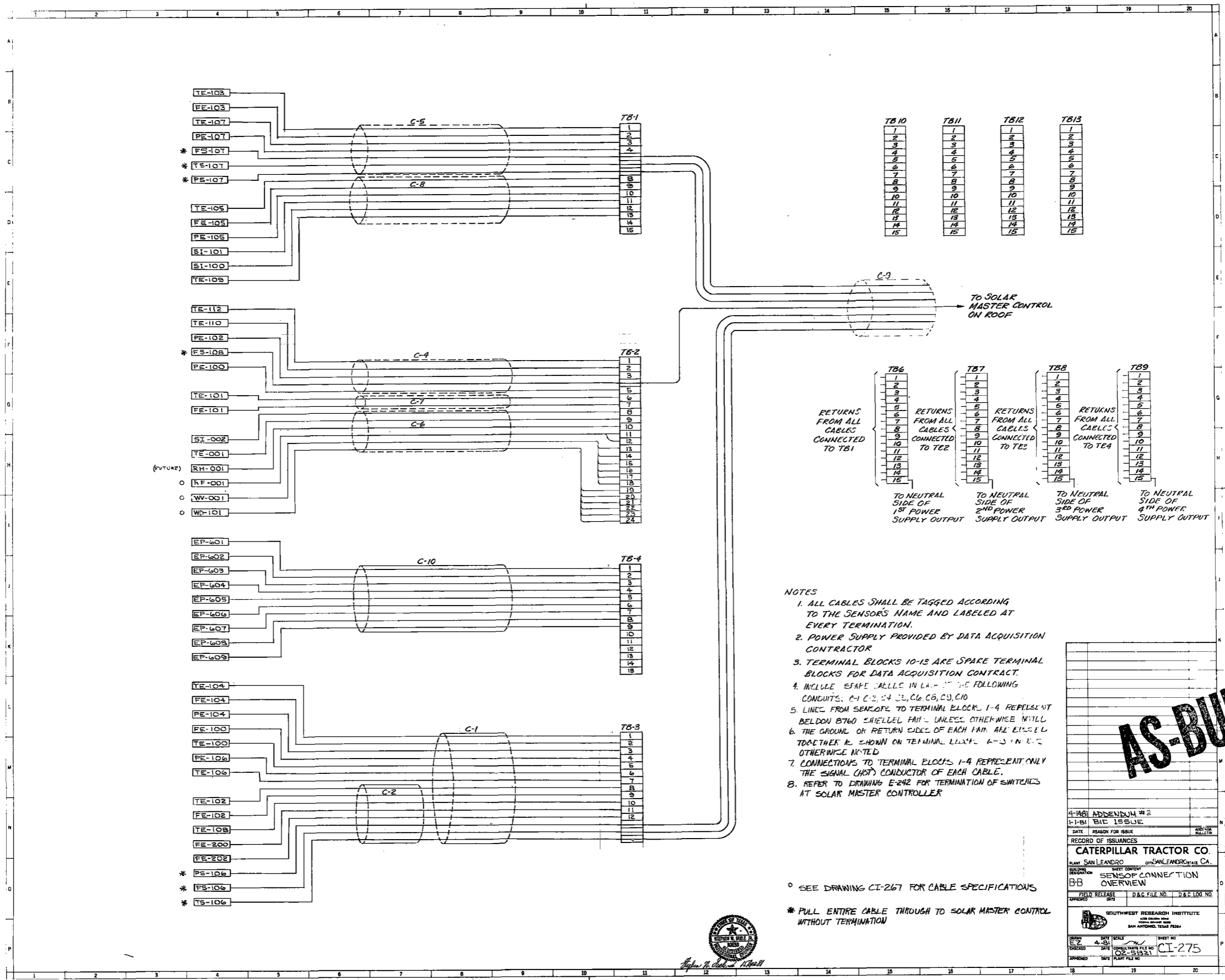
- NOTES:
1. CONDUIT SIZES PER DWG. CI-261.
2. WIRE GAGE SHOULD BE # 22 OR THICKER
3. FIELD VERIFY ALL CABLE LENGTHS.

AS-BUILT

4-18-81 APPENDIX #1			
1-1-B1 BID ISSUE			
DATE	REASON FOR ISSUE	ISSUED BY	REVISED BY
RECORD OF ISSUANCES			
CATERPILLAR TRACTOR CO.			
PLANT	SAN LEANDRO	CITY	SAN LEANDRO, CALIF.
PROJECT	SOLAR IPH SYSTEM		
DOCUMENT	SPECIFICATIONS LIST		
FIELD RELEASE DATE	D&C FILE NO.	D&C LOG NO.	
APPROVED			
SOUTHWEST RESEARCH INSTITUTE			
4800 BRADLEY BLVD. SAN ANTONIO, TEXAS 78248			
FORM	DATE	SCALE	SHEET NO.
1-2	4/80	1/4"	1
DESIGNED BY	DATE	CONSULTANT FILE NO.	
J.M.	1/77	CI-261	
APPROVED	DATE	DRAWING FILE NO.	
		CI-261	



Stephen H. ...



- NOTES**
1. ALL CABLES SHALL BE TAGGED ACCORDING TO THE SENSOR'S NAME AND LABELED AT EVERY TERMINATION.
 2. POWER SUPPLY PROVIDED BY DATA ACQUISITION CONTRACTOR
 3. TERMINAL BLOCKS 10-15 ARE SPARE TERMINAL BLOCKS FOR DATA ACQUISITION CONTRACT.
 4. INCLUDE STRAP LABELS IN EACH OF THE FOLLOWING CONDUITS: C-1, C-2, C-3, C-4, C-5, C-6, C-7, C-8, C-9, C-10
 5. LINE FROM SENSORS TO TERMINAL BLOCKS 1-4 REPRESENT BELDON 8760 SHIELDED PAIR UNLESS OTHERWISE NOTED
 6. THE GROUND OR RETURN SIDES OF EACH PAIR ARE LISTED TOGETHER AS SHOWN ON TERMINAL BLOCKS 1-4 UNLESS OTHERWISE NOTED
 7. CONNECTIONS TO TERMINAL BLOCKS 1-4 REPRESENT ONLY THE SIGNAL (HOT) CONDUCTOR OF EACH CABLE.
 8. REFER TO DRAWING E-242 FOR TERMINATION OF SWITCHES AT SOLAR MASTER CONTROLLER

SEE DRAWING CI-267 FOR CABLE SPECIFICATIONS

PULL ENTIRE CABLE THROUGH TO SOLAR MASTER CONTROL WITHOUT TERMINATION

AS-BUILT



4-1461 ADDENDUM #2
 1-1-81 BID ISSUE

DATE: _____ REASON FOR ISSUE: _____

RECORD OF ISSUANCES

CATERPILLAR TRACTOR CO.

PLANT: SAN LEANDRO CITY: SAN LEANDRO, CALIF. CA.

PROJECT: _____

DESCRIPTION: SENSOR CONNECTION OVERVIEW

BB

FIELD RELEASE DATE: _____ D&C FILE NO.: _____ D&C LOG NO.: _____

APPROVED: _____

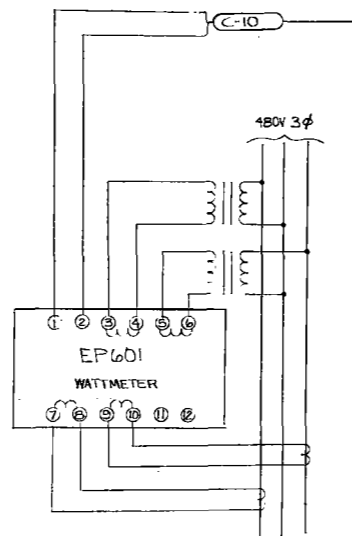
SOUTHWEST RESEARCH INSTITUTE
 1000 RESEARCH DRIVE
 SAN ANTONIO, TEXAS 78241

DRAWN: E2 DATE: 4-81 SHEET NO.: _____

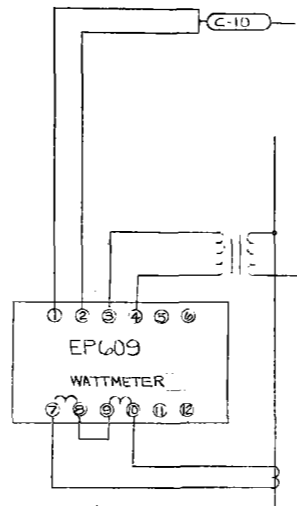
CHECKED: _____ DATE: _____ SHEET TOTAL: 15 BY: _____

APPROVED: _____ DATE: _____ SHEET FILE NO.: _____

CI-275

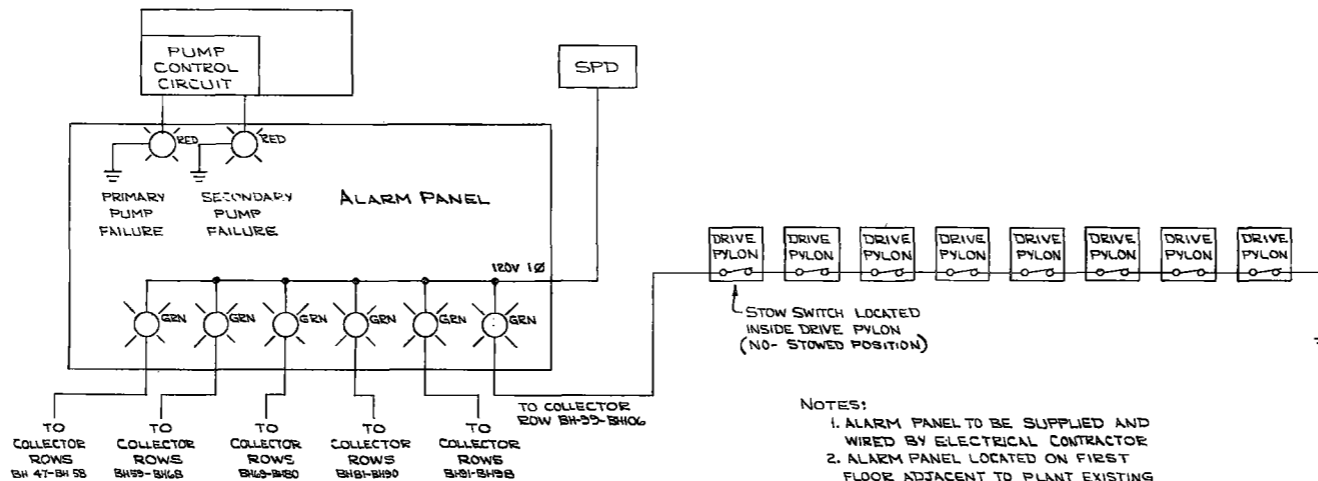
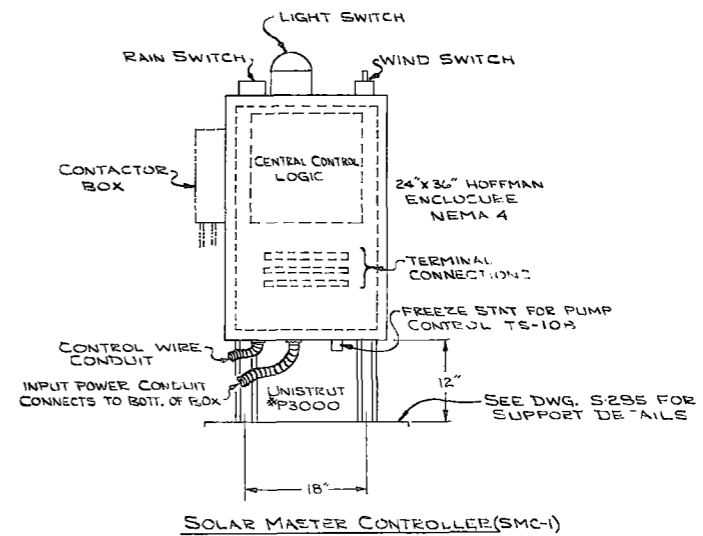


TYPICAL 3 ϕ WATTMETER CONNECTIONS
(EP601-608)



TYPICAL 1 ϕ WATTMETER CONNECTIONS
(EP609)

RDC CURRENT & POTENTIAL TRANSFORMER CONNECTIONS (EP601-EP609)
SEE DWG. E-240, SUPPLIED AND INSTALLED BY ELECTRICAL CONTRACTOR



ALARM PANEL SYSTEM
BLOCK DIAGRAM
NO SCALE

- NOTES:
1. ALARM PANEL TO BE SUPPLIED AND WIRED BY ELECTRICAL CONTRACTOR
 2. ALARM PANEL LOCATED ON FIRST FLOOR ADJACENT TO PLANT EXISTING ALARM PANELS. CHECK WITH OWNERS REF FOR EXACT LOCATION.

AS-BUILT

4-1421 ADDENDUM #2
1-1-81 BID ISSUE

SAN LEANDRO SAN LEANDRO CA.
SOLAR IPH SYSTEM
B B POWER TO MOTOR CONTROLS

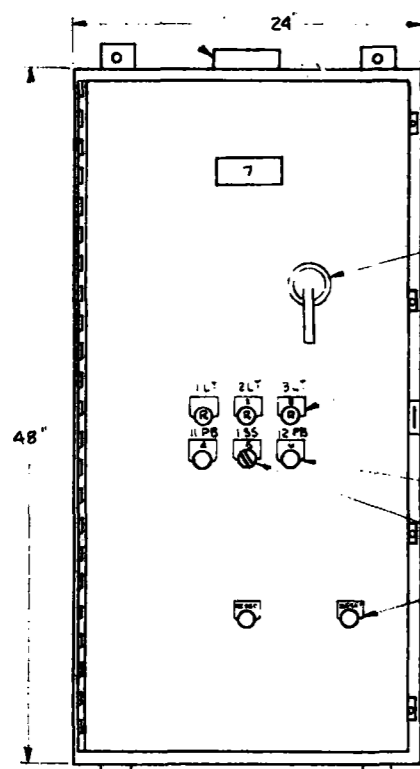


Stephen A. Steinhilber No. 112480

SOUTHWEST RESEARCH INSTITUTE
4325 CAMPUS DR.
10700 BURNETT DR.
SAN ANTONIO, TEXAS 78244

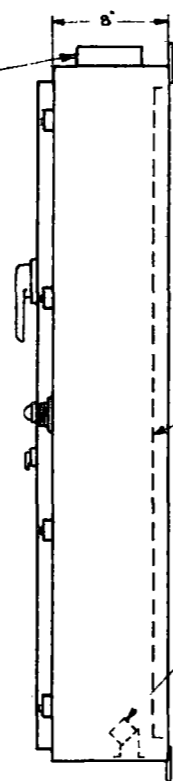
EZ 1124-80
M.H. 12-21-80 02-582.1 CI-276

← ALARM HORN (MOUNTED ON TOP)



ENCLOSURE
SCALE: 1/8"=1"

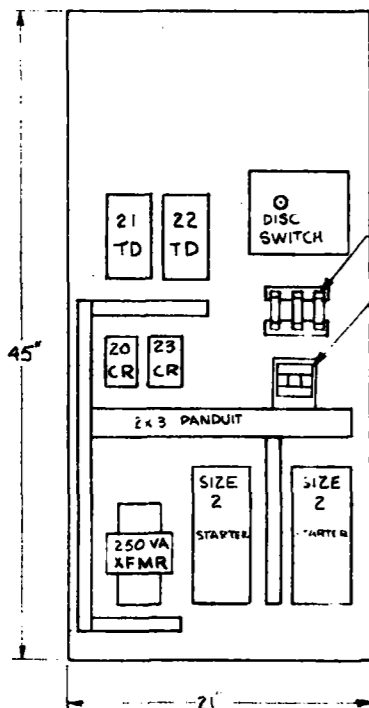
ALARM HORN



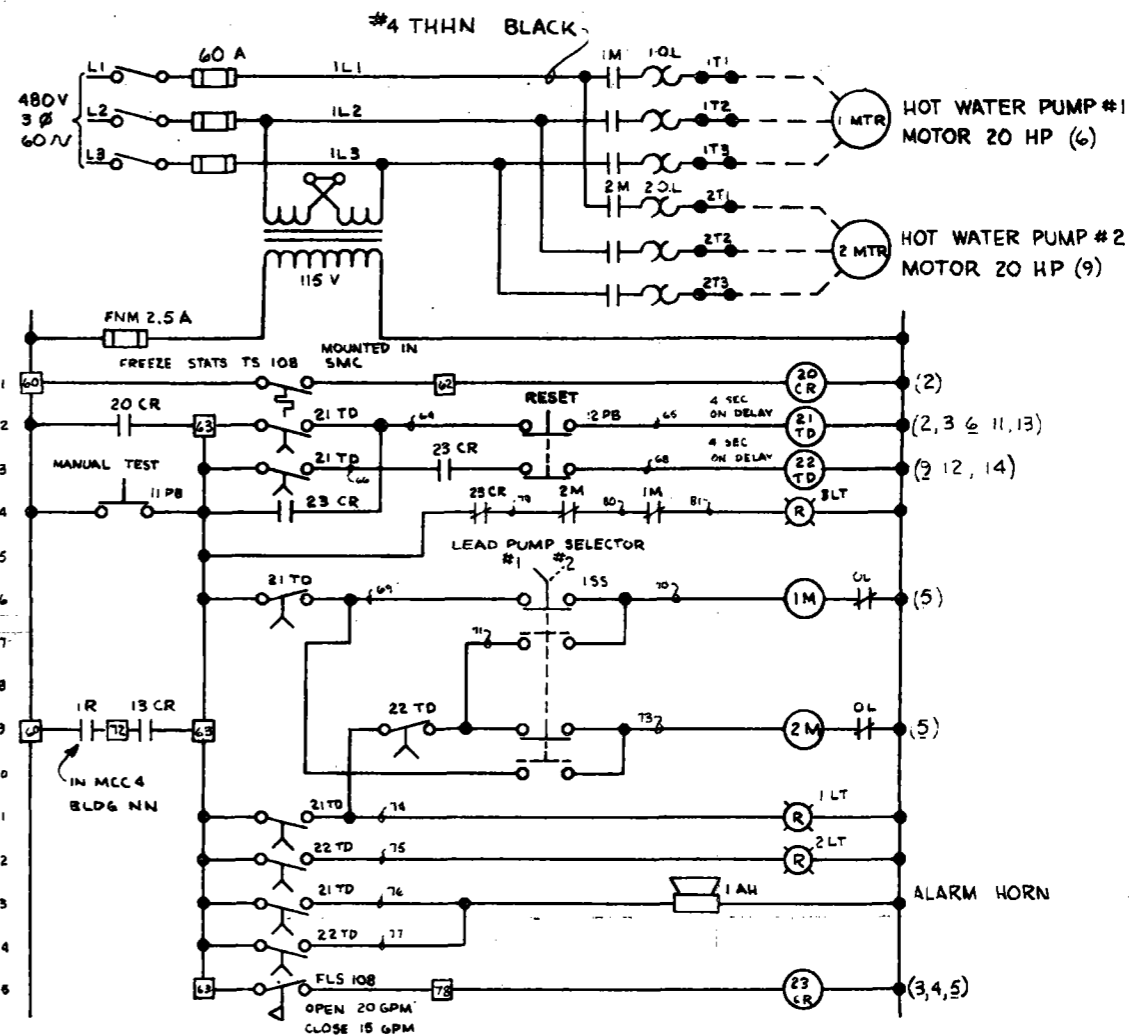
SECONDARY FUSE AND
TERMINALS MOUNTED
ON ANGLE BRACKETS

BILL OF MATERIALS:

- ENCLOSURE - 48x24x8 NEMA 12 PAINTED RUSTOLEUM #925 FEDERAL SAFETY BLUE
- FUSED DISCONNECT SWITCH ALLEN BRADLEY: 60A 600V CAT NO. 1494R-N60
- SIZE 2 STARTERS - ALLEN BRADLEY: #509 COD W/AUX CONTACTS #595AB
- ALARM HORN - FEDERAL: MODEL 350
- TRANSFORMER - ACME: 250 VA 480 120 #TA-1-81305
- TERMINAL BLOCKS - CONNECTRON: #NFT-3 600V
- TIME DELAY RELAY - AGASTAT: #7014 AC 4 PDT 10A 600V CONTACTS 2-20 SEC ON DELAY 120 VAC COIL
- CONTROL RELAYS - ALLEN BRADLEY: TYPE P #700P400-AL
- PUSHBUTTONS - ALLEN BRADLEY: 800T SERIES FLUSH BLACK HEADS CONTACTS AS REQD.
- SELECTOR SWITCH - ALLEN BRADLEY: #800T-H2B
- PILOT LIGHT - ALLEN BRADLEY: #800T-P16R W/RED LENS
- FUSES/FUSE BLOCKS - ALLEN BRADLEY: #1491-R266 W/ECON: FUSE #ECSR-60
- SPLICE BLOCK - MARATHON: #1423570



MOUNTING PANEL
SCALE: 1/8"=1"



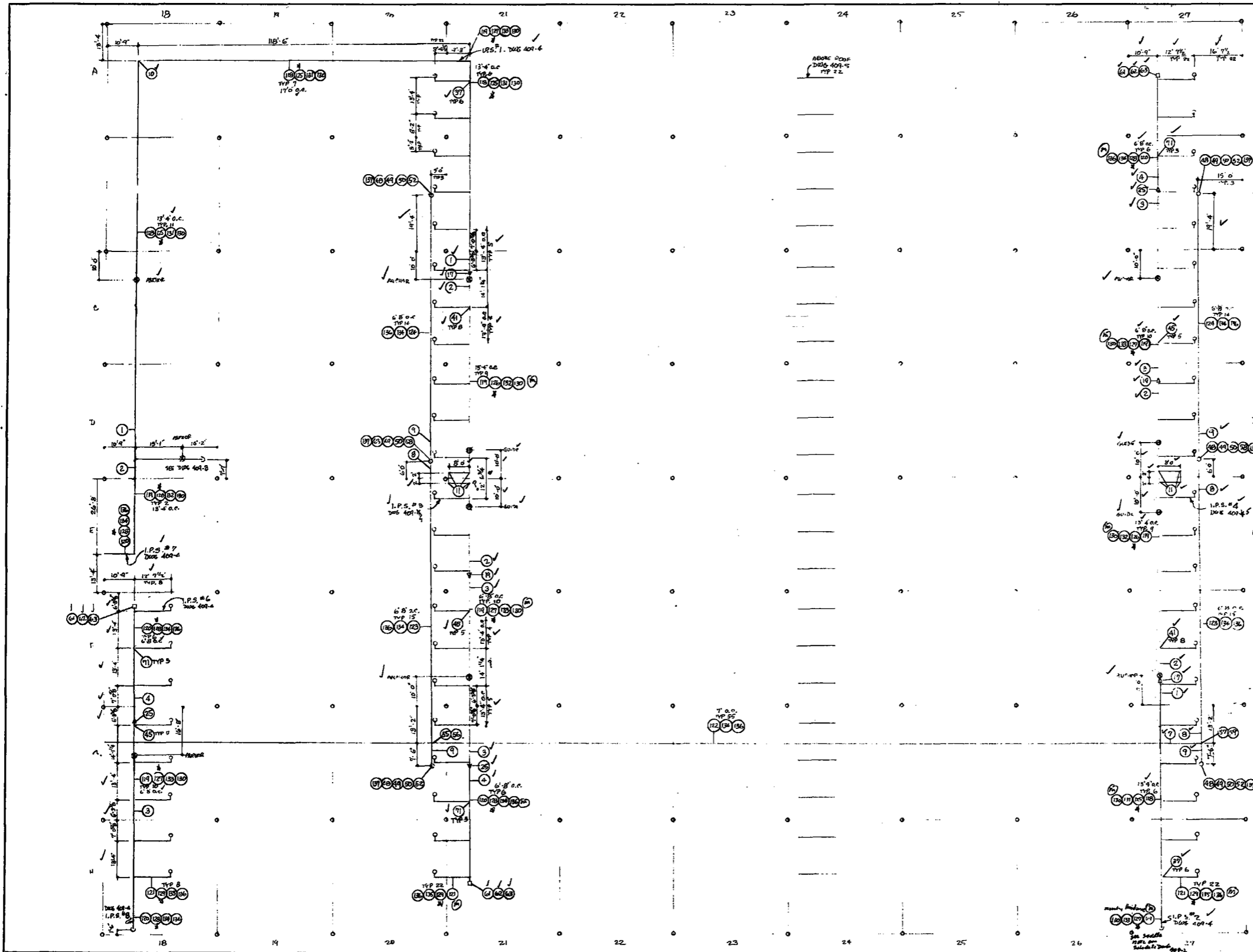
PUMP CONTROL PANEL SCHEMATIC
NO SCALE

NOTES:

1. ALL POWER WIRING TO BE #4 THHN BLACK
2. ALL CONTROL WIRING TO BE #16 MTW RED W/ VINYL SLEEVE WIRE MARKERS
- NO. ENGRAVING SCHEDULE:
1. LEAD PUMP FAILURE
2. SECONDARY PUMP FAILURE
3. FLOW SWITCH STUCK ON
4. PUMP MANUAL TEST
5. LEAD PUMP #1 #2
6. ALARM RESET
7. SOLAR CIRCULATION PUMP CONTROL PANEL (1/2" LETTERING)

AS-BUILT
JUN 19 1981

REVISIONS		APTOS CONTROL SYSTEMS INC. P. O. BOX 732 WATSONVILLE, CA 95076		TITLE: PUMP CONTROL PANEL	
SYMBOL	DATE	FOR: PHILLIPS & OBER ELECTRIC SUPPLY SAN FRANCISCO CA.		SF 35986	
PER ENG. NOTES	1 5-8			DRN. BY: PE-TON	
FOR APPROVAL	0 4-28			CHKD. BY:	
				A.C.S. JOB NO. 195-681	
				195-1	



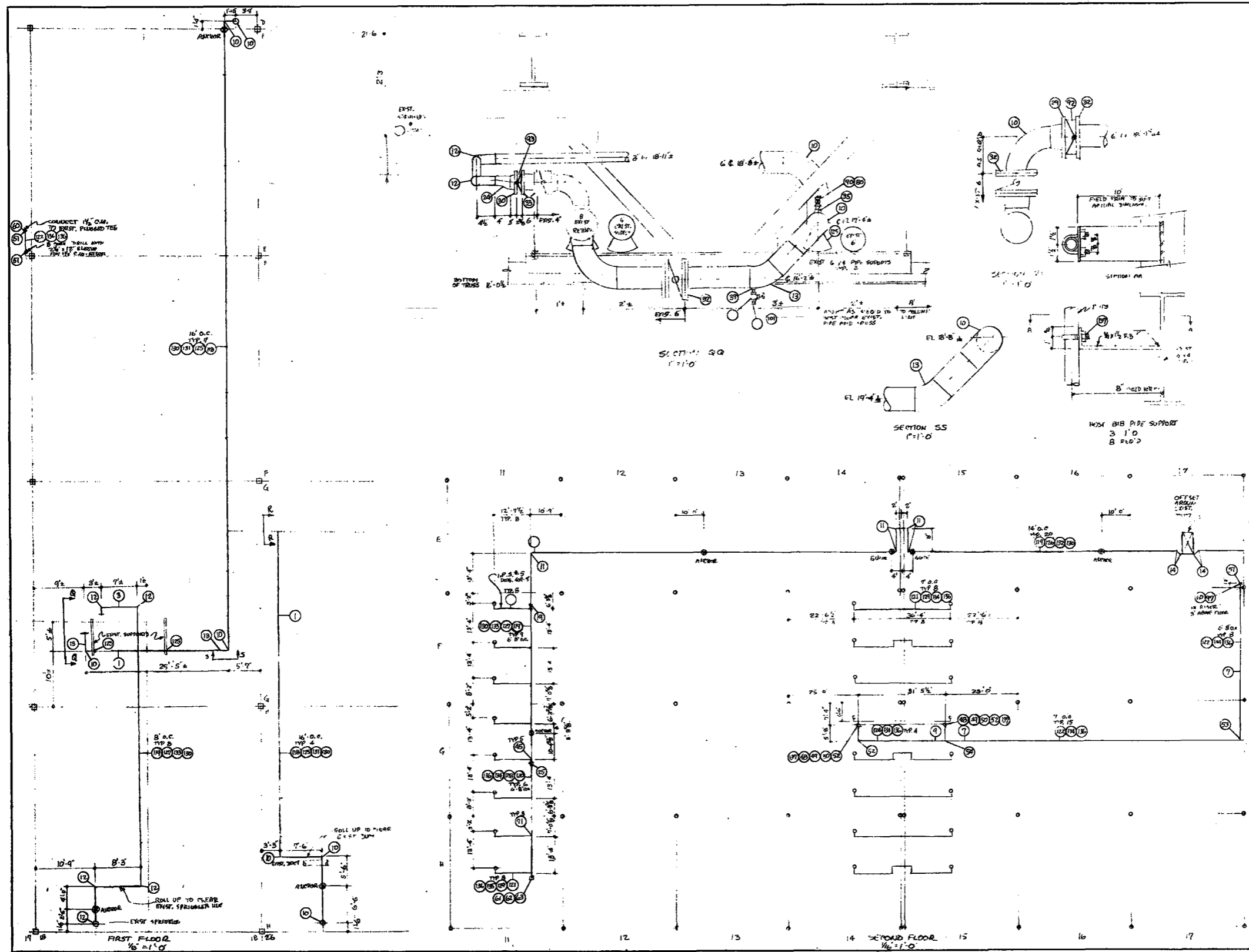
NO.	QTY	ITEM
1	610	6\"/>

AS-BUILT

JUN 19 1967

MONTEREY MECHANICAL CO.
8278 SAN LEANDRO STREET
OAKLAND, CALIFORNIA 94621
(415) 632-3173 Calif. Lic. No. 240442

TITLE: SECOND FLOOR - SOUTH PIPING
CUSTOMER: CATERPILLAR TRACTOR 10.
DRAWN BY: [Name] SCALE: 1/4" = 1'-0" DATE: 5/10/67
CHECKED BY: [Name] DATE: 5/10/67



NO.	QTY	DESCRIPTION	ITEM
70	2	2x1/2x2 STD BLANK MAIL	70
71	12	2x2x1	71
72	2	2x2x3/4	72
73	2	1x1/2x1	73
74	22	1x3/4x1	74
75	12	1x1x3/4	75
76	30	1	76
77	8	3/4	77
78	2	1 1/2	UNION
79	2	1	
80	4	2	PLUS
81	4	1	
82	12	3/4	
83	8	1/2	
84	22	1	CAP
85	8	2	STD. C.I. SWEETWELD WAMP FLANGE
86	16	1	
87	7	6	POWER 4222 T BALL VALVE
88	5	4	
89	2	3	
90	1	2	NBRD T-580
91	68	1	
92	1	6	TECHNOCHECK CHECK VALVE
93	3	4	
94	1	6	SPENCE 634 T57 TEMP. REG. VALVE
95	1	3	
96	5	2	WALWORTH 95 GLOBE VALVE
97	2	1 1/2	
98	2	1 1/4	
99	8	1	
100	12	3/4	
101	1	1/2	
102	5	6	MULLER 751 STRAINER
103	1	4	
104	2	3	
105	4	1	11
106	1	1 1/2	B. P.G. AIRMINT SETTER
107	30	1 1/2	
108	1	1	
109	86	3/4	TERRICE 3-4122 EXT. NECK TH. S. MULLER
110	4	TRICE BX93406 9" TURBOCHARGER	
111	6	1/2	STAINLESS STEEL WELDED VALVE
112	6	1/2	ASHROFT 2042 GUNGE 0/100 PSI
113	1	6	SEAFORD 743 VENTURI - WELD END
114	4	670	
115	2	1/2	300# HALF NIPPLING
116	60	1/4	X 4 KH NIPPLE - CUT IN HALF & OILED TO WORK
117	30	1/4	X 6 STD NIPPLE
118	41	16	ELMER 14 DRILL HANSLER 6" PIPE WITH 4 DR
119	87	10	4P
120	26	8	12 CLEVIS
121	158	5	
122	30	1 1/2	
123	30	1 1/4	
124	28	1	
125	43	674	0.797 25
126	28	4+3	25
127	49	3x3	
128	26	2x3	
129	158	1x2	253
130	20	ELMER 95 ADJ. SCAM CLAMP	
131	41	3/4	ELMER 235 ROD SOCKET FOR 95-6 PIPE
132	38	3/8	
133	49	1/2	
134	146	3/8	ELMER 29A C CLAMP - 2" SMALLER PIPE
135	60	3/8	ELMER 26 EXPANSION C CLAMP - 1" SMALLER PIPE
136	256	ELMER 29 B C CLAMP PL TANK	
137	84	1" IPS	3/8 ELMER 68 U BOLT FOR PIPE SUPPORT
138	2	3	METROPLEX SL PUMP MANIFOLD
139	2	4	

AS-BUILT

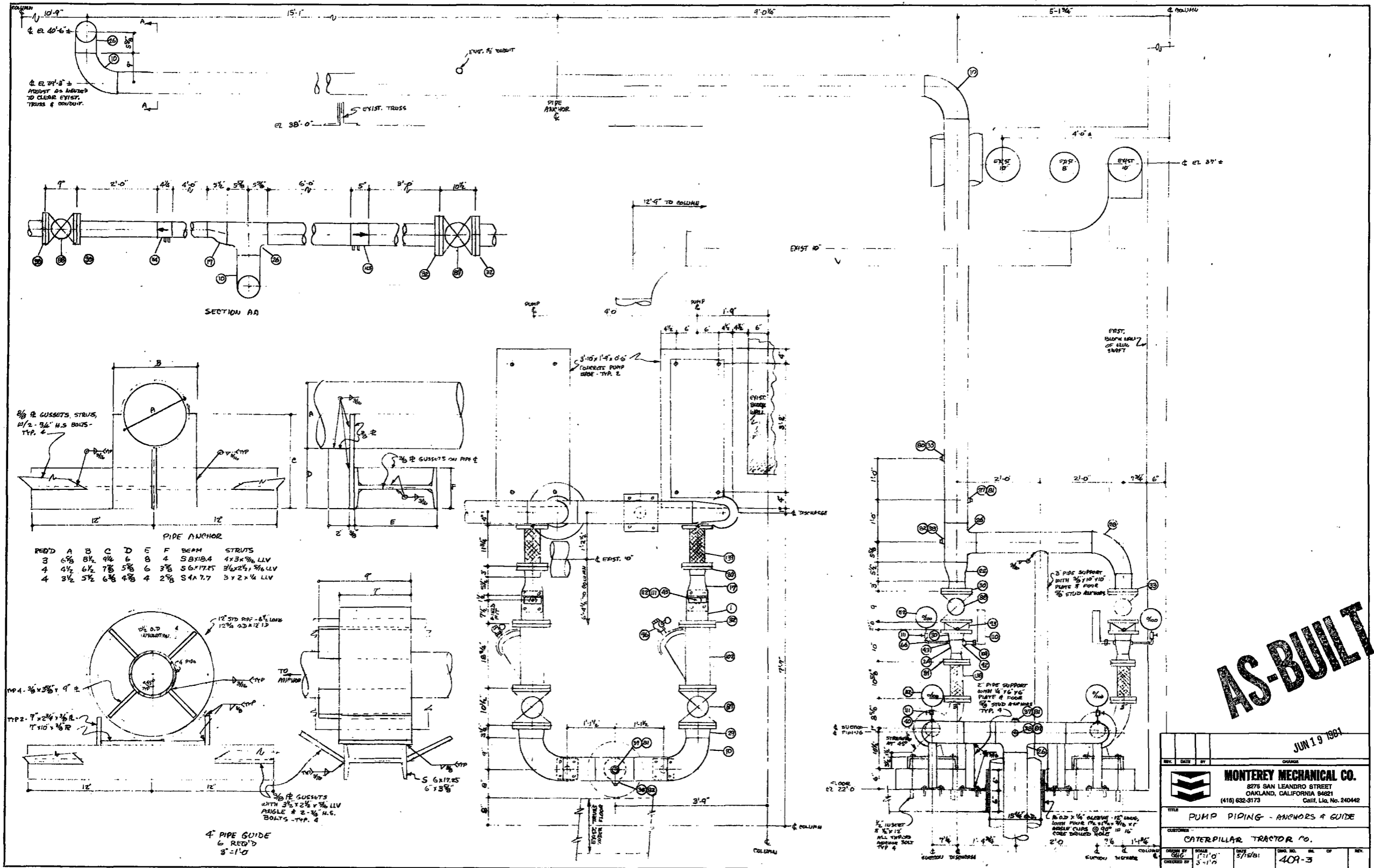
JUN 19 1981

MONTEREY MECHANICAL CO.
 8278 SAN LEANDRO STREET
 OAKLAND, CALIFORNIA 94621
 (415) 632-3173 Calif. Lic. No. 240442

TITLE: SECOND FLOOR - HYDRA PIPING

CUSTOMER: CATERPILLAR TRACTOR '80

ORDER BY: DATE: 5/11/80 DWG NO: 409-2



SECTION AA

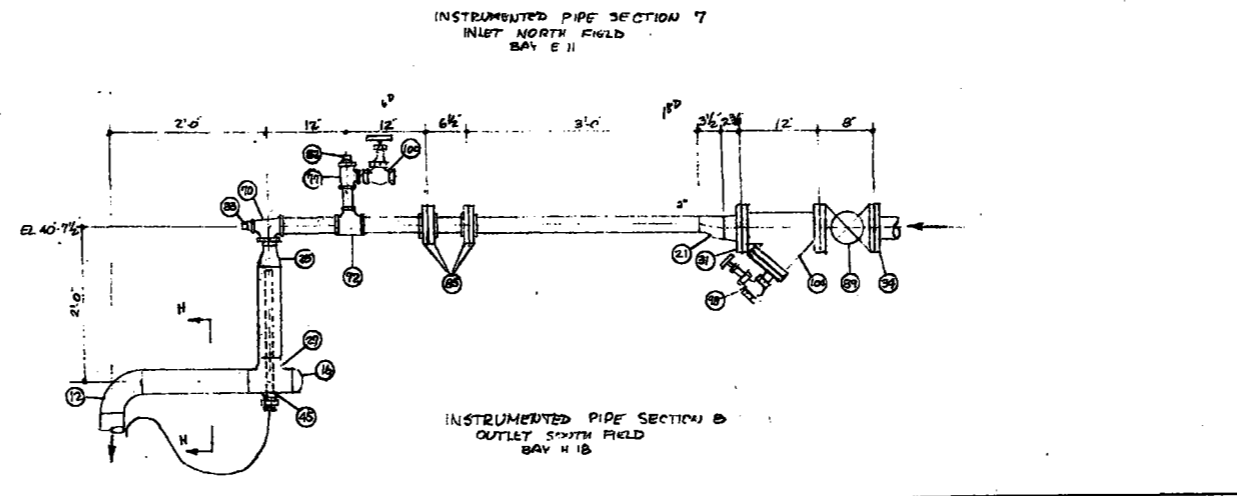
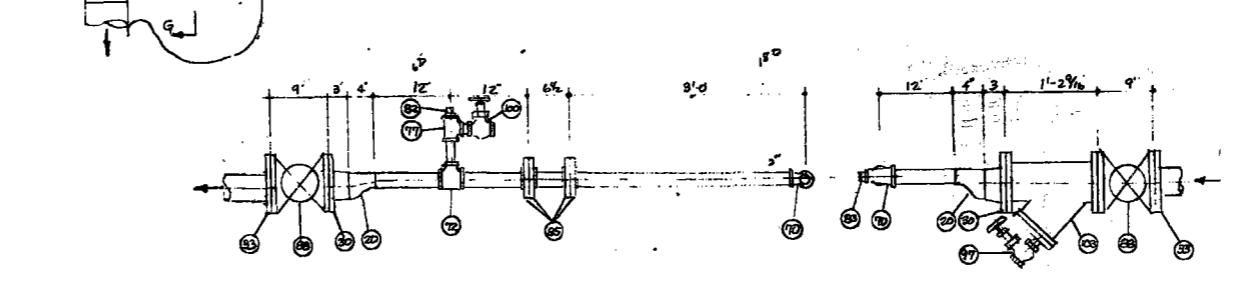
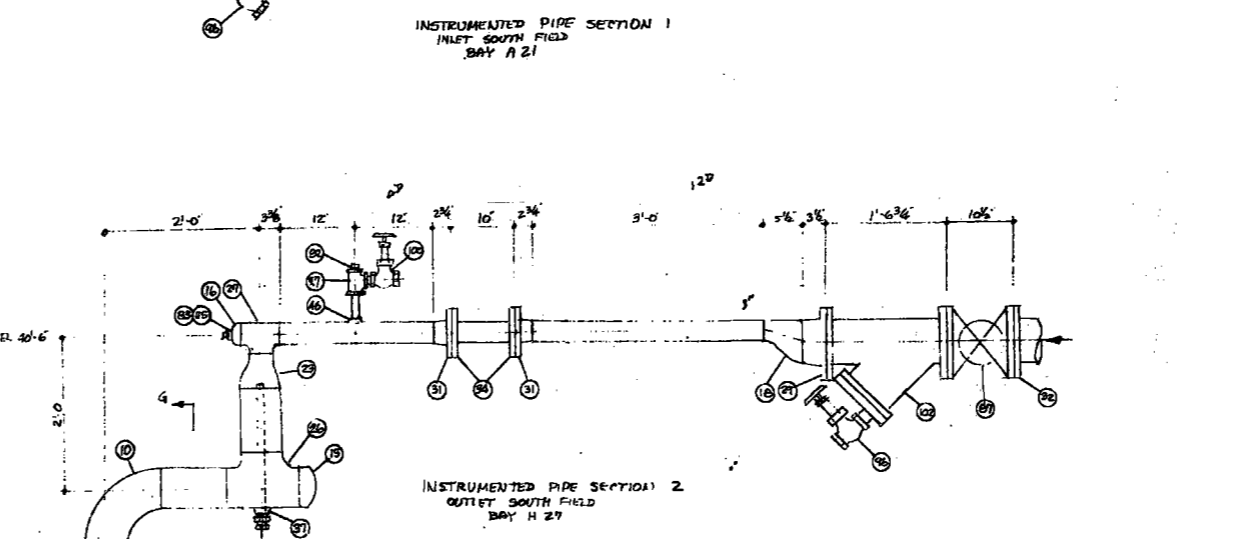
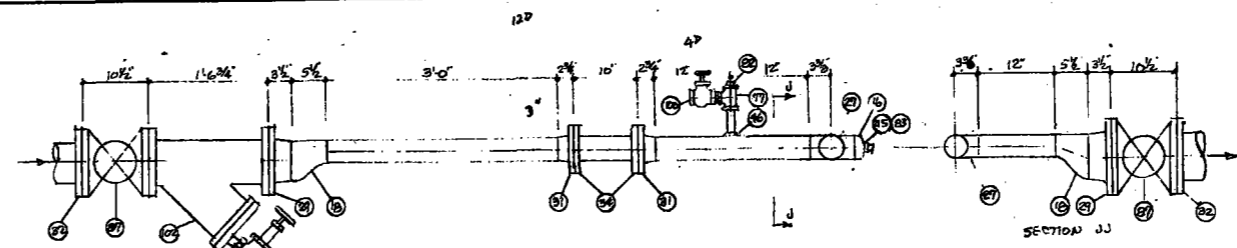
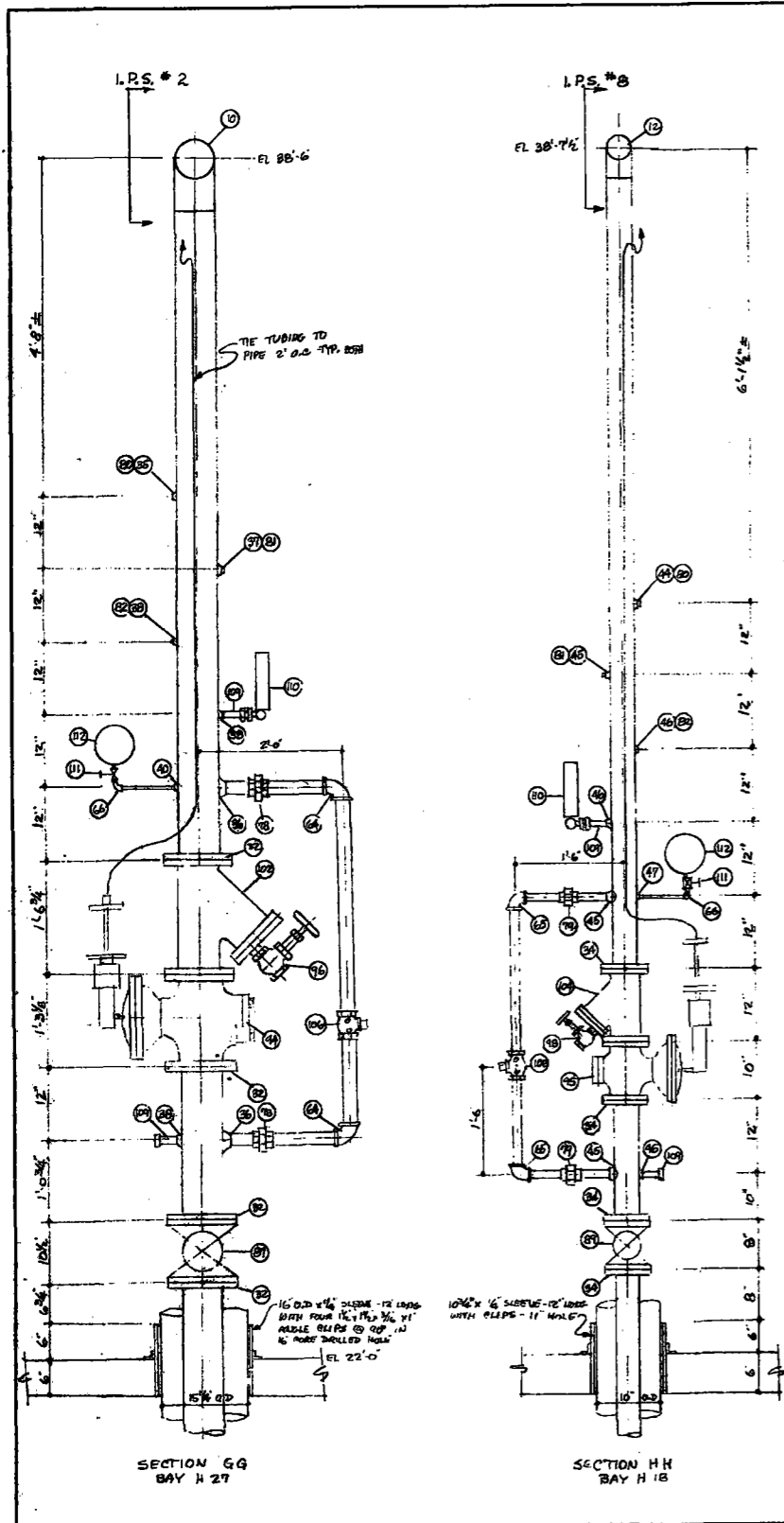
PIPE ANCHOR

REQ'D	A	B	C	D	E	F	BEAM	STRUTS
3	6 3/8	8 1/2	9 1/2	6	8	4	S8X10.4	4x3x3/4 LLV
4	4 1/2	6 1/2	7 3/8	5 3/8	6	3 3/8	S6X17.25	3/4x2 1/2x3/8 LLV
4	3 1/2	5 1/2	6 3/8	4 3/8	4	2 3/8	S4X7.7	3x2x1/4 LLV

AS-BUILT

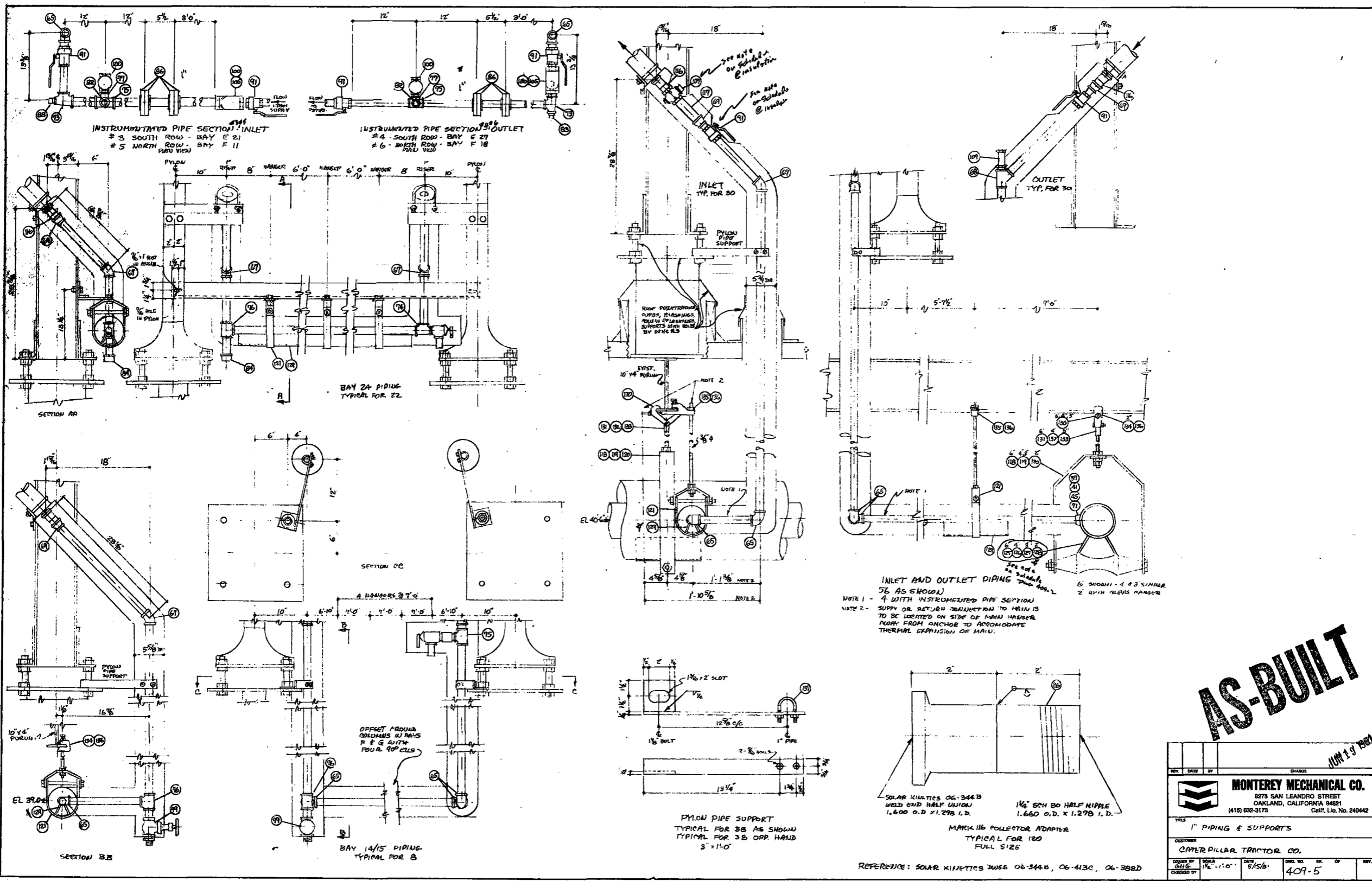
JUN 19 1981

REV.	DATE	BY	CHANGE
MONTEREY MECHANICAL CO.			
8275 SAN LEANDRO STREET OAKLAND, CALIFORNIA 94621 (415) 632-9173 Calif. Lic. No. 240442			
TITLE: PUMP PIPING - ANCHORS & GUIDE			
CUSTOMER: CATERPILLAR TRACTOR CO.			
DESIGNED BY	SCALE	DATE	DWG. NO.
CHKD BY	3-1/2"	5/15/81	409-3
CHECKED BY			



AS-BUILT

REV.	DATE	BY	CHANGED
JUN 19 1981			
MONTEREY MECHANICAL CO.			
8273 SAN LEANDRO STREET OAKLAND, CALIFORNIA 94621 (415) 832-3173 Calif. Lic. No. 240442			
TITLE INSTRUMENTED PIPE SECTIONS			
CUSTOMER CATERPILLAR TRACTOR CO.			
DESIGNED BY CJM	SCALE 1" = 1'-0"	DATE 5/15/81	DRAW. NO. 409-4
CHECKED BY			



AS-BUILT

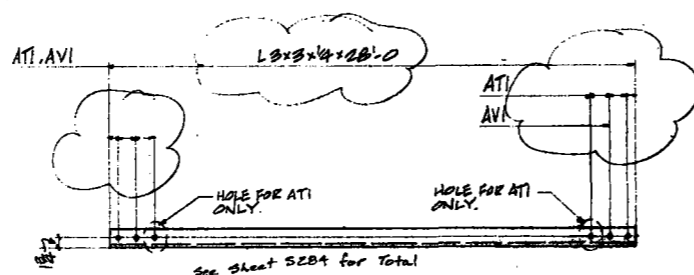
JUN 19 1987

REV.	DATE	BY	CHANGE
MONTEREY MECHANICAL CO.			
8275 SAN LEANDRO STREET OAKLAND, CALIFORNIA 94621 (415) 832-3173 Calif. Lic. No. 240442			
TITLE: 1" PIPING & SUPPORTS			
CUSTOMER: CAPTER PILLAR TRACTOR CO.			
DESIGNED BY: GHS	SCALE: 1/4" = 1'-0"	DATE: 5/5/87	DWG. NO.: 409-5
CHECKED BY:			

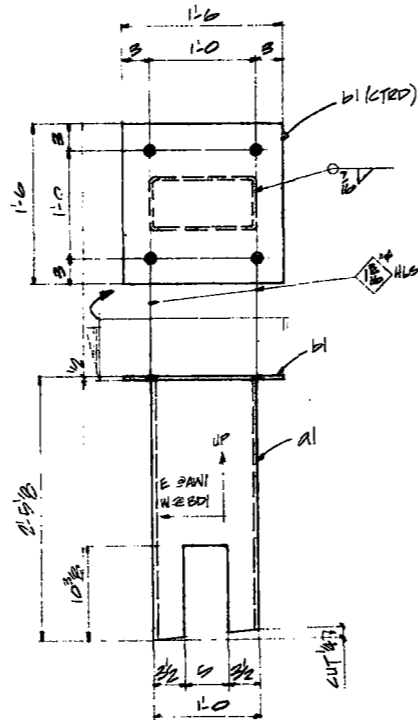
REFERENCE: SOLAR KINETICS JWS 06-344B, 06-413C, 06-388D

FURNISH PLAIN MATERIAL

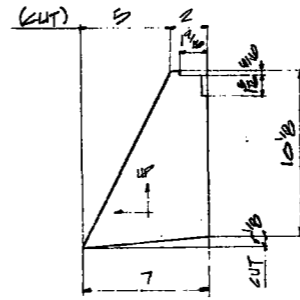
- 84 - L^{1/2}x^{1/2}x^{1/2} x 3'-7" ~ A1 (FOR TRUSS TIE, TIE-1)
- 84 - L^{1/2}x^{1/2}x^{1/2} x 3'-8" ~ B1 (FOR TRUSS TIE, TIE-1)
- 84 - L^{1/2}x^{1/2}x^{1/2} x 3'-10" ~ C1 (FOR TRUSS TIE, TIE-1)
- 84 - L^{1/2}x^{1/2}x^{1/2} x 4'-0" ~ D1 (FOR TRUSS TIE, TIE-1)
- 84 - L^{1/2}x^{1/2}x^{1/2} x 4'-2" ~ H1 (FOR TRUSS TIE, TIE-1)
- 4 - L^{1/2}x^{1/2}x^{1/2} x 4'-1" ~ K1 (FOR TRUSS TIE-1)
- 8 - L^{1/2}x^{1/2}x^{1/2} x 6'-0" ~ M1 (FOR TRUSS TIE-1)
- 130 - L^{1/2}x^{1/2}x^{1/2} x 20'-0" ~ P1 (FOR TRUSS TIE-1, T2R, T2L, T2E)
- 84 - L^{1/2}x^{1/2}x^{1/2} x 4'-8" ~ S1 (FOR TRUSS T2R)
- 84 - L^{1/2}x^{1/2}x^{1/2} x 4'-8" ~ T1 (FOR TRUSS T2R)
- 84 - L^{1/2}x^{1/2}x^{1/2} x 5'-4" ~ V1 (FOR TRUSS T2R)
- 84 - L^{1/2}x^{1/2}x^{1/2} x 5'-8" ~ W1 (FOR TRUSS T2R)
- 96 - L^{1/2}x^{1/2}x^{1/2} x 6'-8" ~ AA1 (FOR TRUSS T2R)
- 96 - L^{1/2}x^{1/2}x^{1/2} x 6'-8" ~ AB1 (FOR TRUSS T2R)
- 96 - L^{1/2}x^{1/2}x^{1/2} x 6'-14" ~ AC1 (FOR TRUSS T2R)
- 264 - L^{1/2}x^{1/2}x^{1/2} x 6'-10" ~ AD1 (FOR TRUSS T2R)
- 44 - L^{1/2}x^{1/2}x^{1/2} x 10'-0" ~ AH1 (FOR TRUSS T2R)
- 76 - L^{1/2}x^{1/2}x^{1/2} x 7'-0" ~ AK1 (FOR TRUSS T2R)
- 176 - L^{1/2}x^{1/2}x^{1/2} x 7'-9" ~ AM1 (FOR TRUSS T2R)
- 96 - L^{1/2}x^{1/2}x^{1/2} x 6'-10" ~ AP1 (FOR TRUSS T2R)
- 4 - L^{1/2}x^{1/2}x^{1/2} x 4'-0" ~ BH1 (FOR TRUSS TIE-1)
- 96 - L^{1/2}x^{1/2}x^{1/2} x 6'-14" ~ BK1 (FOR TRUSS T2R)



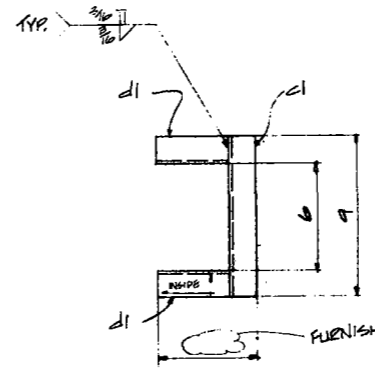
see sheet SEB4 for Total
 6 - SWAY BARS ~ ATI (AS NOTED)
 ONE - SWAY BAR ~ AVI (AS NOTED)



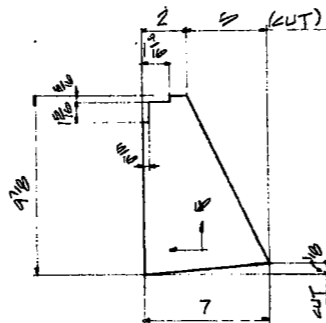
38 - DRIVE PYLON POSTS ~ AW1 (AS NOTED)
 22 - DRIVE PYLON POSTS ~ BDI (AS NOTED)



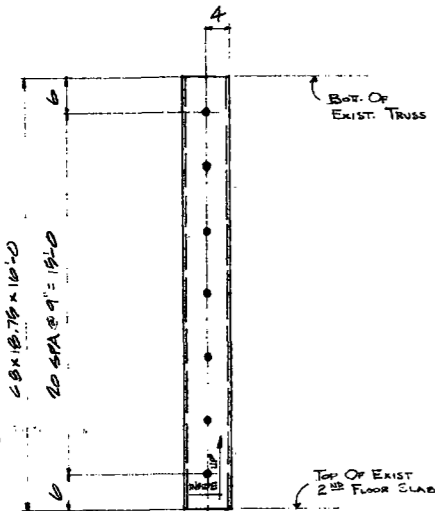
120 - STIFFENER P's ~ BBI



120 - ANGLE FRAMES ~ BCI



120 - STIFFENER P's ~ BAI



184 - CHANNELS ~ AS1
 (See DWG'S B1 & B3 For Locations)

SHIPPING		BILL OF MATERIAL									
NO	QTY	MATERIAL	FT	IN	MARK	T	REMARKS	EST. QUANTITY	TOTAL QUANTITY	COOR	
84 A1	84	L ^{1/2} x ^{1/2} x ^{1/2} x 3'-7"	300.75				1.92		300.75	5.77	
84 B1	84	L ^{1/2} x ^{1/2} x ^{1/2} x 3'-8"	312.00						312.00	6.21	
84 C1	84	L ^{1/2} x ^{1/2} x ^{1/2} x 3'-10"	336.00						336.00	6.15	
84 D1	84	L ^{1/2} x ^{1/2} x ^{1/2} x 4'-0"	336.00						336.00	6.15	
84 H1	84	L ^{1/2} x ^{1/2} x ^{1/2} x 4'-2"	336.00						336.00	6.15	
4 K1	4	L ^{1/2} x ^{1/2} x ^{1/2} x 4'-1"	16.80						16.80	3.1	
8 M1	8	L ^{1/2} x ^{1/2} x ^{1/2} x 6'-0"	50.40						50.40	10.2	
130 P1	130	L ^{1/2} x ^{1/2} x ^{1/2} x 20'-0"	272.00						272.00	53.3	
84 S1	84	L ^{1/2} x ^{1/2} x ^{1/2} x 4'-8"	336.00						336.00	6.21	
84 T1	84	L ^{1/2} x ^{1/2} x ^{1/2} x 4'-8"	336.00						336.00	6.21	
84 V1	84	L ^{1/2} x ^{1/2} x ^{1/2} x 5'-4"	336.00						336.00	6.21	
84 W1	84	L ^{1/2} x ^{1/2} x ^{1/2} x 5'-8"	336.00						336.00	6.21	
96 AA1	96	L ^{1/2} x ^{1/2} x ^{1/2} x 6'-8"	336.00						336.00	6.21	
96 AB1	96	L ^{1/2} x ^{1/2} x ^{1/2} x 6'-8"	336.00						336.00	6.21	
96 AC1	96	L ^{1/2} x ^{1/2} x ^{1/2} x 6'-14"	336.00						336.00	6.21	
264 AD1	264	L ^{1/2} x ^{1/2} x ^{1/2} x 6'-10"	171.60						171.60	32.75	
44 AH1	44	L ^{1/2} x ^{1/2} x ^{1/2} x 10'-0"	44.00						44.00	8.15	
76 AK1	76	L ^{1/2} x ^{1/2} x ^{1/2} x 7'-0"	12.72						12.72	2.35	
176 AM1	176	L ^{1/2} x ^{1/2} x ^{1/2} x 7'-9"	176.00						176.00	31.32	
96 AP1	96	L ^{1/2} x ^{1/2} x ^{1/2} x 6'-10"	336.00						336.00	6.21	
4 BH1	4	L ^{1/2} x ^{1/2} x ^{1/2} x 4'-0"	16.80						16.80	3.1	
96 BK1	96	L ^{1/2} x ^{1/2} x ^{1/2} x 6'-14"	336.00						336.00	6.21	
38 AW1	38	DRIVE PYLON POST									
22 BDI	22	DRIVE PYLON POST									
120 BBI	120	120 STIFFENER P's									
120 BCI	120	120 ANGLE FRAMES									

ERECTION BOLTS (NET)

204 1/2" x 3/4"	0	1/2"
40 3/4" x 1/2"	0	1/2"
240 1/2" x 3/4"	0	6"

112 1/2" x 3/4"	240	1/2"
214 1/2" x 3/4"	240	1/2"
413 1/2" x 3/4"	240	1/2"
24 1/2" x 3/4"	240	1/2"

SUBMITTAL REVIEW
 DATE: 5/26/81
 BY: [Signature]

JUN 19 1981

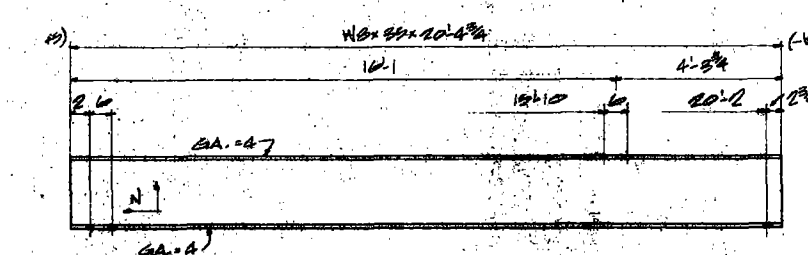
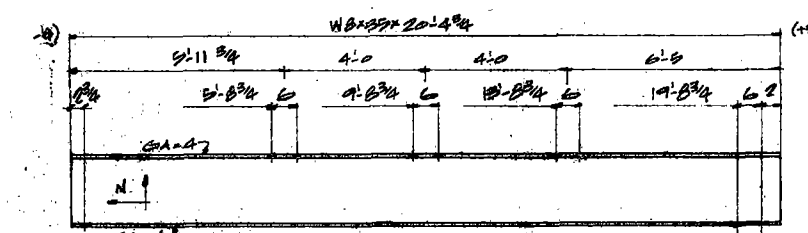
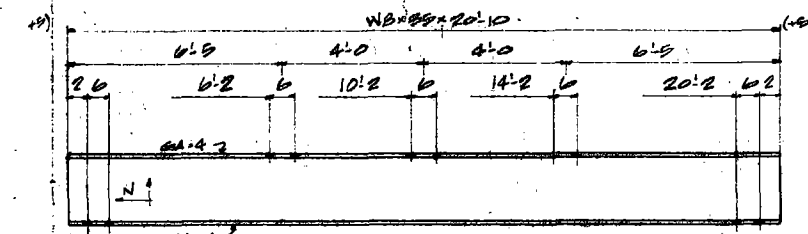
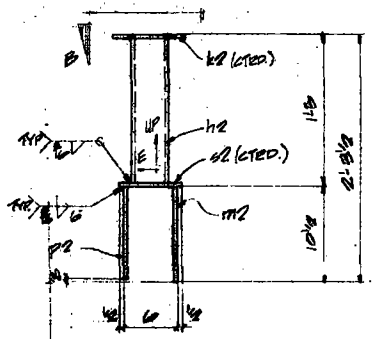
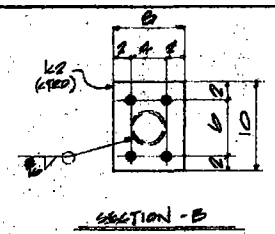
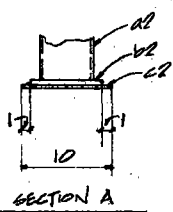
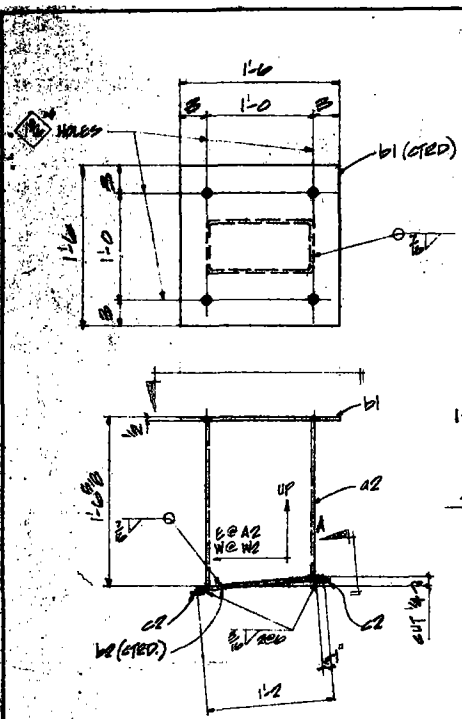
SHOP NOTE

REF. DWG: 980-5284 (INCL.)

CONTRACTORS LIC. NO. 150594

AS-BUILT

SPECIAL NOTES		APPROVAL INFO	
HOLES = 1/16" U.N.I. R&S Pcs. No. 469 - Spec Sect. S102 & S103		DATE	BY
FINISH SCHEDULE		DATE	BY
TITLES		DATE	BY
TITL MICCELANEOUS DETAILS		DATE	BY
JOB CATERPILLAR TRACTOR CO.		DATE	BY
LOCATION SAN LEANDRO, CA.		DATE	BY
ARCH ENGR BISSSELL & KAEN INC.		DATE	BY
CONTRACTOR RUPPEL & GLETTEN		DATE	BY
COMPS ISSUED		DATE	BY
CASCADE METALS CORPORATION		DATE	BY



220 - SUPPORT PYLON POSTS - A2
 132 - SUPPORT PYLON POSTS - W2

B2, W2, W2, AC2	MC10x8A x 8'-9 1/2
B2, W2, W2, AD2	MC10x8A x 8'-0 1/2
D2, W2, W2, AH2	MC10x8A x 1'-9 1/2
B2, W2, W2, AC2	2'-9 1/2 4'-2
C2, W2, W2, AD2	2'-0 1/2
D2, W2, W2, AH2	1'-3 1/2

- 60 - CHANNELS - B2 (AS SHOWN & NOTED)
- 60 - CHANNELS - C2 (AS SHOWN & NOTED)
- 60 - CHANNELS - D2 (AS SHOWN & NOTED)
- 60 - CHANNELS - H2 (OPP. HAND & NOTED)
- 60 - CHANNELS - K2 (OPP. HAND & NOTED)
- 60 - CHANNELS - M2 (OPP. HAND & NOTED)
- 60 - CHANNELS - W2 (OPP. HAND & NOTED)
- 60 - CHANNELS - A2 (OPP. HAND & NOTED)
- 60 - CHANNELS - AB2 (OPP. HAND & NOTED)
- 60 - CHANNELS - AC2 (AS SHOWN & NOTED)
- 60 - CHANNELS - AD2 (AS SHOWN & NOTED)
- 60 - CHANNELS - AH2 (AS SHOWN & NOTED)

SECTION B

SUBMITTAL REVIEW
 DESIGNED BY: [Signature]
 CHECKED BY: [Signature]
 DATE: 5/26/99
 BY: Frank F. [Signature]

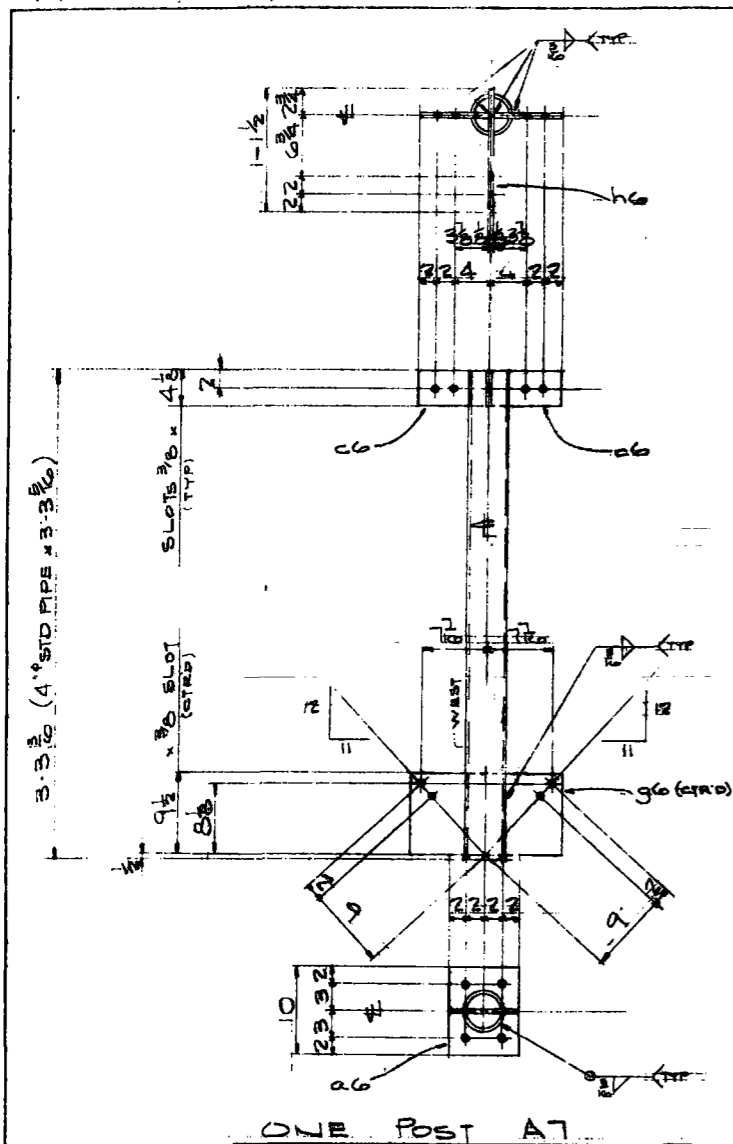
JUN 19 1999

REF. DWG: 4400-000-000-000

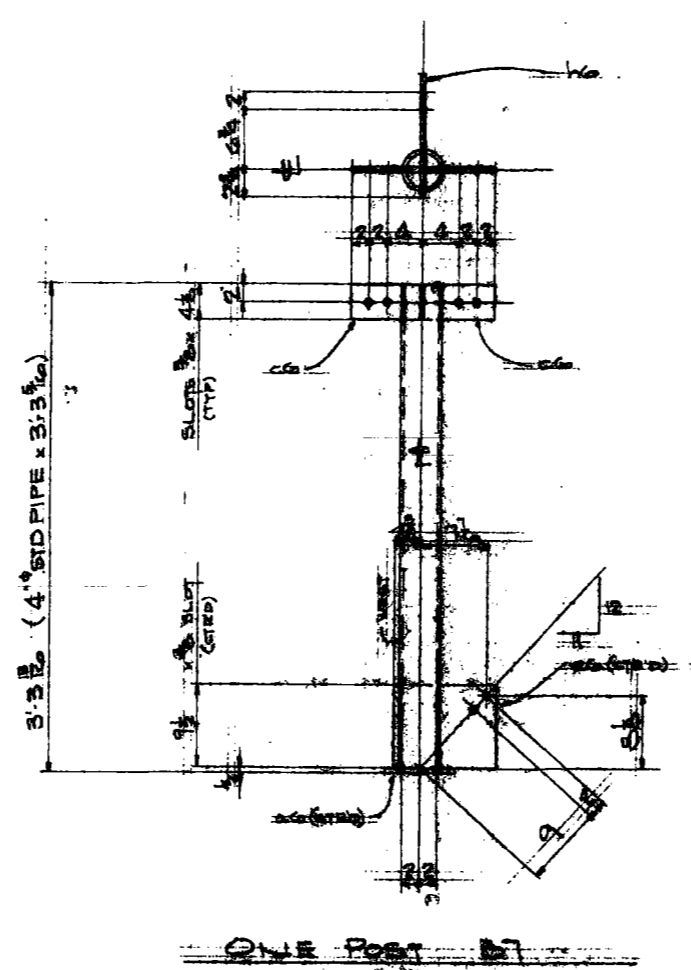
SHIPPING		BILL OF MATERIAL									
NO.	QTY	MATERIAL	FT	IN	MARK	T	REMARKS	3200	3200	3200	3200
220	A2	220 SUPPORT PYLON POST			A2						
132	W2	132 SUPPORT PYLON POST			W2						
200		200 2" x 1/2" x 10'	1	10	B1		22.16	540.00	16.52		
200		200 2" x 1/2" x 10'	1	10	A2		57.11	513.60	210.45		
200		200 2" x 1/2" x 10'	1	10	W2		13.16	421.20	57.88		
200		200 2" x 1/2" x 10'	2	10	C2		13.89	597.60	76.5		
60	B2	60 MC10x8A	3	8 1/2	B2			37.70	113.10		
60	C2	60 MC10x8A	3	8 1/2	C2			153.41	460.20		
60	D2	60 MC10x8A	1	8 1/2	D2			47.40	142.20		
60	H2	60 MC10x8A	3	8 1/2	H2			57.70	173.10		
60	K2	60 MC10x8A	2	8 1/2	K2			153.40	460.20		
60	M2	60 MC10x8A	1	8 1/2	M2			47.40	142.20		
60	W2	60 MC10x8A	3	8 1/2	W2			157.40	472.20		
60	AB2	60 MC10x8A	2	8 1/2	AB2			152.40	457.20		
60	AC2	60 MC10x8A	1	8 1/2	AC2			47.40	142.20		
60	AD2	60 MC10x8A	3	8 1/2	AD2			152.40	457.20		
60	AH2	60 MC10x8A	1	8 1/2	AH2			47.40	142.20		
1440		1440 2" x 1/2" x 10'	0	10	D2		1.23	123.00	50.82		
7	P2	7 POST			P2		4.77				
7		7 STD. PIPE 4"	1	2	H2		5.25	10.50	4.17	8.8	
7		7 2" x 1/2" x 10'	0	10	W2		13.16	131.60	57.88		
7		7 2" x 1/2" x 10'	0	10	H2		4.77	47.70	18.7		
7		7 2" x 1/2" x 10'	0	10	P2		4.03	40.30	16.1		
7		7 2" x 1/2" x 10'	0	7	S2		4.06	40.60	16.1		
2	S2	2 WB135	20	10	S2			41.66	83.32		
1	T2	1 WB135	20	10	T2			20.80	41.60		
1	V2	1 WB135	20	10	V2			20.80	41.60		
1440		1440 1/2" x 1/2" x 10'	0	6							
60		60 1/2" x 1/2" x 10'	0	2							

AS-BUILT

SPECIAL NOTES		APPROVAL INFO.	
FINISH SCHEDULE TRESPCO No. 1282 ORO-TEX RED PRIMER TYP180 BASIC LEAD CHROM PRIMER TP 11 GREEN ZINC CHROMATE OF TRESPCO 80 HOT DIP GALVANIZE TSP/MEC #1009 Gray		TITLE ITEM: MISCELLANEOUS DETAILS JOB: CATEPILLAR TRACTOR CO. LOCATION: SAN LEANDRO, CA. ARCH-ENGR: BISSELL & KAHN INC. CONTRACTOR: ELDORF & OLETTEN	
CASCADE METALS CORPORATION P.O. BOX 870 • 1182 HARBURY ROAD • SAN JOSE, CALIF. 95128			



ONE POST A7



ONE POST B7

X
 Forg 8/20/4
 SEE SHEET E-7

GILL OF MATERIAL

NO.	QTY	MATERIAL	FT	IN	MADE	PRIMARY
1	A7	ONE 4" STD PIPE	3	3/4	A7	
		1 R 1/2 x 8	0	10	CG	
		2 R 1/2 x 4	0	7 1/2	CG	
		1 R 1/2 x 9 3/8	0	1 1/2	CG	
		1 R 1/2 x 4	1	1 1/2	CG	

1	B7	ONE 4" STD PIPE	3	3/4	B7	
		1 R 1/2 x 8	0	10	CG	
		2 R 1/2 x 4	0	7 1/2	CG	
		1 R 1/2 x 9 3/8	0	1 1/2	CG	
		1 R 1/2 x 4	1	1 1/2	CG	

ERECTION BOLTS (SUMM ON ET)

14	5/8" A325	0	1 1/2
4	5/8" A325	0	2

AS-BUILT

REVISIONS

NO	DATE	REVISIONS

SPECIAL NOTES

OPEN HOLES 1/2" UN
 MIN. EDGE DIST. 1/2" UN

FINISH SCHEDULE	TITLE
TRESCO NO. 1282 GRD. TEX. RED PRIMER	POST
TP150 BASIC LEAD CHROM. PRIMER TP 11	JOB: CATERPILLAR TRACTOR CO.
GREEN ZINC CHROMATE OF TRIMET. 88	LOCATION: SAN LEANDRO, CA
HOT DIP GALVANIZE	ARCH: THEO. PISSELL & KARN, INC.
	CONTRACTOR: RUDOLPH & SLETTEN

COPIES ISSUED

NO.	DATE	NO.	DATE	NO.	DATE	NO.	DATE

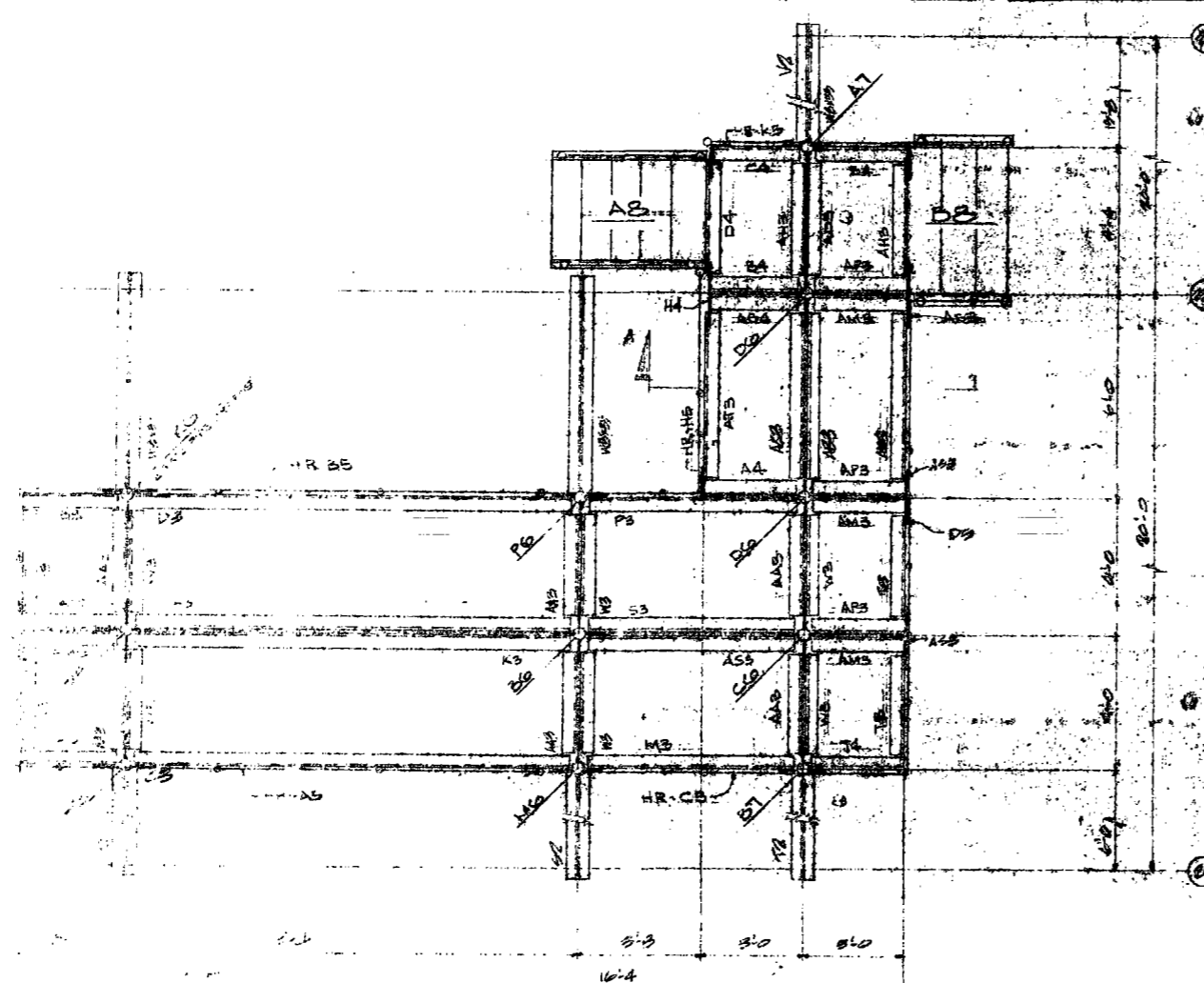
CASCADE METALS CORPORATION
 1100 S. 11th St. Seattle, WA 98148

NO.	DATE	NO.	DATE	NO.	DATE	NO.	DATE

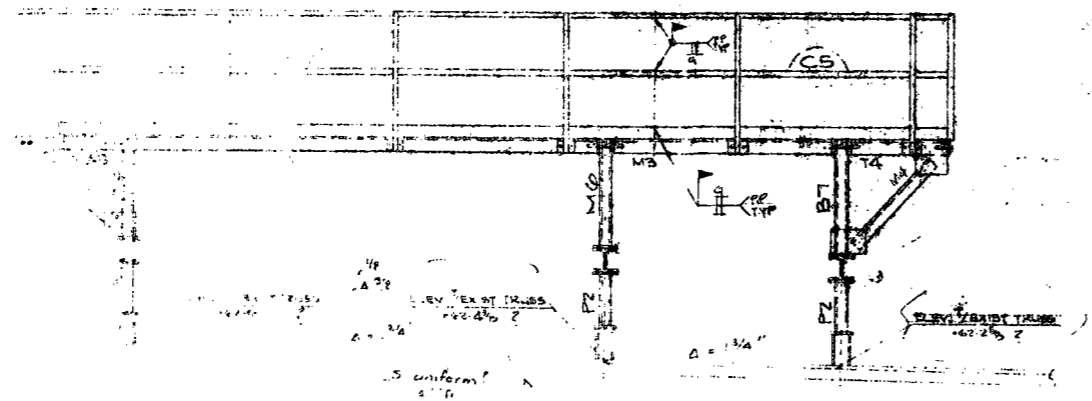
AUG 28 1947

CONTRACTORS LIC NO. 18084

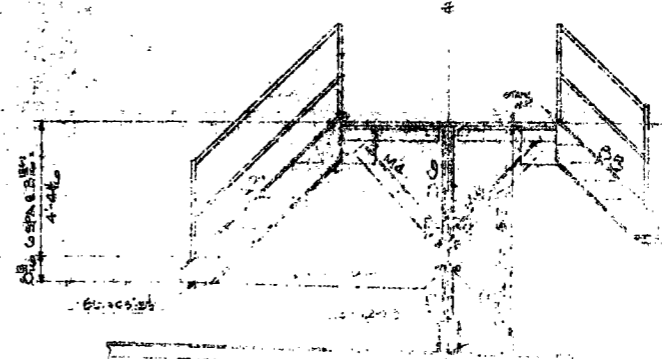
JOB NO. 382
 SEQ. NO. 0215
 DWG. NO. D7



↑
OBSERVATION PLATFORM FRAMING PLAN
ALL MEMBERS L 6x8x5 LVL



Dimensioning
Based upon
SLOPE
AFFECTS ALL OTHER
SHEETS



SECTION A

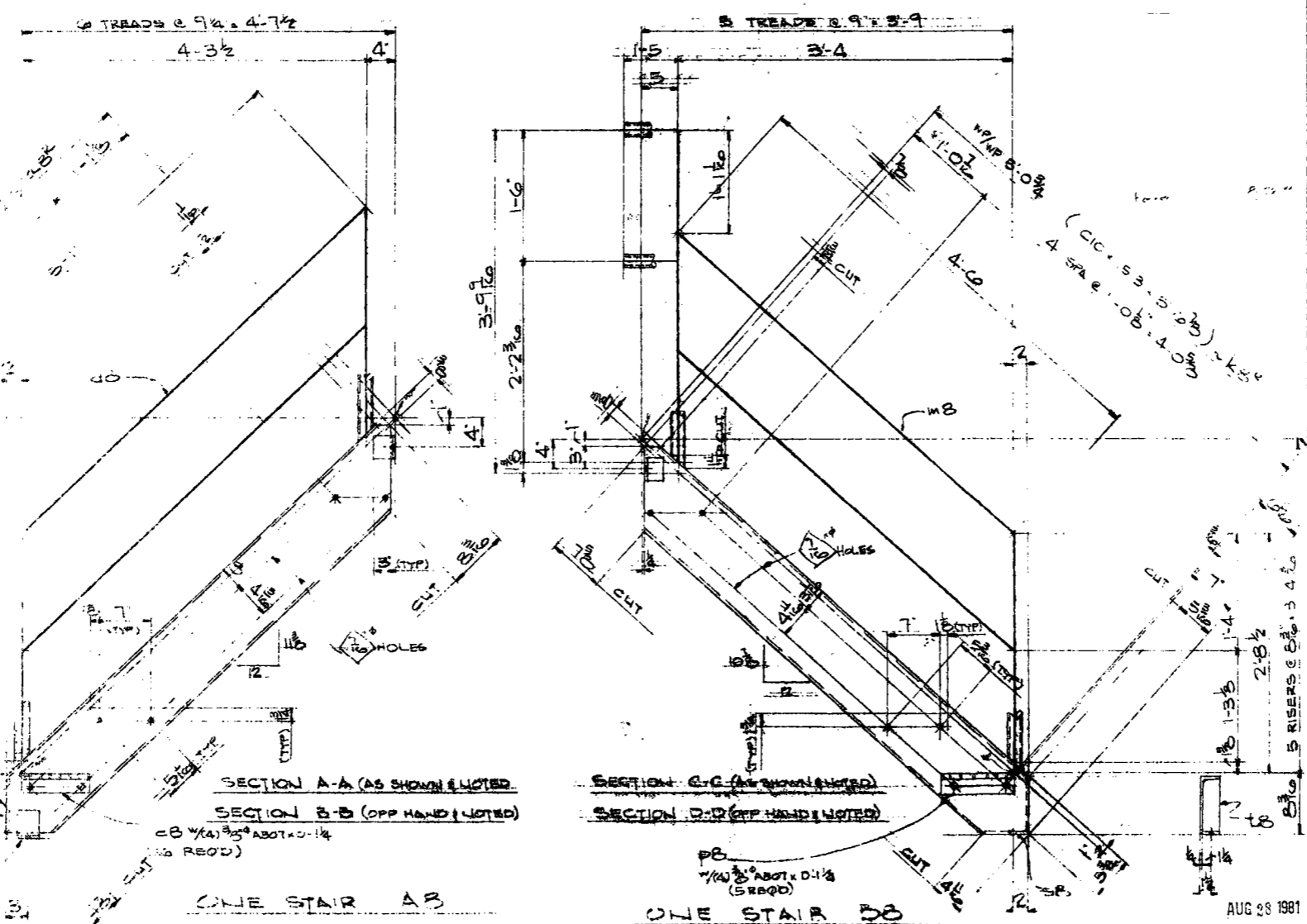
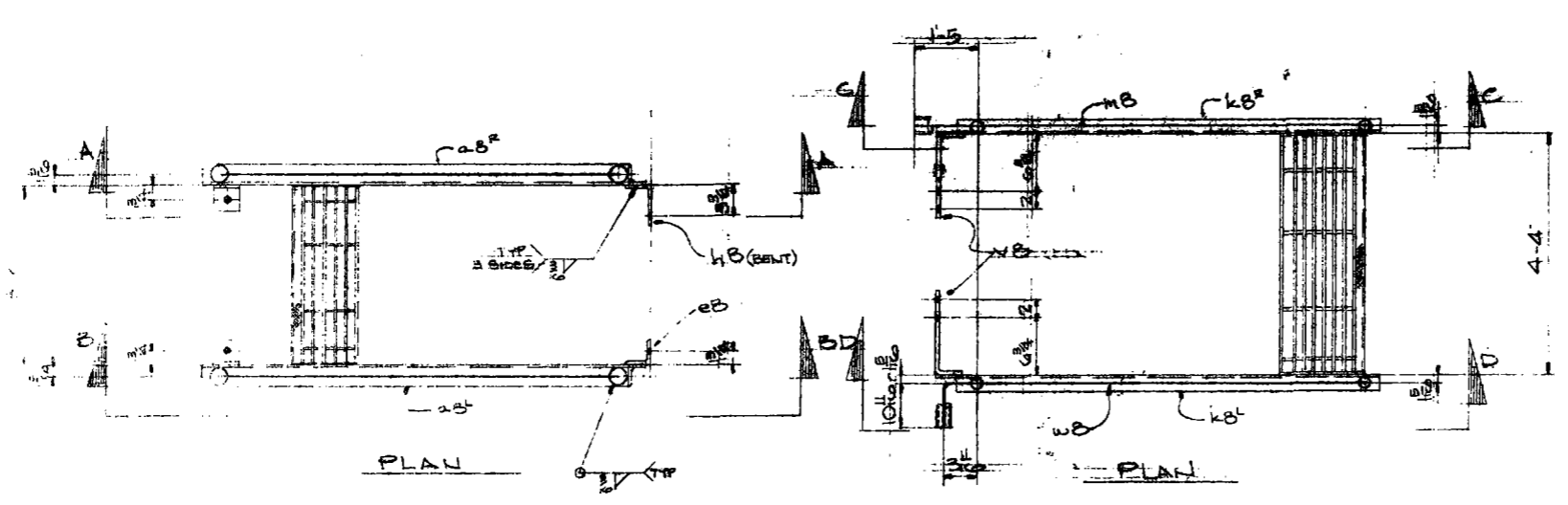
AS-BUILT

NO.	DESCRIPTION	REVISION	DATE
1	AS-BUILT		

NO.	DESCRIPTION	REVISION	DATE
1	AS-BUILT		

NO.	DESCRIPTION	REVISION	DATE
1	AS-BUILT		

AUG 28 1981



NO	QTY	MATERIAL	ST	IN	MARK	REMARK
1	1	ONE STAIR			AB	
1	1	C10 x 15.3	10	10	MB	
1	1	GRATING TREADS	3/4	3/4	MB	
1	1	B.B. x 10	3	3	MB	
1	1	W/CHED B. NOSING	CB			
2	2	1/2 STD PIPE	17	17	MB	APPROX
3	3	1/4	3	3	MB	MINET
1	1	4 x 4	10	10	MB	
1	1	1/2 x 2	10	10	MB	
1	1	1/2 x 2	10	10	MB	

NO	QTY	MATERIAL	ST	IN	MARK	REMARK
1	1	ONE STAIR			BB	
1	1	C10 x 15.3	10	10	MB	
1	1	GRATING TREADS	3/4	3/4	MB	
1	1	B.B. x 10	3	3	MB	
1	1	W/CHED B. NOSING	CB			
2	2	1/2 STD PIPE	17	17	MB	APPROX
3	3	1/4	3	3	MB	MINET
1	1	4 x 4	10	10	MB	
1	1	1/2 x 2	10	10	MB	
1	1	1/2 x 2	10	10	MB	

AS-BUILT

FINISH SCHEDULE		TITLE
OPEN HOLES	1/2" MIN. EDGE DIST.	STAIR
MIN. EDGE DIST.	1/4"	CATERPILLAR RATCH
		WAGON SAN LEANDRE
		ANN MCK BISSSELL
		WARRANTY RUDOLPH
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AUG 28 1981

